

Sec1.3OpHw

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9. Let

$$A = \begin{bmatrix} 1 & 2 \\ 1 & -2 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 4 \\ 0 \end{bmatrix}, \quad \mathbf{c} = \begin{bmatrix} -3 \\ -2 \end{bmatrix}$$

- (a) Write \mathbf{b} as a linear combination of the column vectors \mathbf{a}_1 and \mathbf{a}_2 .
- (b) Use the result from part (a) to determine a solution of the linear system $A\mathbf{x} = \mathbf{b}$. Does the system have any other solutions? Explain.
- (c) Write \mathbf{c} as a linear combination of the column vectors \mathbf{a}_1 and \mathbf{a}_2 .

(a) (By observation)

$$\bar{\mathbf{a}}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad \bar{\mathbf{a}}_2 = \begin{pmatrix} 2 \\ -2 \end{pmatrix}$$

$$2\bar{\mathbf{a}}_1 + \bar{\mathbf{a}}_2 = 2\begin{pmatrix} 1 \\ 1 \end{pmatrix} + \begin{pmatrix} 2 \\ -2 \end{pmatrix} = \begin{pmatrix} 4 \\ 0 \end{pmatrix} = \bar{\mathbf{b}}$$

(b). Let $\bar{\mathbf{x}} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$, i.e., $x_1 = 2, x_2 = 1$

$$\text{Then } A\bar{\mathbf{x}} = (\bar{\mathbf{a}}_1, \bar{\mathbf{a}}_2) \cdot \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$= x_1 \cdot \bar{\mathbf{a}}_1 + x_2 \cdot \bar{\mathbf{a}}_2 = \bar{\mathbf{b}}$$

Therefore, $\bar{\mathbf{x}} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ is a solution to the system.

the system.

The solution is unique since

$$A = \begin{bmatrix} 1 & 2 \\ 1 & -2 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 2 \\ 0 & -4 \end{bmatrix} \text{ has.}$$

(row operation)

strict triangular form (the explanation is not unique?)

(c). Solve the system $A\bar{x} = \bar{c}$ by row operation.

$$\left[\begin{array}{cc|c} 1 & 2 & -3 \\ 1 & -2 & -2 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} 1 & 2 & -3 \\ 0 & -4 & 1 \end{array} \right]$$

$$\Rightarrow -4x_2 = 1 \Rightarrow x_2 = -\frac{1}{4}$$

(back-sub)

$$x_1 + 2 \cdot \left(-\frac{1}{4}\right) = -3 \Rightarrow x_1 = \frac{1}{2} - 3 = -\frac{5}{2}$$

Therefore, $\bar{c} = \begin{pmatrix} -3 \\ -2 \end{pmatrix}$ can be written as

$$\bar{c} = -\frac{5}{2} \bar{a}_1 - \frac{1}{4} \bar{a}_2$$

16. A matrix A is said to be *skew symmetric* if $A^T = -A$. Show that if a matrix is skew symmetric, then its diagonal entries must all be 0.

Consider a $n \times n$ matrix $A = (a_{ij})$

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix}$$

$$\text{Then } A^T = (a_{ji}) = \begin{pmatrix} a_{11} & a_{21} & \dots & a_{n1} \\ a_{12} & a_{22} & \dots & a_{n2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1n} & a_{2n} & \dots & a_{nn} \end{pmatrix}$$

Skew symmetric means

$$A = -A^T, \text{ i.e., } (a_{ij}) = (-a_{ji}).$$

In particular, on the diagonal,

we have $a_{ii} = -a_{ii}$ for all $i=1,2,\dots,n$.

This implies $a_{ii} = 0$ for all $i=1,\dots,n$.

This implies $\boxed{a_{ii} = 0}$ for all $i = 1, \dots, n$.