

**LIOUVILLE TYPE THEOREMS ON MANIFOLDS WITH
NONNEGATIVE CURVATURE AND STRICTLY CONVEX
BOUNDARY**

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ABSTRACT. We prove some Liouville type theorems on smooth compact Riemannian manifolds with nonnegative sectional curvature and strictly convex boundary. This gives a nonlinear generalization in low dimension of the recent sharp lower bound for the first Steklov eigenvalue by Xia-Xiong and verifies partially a conjecture by the third named author. As a consequence, we derive several sharp Sobolev trace inequalities on such manifolds.

1. Introduction

In [BVV, section 6], a remarkable calculation of Bidaut-Véron and Véron implies the following Liouville type theorem (see also [I] for the case of Neumann boundary condition):

Theorem 1. ([BVV, I]) *Let (M^n, g) be a smooth compact Riemannian manifold with a (possibly empty) convex boundary. Suppose $u \in C^\infty(M)$ is a positive solution of the following equation*

$$\begin{aligned} -\Delta u + \lambda u &= u^q && \text{on } M, \\ \frac{\partial u}{\partial \nu} &= 0 && \text{on } \partial M, \end{aligned}$$

where $\lambda > 0$ is a constant and $1 < q \leq (n + 2) / (n - 2)$. If $\text{Ric} \geq \frac{(n-1)(q-1)\lambda}{n}g$, then u must be constant unless $q = (n + 2) / (n - 2)$ and (M, g) is isometric to $(\mathbb{S}^n, \frac{4\lambda}{n(n-2)}g_{\mathbb{S}^n})$ or $(\mathbb{S}_+^n, \frac{4\lambda}{n(n-2)}g_{\mathbb{S}^n})$. In the latter case u is given on \mathbb{S}^n or \mathbb{S}_+^n by the following formula

$$u(x) = \frac{1}{(a + x \cdot \xi)^{(n-2)/2}}.$$

for some $\xi \in \mathbb{R}^{n+1}$ and some constant $a > |\xi|$.

By convex boundary we mean that the 2nd fundamental form Π is nonnegative. To be precise, throughout this paper ν denotes the outer unit normal on the boundary and the second fundamental form is defined as

$$\Pi(X, Y) = \langle \nabla_X \nu, Y \rangle.$$

for $X, Y \in T_p(\partial M)$.

This theorem has some very interesting corollaries. In particular it yields a sharp lower bound for type I Yamabe invariant (see [BVV, section 6] and [W2]). It is proposed in [W2] that a similar result should hold for type II Yamabe problem on a compact Riemannian manifold with nonnegative Ricci curvature and strictly convex boundary. By strict convexity we mean the second fundamental form Π of the

boundary has a positive lower bound. By scaling we can always assume that the lower bound is 1. In its precise form, the conjecture in [W2] states the following:

Conjecture 1 ([W2]). *Let (M^n, g) be a smooth compact Riemannian manifold with $Ric \geq 0$ and $\Pi \geq 1$ on its nonempty boundary. Let $u \in C^\infty(M)$ be a positive solution to the following equation*

$$(1.1) \quad \begin{aligned} \Delta u &= 0 && \text{on } M, \\ \frac{\partial u}{\partial \nu} + \lambda u &= u^q && \text{on } \partial M, \end{aligned}$$

where the parameters λ and q are always assumed to satisfy $\lambda > 0$ and $1 < q \leq \frac{n}{n-2}$. If $\lambda \leq \frac{1}{q-1}$, then u must be constant unless $q = \frac{n}{n-2}$, M is isometric to $\overline{\mathbb{B}^n} \subset \mathbb{R}^n$ and u corresponds to

$$u_a(x) = \left[\frac{2}{n-2} \frac{1 - |a|^2}{1 + |a|^2 |x|^2 - 2x \cdot a} \right]^{(n-2)/2}$$

for some $a \in \mathbb{B}^n$.

This conjecture, if true, would have very interesting geometric consequences. We refer the readers to [W2] for further discussion. In this paper we will verify the conjecture in some special cases.

Theorem 2. *Let (M^n, g) be a smooth compact Riemannian manifold with nonnegative sectional curvature and the second fundamental form of the boundary $\Pi \geq 1$. Then the only positive solution to (1.1) is constant if $\lambda \leq \frac{1}{q-1}$, provided $2 \leq n \leq 8$ and $1 < q \leq \frac{4n}{5n-9}$.*

Although this result requires the stronger assumption on the sectional curvature and severe restriction on the dimension and the exponent, it does yield the conjectured sharp range for λ . This is a delicate issue as illustrated by the following result on the model space $\overline{\mathbb{B}^n}$.

Proposition 1. *If $1 < q < \frac{n}{n-2}$ and $\lambda(q-1) > 1$ then the equation*

$$\begin{aligned} \Delta u &= 0 && \text{on } \overline{\mathbb{B}^n}, \\ \frac{\partial u}{\partial \nu} + \lambda u &= u^q && \text{on } \partial \overline{\mathbb{B}^n}, \end{aligned}$$

admits a positive, nonconstant solution.

It should be mentioned that on the model space $\overline{\mathbb{B}^n}$ with $n \geq 3$ the conjecture is verified in [GuW] in all dimensions when $\lambda \leq \frac{n-2}{2}$ by the method of moving planes. The approach to Theorem 2 is based on an integral method with a key idea borrowed from the recent work [XX] by Xia and Xiong, where a sharp lower bound for the first Steklov eigenvalue was proved.

For $n = 2$ Theorem 2 confirms the conjecture when $q \leq 8$. By an approach based on maximum principle in the spirit of [E1, P, W1], we can verify the conjecture in dimension 2 for $q \geq 2$. Combining both results we fully confirm Conjecture 1 in dimension 2.

Theorem 3. *Let (Σ, g) be a smooth compact surface with nonnegative Gaussian curvature and geodesic curvature $\kappa \geq 1$ on the boundary. Then the only positive solution to the following equation*

$$(1.2) \quad \begin{aligned} \Delta u &= 0 && \text{on } \Sigma, \\ \frac{\partial u}{\partial \nu} + \lambda u &= u^q && \text{on } \partial\Sigma, \end{aligned}$$

where $q > 1$ and $0 < \lambda \leq \frac{1}{q-1}$, is constant.

The paper is organized as follows. In Section 2 we derive some integral identities that will be used later. The proof of Theorem 2 is given in Section 3. In Section 4 we present the argument based on maximum principle in dimension two and prove Theorem 3. In the last section we make some further remarks about Conjecture 1 and deduce some corollaries from our Liouville type results.

2. Some integral identities

Let (M^n, g) be a smooth compact Riemannian manifold with boundary Σ and $v \in C^\infty(M)$ be a **positive** function. We write $f = v|_\Sigma$, $\chi = \frac{\partial v}{\partial \nu}$. Let w be another smooth functions on M satisfying the following boundary conditions

$$(2.1) \quad w|_\Sigma = 0, \frac{\partial w}{\partial \nu} = -1.$$

Proposition 2. *For any $b \in \mathbb{R}$*

$$\begin{aligned} & \int_M \left(1 - \frac{1}{n} \right) (\Delta v)^2 v^b w + \frac{b}{2} w v^{b-2} |\nabla v|^2 \left[3v \Delta v + (b-1) |\nabla v|^2 \right] \\ &= \int_M v^b D^2 w (\nabla v, \nabla v) - |\nabla v|^2 v^b \Delta w - \frac{b}{2} |\nabla v|^2 v^{b-1} \langle \nabla v, \nabla w \rangle \\ &+ \left(\left| D^2 v - \frac{\Delta v}{n} g \right|^2 + Ric(\nabla v, \nabla v) \right) v^b w - \int_\Sigma f^b |\nabla f|^2. \end{aligned}$$

Proof. The following weighted Reilly formula was proved in [QX] for any smooth functions v and ϕ

$$(2.2) \quad \begin{aligned} & \int_M \left[\left(1 - \frac{1}{n} \right) (\Delta v)^2 - \left| D^2 v - \frac{\Delta v}{n} g \right|^2 \right] \phi \\ &= \int_M D^2 \phi (\nabla v, \nabla v) - |\nabla v|^2 \Delta \phi + Ric(\nabla v, \nabla v) \phi \\ &+ \int_\Sigma \phi \left[2\chi \Delta_\Sigma f + H\chi^2 + \Pi(\nabla f, \nabla f) \right] + \frac{\partial \phi}{\partial \nu} |\nabla f|^2, \end{aligned}$$

Take $\phi = v^b w$. We calculate

$$\begin{aligned}\nabla\phi &= v^b\nabla w + b w v^{b-1}\nabla v \\ D^2\phi &= v^b D^2 w + b v^{b-1}(dv \otimes dw + dw \otimes dv) + b w v^{b-1} D^2 v \\ &\quad + b(b-1) w v^{b-2} dv \otimes dv, \\ \Delta\phi &= v^b \Delta w + 2b v^{b-1} \langle \nabla v, \nabla w \rangle + b w v^{b-1} \Delta v + b(b-1) w v^{b-2} |\nabla v|^2, \\ D^2\phi(\nabla v, \nabla v) &= v^b D^2 w(\nabla v, \nabla v) + 2b v^{b-1} |\nabla w|^2 \langle \nabla v, \nabla v \rangle + b w v^{b-1} D^2 v(\nabla v, \nabla v) \\ &\quad + b(b-1) w v^{b-2} |\nabla v|^4.\end{aligned}$$

Plugging these equations into (2.2) and using (2.1) yields

$$\begin{aligned}&\int_M \left[\left(1 - \frac{1}{n}\right) (\Delta v)^2 - \left| D^2 v - \frac{\Delta v}{n} g \right|^2 \right] v^b w \\ &= \int_M v^b D^2 w(\nabla v, \nabla v) + b w v^{b-1} D^2 v(\nabla v, \nabla v) - |\nabla v|^2 (v^b \Delta w + b w v^{b-1} \Delta v) \\ &\quad + Ric(\nabla v, \nabla v) v^b w - \int_{\Sigma} f^b |\nabla f|^2.\end{aligned}$$

We calculate

$$\begin{aligned}w v^{b-1} D^2 v(\nabla v, \nabla v) &= \frac{1}{2} w v^{b-1} \langle \nabla v, \nabla |\nabla v|^2 \rangle \\ &= \frac{1}{2} \left[\operatorname{div} (w v^{b-1} |\nabla v|^2 \nabla v) - |\nabla v|^2 \operatorname{div} (w v^{b-1} \nabla v) \right] \\ &= \frac{1}{2} \left[\operatorname{div} (w v^{b-1} |\nabla v|^2 \nabla v) - w |\nabla v|^2 v^{b-1} \Delta v \right. \\ &\quad \left. - (b-1) w v^{b-2} |\nabla v|^4 - |\nabla v|^2 v^{b-1} \langle \nabla v, \nabla w \rangle \right].\end{aligned}$$

Integrating yields

$$\int_M w v^{b-1} D^2 v(\nabla v, \nabla v) = -\frac{1}{2} \int_M w |\nabla v|^2 v^{b-1} \Delta v + (b-1) w v^{b-2} |\nabla v|^4 + |\nabla v|^2 v^{b-1} \langle \nabla v, \nabla w \rangle. \blacksquare$$

Plugging this into the previous integral identity yields

$$\begin{aligned}&\int_M \left[\left(1 - \frac{1}{n}\right) (\Delta v)^2 - \left| D^2 v - \frac{\Delta v}{n} g \right|^2 \right] v^b w \\ &= \int_M v^b D^2 w(\nabla v, \nabla v) - |\nabla v|^2 v^b \Delta w - \frac{b}{2} w v^{b-2} |\nabla v|^2 \left[3v \Delta v + (b-1) |\nabla v|^2 \right] \\ &\quad - \frac{b}{2} |\nabla v|^2 v^{b-1} \langle \nabla v, \nabla w \rangle + Ric(\nabla v, \nabla v) v^b w - \int_{\Sigma} f^b |\nabla f|^2.\end{aligned}$$

Reorganizing yields the desired identity. \square

Proposition 3. *Under the same assumptions as in Proposition 2, we have*

$$\begin{aligned} & \int_M v^b D^2 w (\nabla v, \nabla v) + \left(v \Delta v + \frac{b}{2} |\nabla v|^2 \right) v^{b-1} \langle \nabla v, \nabla w \rangle - \frac{1}{2} v^b |\nabla v|^2 \Delta w \\ &= \frac{1}{2} \int_\Sigma f^b (|\nabla f|^2 - \chi^2). \end{aligned}$$

Proof. For any vector field X the following identity holds

$$\langle \nabla_{\nabla v} X, \nabla v \rangle + X v \Delta v - \frac{1}{2} |\nabla v|^2 \operatorname{div} X = \operatorname{div} \left(X v \nabla v - \frac{1}{2} |\nabla v|^2 X \right).$$

In the following we take $X = \nabla w$. Note that $\nabla w = -\nu$ on Σ . Multiplying both sides of the above identity by v^b and integrating yields

$$\begin{aligned} & \int_M v^b D^2 w (\nabla v, \nabla v) + v^b \Delta v \langle \nabla v, \nabla w \rangle - \frac{1}{2} v^b |\nabla v|^2 \Delta w \\ &= \int_M v^b \operatorname{div} \left(\langle \nabla v, \nabla w \rangle \nabla v - \frac{1}{2} |\nabla v|^2 \nabla w \right) \\ &= \int_M -b v^{b-1} \left(\langle \nabla v, \nabla w \rangle |\nabla v|^2 - \frac{1}{2} |\nabla v|^2 \langle \nabla v, \nabla w \rangle \right) + \int_\Sigma f^b \left(\langle \nabla v, \nabla w \rangle \chi - \frac{1}{2} |\nabla v|^2 \frac{\partial w}{\partial \nu} \right) \\ &= -\frac{b}{2} \int_M v^{b-1} \langle \nabla v, \nabla w \rangle |\nabla v|^2 + \int_\Sigma f^b \left(-\chi^2 + \frac{1}{2} |\nabla v|^2 \right). \end{aligned}$$

Therefore

$$\begin{aligned} & \int_M v^b D^2 w (\nabla v, \nabla v) + \left(v \Delta v + \frac{b}{2} |\nabla v|^2 \right) v^{b-1} \langle \nabla v, \nabla w \rangle - \frac{1}{2} v^b |\nabla v|^2 \Delta w \\ &= \frac{1}{2} \int_\Sigma f^b (|\nabla f|^2 - \chi^2). \end{aligned}$$

□

3. The proof of Theorem 2

Throughout this section (M^n, g) is a smooth compact Riemannian manifold with nonempty boundary Σ . We study **positive** solutions of the following equation

$$\begin{aligned} \Delta u &= 0 & \text{on } M, \\ \frac{\partial u}{\partial \nu} + \lambda u &= u^q & \text{on } \Sigma, \end{aligned}$$

We write $u = v^{-a}$ with $a \neq 0$ a constant to be determined later. Then v satisfies the following equation

$$(3.1) \quad \begin{aligned} \Delta v &= (a+1) v^{-1} |\nabla v|^2 & \text{on } M, \\ \chi &= \frac{1}{a} (\lambda f - f^{1+a-aq}) & \text{on } \Sigma, \end{aligned}$$

where $f = v|_{\partial \Sigma}$, $\chi = \frac{\partial v}{\partial \nu}$. Multiplying both sides by v^s and integrating over M yields

$$(3.2) \quad (a+s+1) \int_M |\nabla v|^2 v^{s-1} = \int_\Sigma f^s \chi.$$

By Proposition 2

$$\begin{aligned} & \left[\left(1 - \frac{1}{n}\right) (a+1)^2 + \frac{b(3a+b+2)}{2} \right] \int_M v^{b-2} |\nabla v|^4 w \\ &= \int_M v^b D^2 w (\nabla v, \nabla v) - |\nabla v|^2 v^b \Delta w - \frac{b}{2} |\nabla v|^2 v^{b-1} \langle \nabla v, \nabla w \rangle - \int_\Sigma f^b |\nabla f|^2 + Q, \end{aligned}$$

where

$$Q = \int_M \left(\left| D^2 v - \frac{\Delta v}{n} g \right|^2 + Ric(\nabla v, \nabla v) \right) v^b w.$$

By Proposition 3

$$\begin{aligned} & \int_M v^b D^2 w (\nabla v, \nabla v) + \left(a+1 + \frac{b}{2} \right) v^{b-2} |\nabla v|^2 \langle \nabla v, \nabla w \rangle - \frac{1}{2} v^b |\nabla v|^2 \Delta w \\ &= \frac{1}{2} \int_\Sigma f^b (|\nabla f|^2 - \chi^2). \end{aligned}$$

We use the above identity to eliminate the term involving $\langle \nabla v, \nabla w \rangle$ in the previous identity and obtain

$$\begin{aligned} & \left[\left(1 - \frac{1}{n}\right) (a+1)^2 + \frac{b(3a+b+2)}{2} \right] \int_M v^{b-2} |\nabla v|^4 w \\ &= \int_M \frac{a+1+b}{a+1+\frac{b}{2}} v^b D^2 w (\nabla v, \nabla v) - \frac{a+1+\frac{3}{4}b}{a+1+\frac{b}{2}} |\nabla v|^2 v^b \Delta w \\ &+ \int_\Sigma \frac{\frac{1}{4}b}{a+1+\frac{b}{2}} f^b \chi^2 - \frac{a+1+\frac{3}{4}b}{a+1+\frac{b}{2}} f^b |\nabla f|^2 + Q. \end{aligned}$$

We choose $b = -\frac{4}{3}(a+1)$. Then

$$\begin{aligned} (3.3) \quad & \frac{[5n-9-(n+9)a](a+1)}{9n} \int_M v^{b-2} |\nabla v|^4 w \\ &= - \int_M v^b D^2 w (\nabla v, \nabla v) - \int_\Sigma f^b \chi^2 + Q. \end{aligned}$$

Let $\rho = d(\cdot, \Sigma)$ be the distance function to the boundary. It is Lipschitz on M and smooth away from the cut locus $\text{Cut}(\Sigma)$ which is a closed set of measure zero in the interior of M . We consider $\psi := \rho - \frac{\rho^2}{2}$. Notice that ψ is smooth near Σ and satisfies

$$\psi|_\Sigma = 0, \quad \frac{\partial \psi}{\partial \nu} = -1.$$

From now on we assume that M has nonnegative sectional curvature and $\Pi \geq 1$ on Σ . By the Hessian comparison theorem (cf. [K]) $\rho \leq 1$ hence $\psi \geq 0$ and

$$-D^2 \psi \geq g$$

in the support sense. The new idea that ψ can be used as a good weight function is introduced in [XX] to study the first Steklov eigenvalue. To overcome the difficulty that ψ is not smooth, they constructed smooth approximations.

Proposition 4 ([XX]). *Fix a neighborhood \mathcal{C} of $\text{Cut}(\Sigma)$ in the interior of M . Then for any $\varepsilon > 0$, there exists a smooth nonnegative function ψ_ε on M s.t. $\psi_\varepsilon = \psi$ on $M \setminus \mathcal{C}$ and*

$$-D^2\psi_\varepsilon \geq (1 - \varepsilon)g$$

The construction is based on the work [GW1, GW2, GW3].

In (3.3) taking the weight $w = \psi_\varepsilon$ yields

$$\begin{aligned} & \frac{[5n - 9 - (n + 9)a](a + 1)}{9n} \int_M v^{b-2} |\nabla v|^4 \psi_\varepsilon \\ & \geq (1 - \varepsilon) \int_{\mathcal{C}} v^b |\nabla v|^2 - \int_{M \setminus \mathcal{C}} v^b D^2\psi(\nabla v, \nabla v) - \int_\Sigma f^b \chi^2 + Q_\varepsilon, \end{aligned}$$

where

$$Q_\varepsilon = \int_M \left(\left| D^2v - \frac{\Delta v}{n} g \right|^2 + \text{Ric}(\nabla v, \nabla v) \right) v^b \psi_\varepsilon.$$

Letting $\varepsilon \rightarrow 0$ and shrinking the neighborhood yields

$$\begin{aligned} & \frac{[5n - 9 - (n + 9)a](a + 1)}{9n} \int_M v^{b-2} |\nabla v|^4 \psi \\ & \geq \int_{\mathcal{C}} v^b |\nabla v|^2 - \int_{M \setminus \mathcal{C}} v^b D^2\psi(\nabla v, \nabla v) - \int_\Sigma f^b \chi^2 + Q \end{aligned}$$

where

$$Q = \int_M \left(\left| D^2v - \frac{\Delta v}{n} g \right|^2 + \text{Ric}(\nabla v, \nabla v) \right) v^b \psi.$$

On $M \setminus \mathcal{C}$ the function ψ is smooth and satisfies $-D^2\psi \geq g$. Therefore

$$\begin{aligned} & \frac{[5n - 9 - (n + 9)a](a + 1)}{9n} \int_M v^{b-2} |\nabla v|^4 \psi \\ & \geq \int_M v^b |\nabla v|^2 - \int_\Sigma f^b \chi^2 + Q. \end{aligned}$$

Using the boundary condition for v we obtain

$$\begin{aligned} & \frac{[5n - 9 - (n + 9)a](a + 1)}{9n} \int_M v^{b-2} |\nabla v|^4 \psi \\ & \geq \int_M v^b |\nabla v|^2 - \frac{1}{a} \int_\Sigma (\lambda f^{b+1} - f^{b+1+a-aq}) \chi + Q \\ & = \int_M v^b |\nabla v|^2 - \frac{(a + b + 2)\lambda}{a} w^b |\nabla w|^2 + \frac{2a + b + 2 - aq}{a} w^{b+a-aq} |\nabla w|^2 + Q \\ & = \int_M \left(1 - \frac{\lambda(2-a)}{3a} \right) v^b |\nabla v|^2 + \left(\frac{2}{3} - q + \frac{2}{3a} \right) v^{b+a-aq} |\nabla v|^2 + Q, \end{aligned}$$

which can be written as

$$(3.4) \quad A \int_M v^{b-2} |\nabla v|^4 \psi + B \int_M v^b |\nabla v|^2 + C \int_M v^{b+a-aq} |\nabla v|^2 \geq Q,$$

where, with $x = a^{-1}$

$$A = \frac{[5n - 9 - (n + 9)a](a + 1)}{9n} = \frac{[(5n - 9)x - (n + 9)](x + 1)}{9nx^2},$$

$$B = \frac{\lambda(2 - a)}{3a} - 1 = \frac{\lambda}{3}(2x - 1) - 1$$

$$C = q - \frac{2}{3} - \frac{2}{3a} = q - \frac{2}{3} - \frac{2}{3}x$$

We want to choose a s.t. $A, B, C \leq 0$, i.e.

$$\left(x - \frac{n + 9}{5n - 9}\right)(x + 1) \leq 0,$$

$$\frac{\lambda}{3}(2x - 1) - 1 \leq 0,$$

$$q - \frac{2}{3} - \frac{2}{3}x \leq 0.$$

By simple calculations these inequalities become

$$-1 \leq x \leq \frac{n + 9}{5n - 9},$$

$$\frac{3}{2}q - 1 \leq x \leq \frac{3}{2}\frac{1}{\lambda} + \frac{1}{2}.$$

The choice is possible when $\frac{3}{2}q - 1 \leq \frac{3}{2}\frac{1}{\lambda} + \frac{1}{2}$ and $\frac{3}{2}q - 1 \leq \frac{n + 9}{5n - 9}$ i.e. when $(q - 1)\lambda \leq 1$ and $q \leq \frac{4n}{5n - 9}$. As $q > 1$ we must have $2 \leq n \leq 8$. Then when $q \leq \frac{4n}{5n - 9}$ and $(q - 1)\lambda \leq 1$ by choosing $\frac{1}{a} = \frac{3}{2}q - 1$ we have

$$C = 0, B = (q - 1)\lambda - 1 \leq 0, A = \frac{5n - 9}{6n}q \left(\frac{3}{2}q - 1\right)^2 \left(q - \frac{4n}{5n - 9}\right) \leq 0.$$

Thus the left hand side of (3.4) is nonpositive while the right hand side is nonnegative. It follows that both sides of (3.4) are zero and we must have

$$(3.5) \quad D^2v = \frac{a + 1}{n}v^{-1}|\nabla v|^2g, \quad Ric(\nabla v, \nabla v) = 0.$$

If $q < \frac{4n}{5n - 9}$ or $\lambda(q - 1) < 1$ we have $A < 0$ or $B < 0$, respectively and hence v must be constant. It remains to prove that v must also be constant when

$$(3.6) \quad q = \frac{4n}{5n - 9}, \quad \lambda(q - 1) = 1.$$

Under this assumption, we have

$$a = \frac{1}{\frac{3}{2}q - 1} = \frac{5n - 9}{n + 9}.$$

As $Ric \geq 0$ the second equation in (3.5) implies $Ric(\nabla v, \cdot) = 0$. We denote

$$h = \frac{a + 1}{n}v^{-1}|\nabla v|^2 = \frac{6}{n + 9}v^{-1}|\nabla v|^2.$$

Then $D^2v = hg$. Working with a local orthonormal frame we differentiate

$$\begin{aligned} h_j &= v_{ij,i} = v_{ii,j} - R_{jiii}v_l \\ &= (\Delta v)_j + R_{jl}v_l \\ &= nh_j. \end{aligned}$$

Thus $h_j = 0$, i.e. h is constant. To continue, we observe that since

$$|\nabla v|^2 = \frac{n+9}{6}hv,$$

differentiating both sides we get

$$\frac{n+9}{6}hv_j = 2v_iv_{ij} = 2hv_j.$$

Therefore

$$(n-3)h\nabla v = 0.$$

Taking inner product on both sides with ∇v and using the fact $v > 0$, we see $(n-3)h^2 = 0$. When $n \neq 3$, we have $h = 0$ and hence $\nabla v = 0$ and v must be a constant function.

It remains to handle the case $n = 3$, $q = 2$ and $\lambda = 1$. We need to further inspect the proof and observe that we used the inequality $-D^2\psi(\nabla v, \nabla v) \geq |\nabla v|^2$ on $M \setminus \mathcal{C}$. Therefore this must be an equality. Then this implies that

$$-D^2\psi(\nabla v, \cdot) = \langle \nabla v, \cdot \rangle.$$

As $-\nabla\psi = \nu$ on the boundary the above identity implies $\Pi(\nabla f, \cdot) = \langle \nabla f, \cdot \rangle$ on Σ . As $D^2v = hg$ we have for $X \in T\Sigma$

$$\begin{aligned} 0 &= D^2v(X, \nu) \\ &= X\chi - \Pi(\nabla f, X) \\ &= X\chi - Xf. \end{aligned}$$

Thus $\chi - f$ is constant. But as $\chi = 2(f - f^{1/2})$ by the boundary condition we conclude f is constant. Therefore v is constant.

4. Maximum principle argument in dimension 2

It is unfortunate that the integral argument in previous section only works for $1 < q \leq 8$ in dimension 2. On the other hand, in [E1, P], an approach based on maximum principle is developed to derive a sharp lower bound of the first Steklov eigenvalue on a compact surface with boundary. This idea is also used in [W1] to prove the limiting case $q = \infty$. Surprisingly this type of argument works for any power $q \geq 2$.

Throughout this section (Σ, g) is a smooth compact surface with Gaussian curvature $K \geq 0$ and geodesic curvature $\kappa \geq 1$ on the boundary. Our goal is to prove the following uniqueness result.

Theorem 4. *Let $u > 0$ be a smooth function on Σ satisfying the following equation*

$$\begin{aligned} \Delta u &= 0 && \text{on } \Sigma, \\ \frac{\partial u}{\partial \nu} + \lambda u &= u^q && \text{on } \partial\Sigma, \end{aligned}$$

where λ is a positive constant and $q \geq 2$. Then u must be a constant function if $\lambda \leq \frac{1}{q-1}$.

Theorem 3 follows by combining the above theorem and Theorem 2.

To prove Theorem 4 we write $u = v^{-a}$, with $a \neq 0$ to be determined. Then v satisfies

$$\begin{aligned} \Delta v &= (a+1)v^{-1}|\nabla v|^2 & \text{on } \Sigma, \\ \chi &= \frac{1}{a}(\lambda f - f^{1+a-aq}) & \text{on } \partial\Sigma, \end{aligned}$$

where $f = v|_{\partial\Sigma}$, $\chi = \frac{\partial v}{\partial \nu}$. Let $\phi = v^b|\nabla v|^2$ with b to be determined.

Proposition 5. *We have*

$$(4.1) \quad \Delta\phi - 2(a+b+1)v^{-1}\langle\nabla v, \nabla\phi\rangle \geq [a(a-b) - (b+1)^2]v^{-b-2}\phi^2.$$

Proof. We have $|\nabla v|^2 = v^{-b}\phi$. We compute

$$\begin{aligned} \Delta|\nabla v|^2 &= v^{-b}\Delta\phi - 2bv^{-b-1}\langle\nabla v, \nabla\phi\rangle + \phi\Delta v^{-b} \\ &= v^{-b}\Delta\phi - 2bv^{-b-1}\langle\nabla v, \nabla\phi\rangle + \phi\left[-bv^{-b-1}\Delta v + b(b+1)v^{-b-2}|\nabla v|^2\right] \\ &= v^{-b}\Delta\phi - 2bv^{-b-1}\langle\nabla v, \nabla\phi\rangle + b(b-a)v^{-2b-2}\phi^2. \end{aligned}$$

Using the Bochner formula we obtain

$$\begin{aligned} &v^{-b}\Delta\phi - 2bv^{-b-1}\langle\nabla v, \nabla\phi\rangle + b(b-a)v^{-2b-2}\phi^2 \\ &\geq 2|D^2v|^2 + 2\langle\nabla v, \nabla\Delta v\rangle \\ &\geq (\Delta v)^2 + 2\langle\nabla v, \nabla\Delta v\rangle \\ &= (a+1)^2v^{-2b-2}\phi^2 + 2(a+1)[v^{-b-1}\langle\nabla v, \nabla\phi\rangle - (b+1)v^{-2b-2}\phi^2] \\ &= (a+1)(a-2b-1)v^{-2b-2}\phi^2 + 2(a+1)v^{-b-1}\langle\nabla v, \nabla\phi\rangle. \end{aligned}$$

Therefore

$$\Delta\phi - 2(a+b+1)v^{-1}\langle\nabla v, \nabla\phi\rangle \geq [a(a-b) - (b+1)^2]v^{-b-2}\phi^2.$$

□

We impose the following condition on a and b

$$(4.2) \quad a(a-b) - (b+1)^2 > 0.$$

As a result, $\Delta\phi - 2(a+b+1)v^{-1}\langle\nabla v, \nabla\phi\rangle \geq 0$. By the maximum principle, ϕ achieves its maximum somewhere on the boundary. We use the arclength s to parametrize the boundary. Suppose that ϕ achieves its maximum at s_0 on the boundary. Then we have

$$\phi'(s_0) = 0, \phi''(s_0) \leq 0, \frac{\partial\phi}{\partial\nu}(s_0) \geq 0.$$

Moreover by the Hopf lemma, the 3rd inequality is strict unless ϕ is constant.

Proposition 6. *We have*

$$\frac{\partial\phi}{\partial\nu} \leq 2f^b \left[\left(\left(\frac{b}{2} + a + 1 \right) \frac{\chi}{f} - 1 \right) \left((f')^2 + \chi^2 \right) + f'\chi' - \chi f'' \right].$$

Proof. We compute

$$\begin{aligned}\frac{\partial\phi}{\partial\nu} &= 2f^b D^2v(\nabla v, \nu) + bf^{b-1}\chi\left((f')^2 + \chi^2\right) \\ &= 2f^b \left[\chi D^2v(\nu, \nu) + f' D^2v\left(\frac{\partial}{\partial s}, \nu\right) + \frac{b\chi}{2f}\left((f')^2 + \chi^2\right) \right].\end{aligned}$$

On one hand

$$\begin{aligned}D^2v\left(\frac{\partial}{\partial s}, \nu\right) &= \left\langle \nabla_{\frac{\partial}{\partial s}} \nabla v, \nu \right\rangle \\ &= \chi' - \left\langle \nabla v, \nabla_{\frac{\partial}{\partial s}} \nu \right\rangle \\ &= \chi' - f' \left\langle \frac{\partial}{\partial s}, \nabla_{\frac{\partial}{\partial s}} \nu \right\rangle \\ &= \chi' - \kappa f'.\end{aligned}$$

On the other hand from the equation of v we have on $\partial\Sigma$

$$D^2v(\nu, \nu) + \kappa\chi + f'' = (a+1)f^{-1}\left((f')^2 + \chi^2\right).$$

Plugging the above two identities into the formula for $\frac{\partial\phi}{\partial\nu}$ yields

$$\frac{\partial\phi}{\partial\nu} = 2f^b \left[\left(\left(\frac{b}{2} + a + 1 \right) \frac{\chi}{f} - \kappa \right) \left((f')^2 + \chi^2 \right) + f'\chi' - \chi f'' \right].$$

where in the last step we use the assumption $\kappa \geq 1$. □

As

$$\phi(s) := \phi|_{\partial\Sigma} = f(s)^b \left(f'(s)^2 + \chi(s)^2 \right),$$

we obtain

$$\phi'(s) = 2f^b f' \left[f'' + \frac{1}{a}\chi(\lambda - (1+a-aq)f^{a-aq}) + \frac{b}{2f}(f'^2 + \chi^2) \right].$$

If $f'(s_0) \neq 0$ then at s_0

$$f'' = -\frac{1}{a}\chi(\lambda - (1+a-aq)f^{a-aq}) - \frac{b}{2f}(f'^2 + \chi^2).$$

Therefore

$$\begin{aligned}\frac{\partial\phi}{\partial\nu} &\leq 2f^b \left[\left(\left(\frac{b}{2} + a + 1 \right) \frac{\chi}{f} - 1 \right) \left((f')^2 + \chi^2 \right) + f'\chi' \right. \\ &\quad \left. + \frac{1}{a}\chi^2(\lambda - (1+a-aq)f^{a-aq}) + \frac{b\chi}{2f}(f'^2 + \chi^2) \right] \\ &= 2f^b \left((f')^2 + \chi^2 \right) \left[\frac{a+b+1}{a}(\lambda - f^{a-aq}) - 1 + \frac{1}{a}(\lambda - (1+a-aq)f^{a-aq}) \right] \\ &= 2f^b \left((f')^2 + \chi^2 \right) \left[\frac{a+b+2}{a}\lambda - 1 - \frac{(2-q)a+b+2}{a}f^{a-aq} \right].\end{aligned}$$

We want

$$\begin{aligned} \frac{a+b+2}{a}\lambda - 1 &\leq 0, \\ (2-q)a + b + 2 &= 0. \end{aligned}$$

Therefore we choose $b = (q-2)a - 2$. Then the 1st equation is simply $(q-1)\lambda \leq 1$. The condition (4.2) becomes

$$(q^2 - 3q + 1)a^2 - 2(q-1)a + 1 < 0.$$

A solution always exists as the discriminant equals $4q > 0$. Under such choices for a and b we have $\frac{\partial\phi}{\partial\nu}(s_0) \leq 0$. Therefore ϕ is constant.

If $f'(s_0) = 0$ then at s_0

$$\phi''(s_0) = 2f^b f'' \left[f'' + \frac{1}{a}\chi(\lambda - (1+a-aq)f^{a-aq}) + \frac{b}{2}\frac{\chi^2}{f} \right] \leq 0.$$

Therefore we have at s_0

$$(f'')^2 + f''\chi \left[(q-1)\lambda - \frac{qa}{2}\frac{\chi}{f} \right] \leq 0.$$

while the condition $\frac{\partial\phi}{\partial\nu}(s_0) \geq 0$ becomes

$$\left(\frac{qa}{2}\frac{\chi}{f} - 1 \right) \chi^2 - \chi f'' \geq 0.$$

Set $A = (q-1)\lambda - \frac{qa}{2}\frac{\chi}{f}$. We have $\frac{qa}{2}\frac{\chi}{f} - 1 \leq \frac{qa}{2}\frac{\chi}{f} - (q-1)\lambda = -A$. Therefore the above two inequalities imply

$$\begin{aligned} \chi(A\chi + f'') &\leq 0, \\ f''(A\chi + f'') &\leq 0. \end{aligned}$$

We have

$$A = (q-1)\lambda - \frac{q}{2}(\lambda - f^{a-qa}) = \left(\frac{q}{2} - 1\right)\lambda + \frac{q}{2}f^{a-qa} \geq 0$$

if $q \geq 2$. Combining the two inequalities we then get $(A\chi + f'')^2 \leq 0$. Therefore $A\chi + f'' = 0$. Then again we have $\frac{\partial\phi}{\partial\nu}(s_0) \leq 0$ and ϕ must be constant.

In all cases we have proved that ϕ is constant. As the coefficient on the right hand side of (4.1) is positive, we must have $\phi \equiv 0$. Therefore u is constant. This finishes the proof of Theorem 4.

5. Further discussions

Let (M^n, g) be a smooth compact Riemannian manifold with boundary Σ . We consider for $1 < q \leq \frac{n}{n-2}$ and $\lambda > 0$ the functional

$$J_{q,\lambda}(u) = \frac{\int_M |\nabla u|^2 + \lambda \int_\Sigma u^2}{\left(\int_\Sigma |u|^{q+1} \right)^{\frac{2}{q+1}}}, \quad u \in H^1(M) \setminus \{0\}.$$

The first variation in the direction of \dot{u} is

$$\begin{aligned} & 2 \left[\frac{\int_M \langle \nabla u, \nabla \dot{u} \rangle + \lambda \int_\Sigma u \dot{u}}{\left(\int_\Sigma |u|^{q+1}\right)^{\frac{2}{q+1}}} - \frac{\int_M |\nabla u|^2 + \lambda \int_\Sigma u^2}{\left(\int_\Sigma |u|^{q+1}\right)^{1+\frac{2}{q+1}}} \int_\Sigma |u|^q \dot{u} \right] \\ &= \frac{2}{\left(\int_\Sigma |u|^{q+1}\right)^{\frac{2}{q+1}}} \left[- \int_M \dot{u} \Delta u + \int_\Sigma \left(\frac{\partial u}{\partial \nu} + \lambda u \right) \dot{u} - \frac{\int_M |\nabla u|^2 + \lambda \int_\Sigma u^2}{\int_\Sigma |u|^{q+1}} \int_\Sigma |u|^q \dot{u} \right] \end{aligned}$$

Thus a positive u is a critical point iff

$$\begin{aligned} \Delta u &= 0 && \text{on } M, \\ \frac{\partial u}{\partial \nu} + \lambda u &= cu^q && \text{on } \Sigma, \end{aligned}$$

with $c = \frac{\int_M |\nabla u|^2 + \lambda \int_\Sigma u^2}{\int_\Sigma |u|^{q+1}}$. In particular $u_0 \equiv 1$ is a critical point. The second variation at u_0 in the direction of \dot{u} with $\int_\Sigma \dot{u} = 0$ is

$$\begin{aligned} & \frac{2}{|\Sigma|^{\frac{2}{q+1}}} \left[- \int_M \dot{u} \Delta \dot{u} + \int_\Sigma \left(\frac{\partial \dot{u}}{\partial \nu} + \lambda \dot{u} \right) \dot{u} - \lambda q \left(\dot{u} \right)^2 \right] \\ &= \frac{2}{|\Sigma|^{\frac{2}{q+1}}} \left[\int_M |\nabla \dot{u}|^2 - \lambda (q-1) \int_\Sigma \left(\dot{u} \right)^2 \right]. \end{aligned}$$

Therefore u_0 is stable iff $\lambda(q-1) \leq \sigma_1$, the first Steklov eigenvalue. On $\overline{\mathbb{B}^n}$ the first Steklov eigenvalue is 1. Therefore u_0 is not stable on $\overline{\mathbb{B}^n}$ when $\lambda(q-1) > 1$. As the trace operator $H^1(M) \rightarrow L^q(\Sigma)$ is compact when $q < \frac{n}{n-2}$, $\inf J_{q,\lambda}$ is always achieved. Therefore we get the following

Proposition 7. *If $q < \frac{n}{n-2}$ and $\lambda(q-1) > 1$ then the equation*

$$\begin{aligned} \Delta u &= 0 && \text{on } \overline{\mathbb{B}^n}, \\ \frac{\partial u}{\partial \nu} + \lambda u &= u^q && \text{on } \partial \overline{\mathbb{B}^n}, \end{aligned}$$

admits a positive, nonconstant solution.

In the general case, under the assumption that $Ric \geq 0$ and $\Pi \geq 1$ on Σ , Conjecture 1 claims that u_0 , up to scaling, is the only positive critical point of $J_{q,\lambda}$ if $\lambda(q-1) \leq 1$. In particular we must have $\sigma_1 \geq 1$ if the conjecture is true for a single exponent q . Therefore Conjecture 1 implies the following conjecture of Escobar [E2].

Conjecture 2 ([E2]). *Let (M^n, g) be a compact Riemannian manifold with boundary with $Ric \geq 0$ and $\Pi \geq 1$ on Σ . Then the 1st Steklov eigenvalue $\sigma_1 \geq 1$.*

In [E1], the conjecture is confirmed when $n = 2$, extending the method of [P], where the same estimate for a planar domain is derived. In other dimensions, under the stronger assumption that M has nonnegative sectional curvature, the conjecture was proved recently in [XX]. By the previous discussion, Theorem 2 implies estimate in [XX] when $2 \leq n \leq 8$ and can be viewed as a nonlinear generalization. Theorem 2 also gives us the following sharp Sobolev inequalities (see also the discussions in [W2]).

Corollary 1. *Let (M^n, g) be a smooth compact Riemannian manifold with nonnegative sectional curvature and $\Pi \geq 1$ on the boundary Σ . Assume $2 \leq n \leq 8$ and $1 < q \leq \frac{4n}{5n-9}$. Then*

$$(5.1) \quad \left(\frac{1}{|\Sigma|} \int_{\Sigma} |u|^{q+1} \right)^{2/(q+1)} \leq \frac{q-1}{|\Sigma|} \int_M |\nabla u|^2 + \frac{1}{|\Sigma|} \int_{\Sigma} u^2.$$

In the limiting case we can deduce the following logarithmic inequality.

Corollary 2. *Let (M^n, g) be a compact Riemannian manifold with nonnegative sectional curvature and $\Pi \geq 1$ on the boundary Σ . Assume $2 \leq n \leq 8$. Then for any $u \in C^\infty(M)$ with $\frac{1}{|\Sigma|} \int_{\Sigma} u^2 = 1$, we have*

$$\frac{1}{|\Sigma|} \int_{\Sigma} |u|^2 \log u^2 \leq \frac{2}{|\Sigma|} \int_M |\nabla u|^2.$$

Proof. Under the assumption on u (5.1) can be written as

$$\frac{1}{q-1} \left[\left(\frac{1}{|\Sigma|} \int_{\Sigma} |u|^{q+1} \right)^{2/(q+1)} - 1 \right] \leq \frac{1}{|\Sigma|} \int_M |\nabla u|^2.$$

Taking limit $q \downarrow 1$ and applying L'Hospital's rule yields the desired inequality. \square

Remark 1. *Linearization of the above inequality around $u_0 \equiv 1$ yields the inequality $\sigma_1 \geq 1$, i.e. if $\int_{\Sigma} u = 0$, then*

$$\int_{\Sigma} u^2 \leq \int_M |\nabla u|^2.$$

In dimension two we have a complete result in Theorem 3. As a corollary we have

Corollary 3. *Let (Σ, g) be a smooth compact surface with nonnegative Gaussian curvature and geodesic curvature $\kappa \geq 1$. Then for any $u \in H^1(\Sigma)$ and $q \geq 1$, we have*

$$L^{(q-1)/(q+1)} \left(\int_{\partial\Sigma} |u|^{q+1} \right)^{2/(q+1)} \leq (q-1) \int_{\Sigma} |\nabla u|^2 + \int_{\partial\Sigma} u^2.$$

Here L is the length of $\partial\Sigma$. Moreover, equality holds iff u is a constant function.

Finally we recall the following Moser-Trudinger-Onofri type inequality on the disc $\overline{\mathbb{B}^2}$ derived in [OPS]: for any $u \in H^1(\mathbb{B}^2)$,

$$(5.2) \quad \log \left(\frac{1}{2\pi} \int_{\mathbb{S}^1} e^u \right) \leq \frac{1}{4\pi} \int_{\mathbb{B}^2} |\nabla u|^2 + \frac{1}{2\pi} \int_{\mathbb{S}^1} u.$$

In [W1] the following generalization was proved

Theorem 5 ([W1]). *Let (Σ, g) be a smooth compact surface with nonnegative Gaussian curvature and geodesic curvature $\kappa \geq 1$. Then for any $u \in H^1(\Sigma)$,*

$$\log \left(\frac{1}{L} \int_{\partial\Sigma} e^f \right) \leq \frac{1}{2L} \int_{\Sigma} |\nabla f|^2 + \frac{1}{L} \int_{\partial\Sigma} f.$$

Here L is the length of $\partial\Sigma$. Moreover if equality holds at a nonconstant function, then Σ is isometric to $\overline{\mathbb{B}^2}$ and all extremal functions are of the form

$$u(x) = \log \frac{1 - |a|^2}{1 + |a|^2 |x|^2 - 2x \cdot a} + c,$$

for some $a \in \mathbb{B}^2$ and $c \in \mathbb{R}$.

The argument in [W1] is by a variational approach based on the inequality (5.2). We can deduce the above inequality directly from Corollary 3. Indeed, taking $u = 1 + \frac{f}{q+1}$ in Corollary 3 we obtain

$$\left(\frac{1}{L} \int_{\partial\Sigma} \left(1 + \frac{f}{q+1} \right)^{q+1} \right)^{2/(q+1)} \leq \frac{(q-1)}{(q+1)^2} \frac{1}{L} \int_{\Sigma} |\nabla f|^2 + \frac{1}{L} \int_{\partial\Sigma} \left(1 + \frac{f}{q+1} \right)^2.$$

This can be rewritten as

$$\begin{aligned} & (q+1) \left\{ \exp \left[\frac{2}{q+1} \log \frac{1}{L} \int_M \left(1 + \frac{f}{q+1} \right)^{q+1} \right] - 1 \right\} \\ & \leq \frac{(q-1)}{(q+1)} \frac{1}{L} \int_{\Sigma} |\nabla f|^2 + \frac{2}{L} \int_{\partial\Sigma} f + \frac{1}{q+1} \frac{1}{L} \int_{\partial\Sigma} f^2. \end{aligned}$$

Letting $q \rightarrow \infty$ we get

$$\log \frac{1}{L} \int_M e^f \leq \frac{1}{2L} \int_{\Sigma} |\nabla f|^2 + \frac{1}{L} \int_{\partial\Sigma} f.$$

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