

Math 930 Problem Set 5

Due Wednesday, October 8

Problem 5.1 An *orthonormal moving frame* on an open set U in a Riemannian manifold is a set $\{e_1, \dots, e_n\}$ of $n = \dim M$ vector fields on U that is everywhere orthonormal, i.e. $g(e_i, e_j) = \delta_{ij} \quad \forall i, j$. In calculations, it is often more convenient to use moving frames instead of local coordinates.

- (a) Prove that each $p \in M$ has a neighborhood U such that there is an ON moving frame $\{e_i\}$ on U with $(\nabla_{e_i} e_j)_p = 0$ for all i, j . (Hint: Normal coordinates and Gram-Schmidt).
- (b) Let $\{e_i\}$ be an ON moving frame. Show that the dual frame $\{e^i\}$ is an orthonormal set of 1-forms when the metric on T^*M is defined by $\langle \alpha, \beta \rangle = \sum_i \alpha(e_i)\beta(e_i)$.
- (c) Given a moving frame, we define the *connection 1-forms* ω_i^j

$$\nabla_{e_i} e^j = \sum_k \omega_k^j(e_i) e^k.$$

Show that the connection is compatible with the metric if and only if $\omega_i^j = -\omega_j^i$, i.e. ω_i^j is a 1-form with values in the Lie algebra $\mathfrak{so}(n)$ of $n \times n$ skew-symmetric matrices.

Problem 5.2 Let N be a closed embedded submanifold of a complete Riemannian manifold M . For any point $p \in M \setminus N$, we define the distance from p to N to be

$$d(p, N) = \inf \{d(p, x) \mid x \in N\}.$$

- (a) Use the continuity of $d(x, y)$ to prove that there is a point $q \in N$ that realizes this distance.
- (b) The Hopf-Rinow Theorem then implies that there is a minimizing geodesic γ from p to q . Use the first variational formula (set up the variation carefully) to prove that γ intersects N orthogonally.

Problem 5.3 Do Problem 6.6 on page 113 of the textbook.

Problem 5.4 Let $E \rightarrow M$ be a vector bundle with connection ∇ . The *covariant section derivative* of a section $\xi \in \Gamma(E)$ in the direction of vector fields X and Y is defined by

$$\nabla_{X,Y}^2 \xi = \nabla_X \nabla_Y \xi - \nabla_{\nabla_X Y} \xi.$$

Prove that ∇^2 is tensorial in X and Y , i.e. $\nabla_{fX,Y}^2 \xi = f \nabla_{X,Y}^2 \xi$ and $\nabla_{X,fY}^2 \xi = f \nabla_{X,Y}^2 \xi$ for all $f \in C^\infty(M)$.