Math 868 — Homework 1

Due Weds, Sept. 5

- 1. Prove that a bijective map between manifolds need not be a diffeomorphism. In fact, show that $f : \mathbf{R} \to \mathbf{R}$ by $f(x) = x^3$ is an example.
- 2. The graph of a function $f: M \to \mathbf{R}$ on a manifold M is the set

$$G_f = \{ (x, f(x)) \, | \, x \in M \}.$$

Define $\phi: M \to G_f$ by $\phi(x) = (x, f(x))$. Prove that if f is smooth then ϕ is a diffeomorphism; this means that the graph is a manifold.

- 3. Let T be the torus consisting of all points in \mathbb{R}^3 that are distance 1 from the circle of radius 2 in the xy-plane. Prove that T is diffeomorphic to $S^1 \times S^1$ by writing down a map $\phi : S^1 \times S^1 \to T$ and showing that ϕ is 1-1, onto, smooth and has a smooth inverse.
- 4. Prove that one cannot parametrize the sphere S^n by a single chart $\phi : S^n \to V \subset \mathbf{R}^n$. (*Hint:* the sphere is compact.)
- 5. Do Problem 1-5 on page 28 of the textbook (on stereographic projection).
- 6. This problem gives the steps for constructing a " C^{∞} bump function". Pages 49-51 in the textbook describe a similar but not identical construction.
 - (a) An extremely useful function $f : \mathbf{R} \to \mathbf{R}$ is

$$f(x) = \begin{cases} e^{-1/x^2} & x > 0\\ 0 & x \le 0 \end{cases}$$

Sketch the graph of f and prove that f is smooth (use the fact that the composition of smooth functions is smooth, that e^x and $1/x^2$ (for $x \neq 0$) are smooth, and explicitly show that all derivatives of f are continuous at x = 0).

- (b) Fix 0 < a < b. Sketch the graph of g(x) = f(x-a)f(b-x) and show that g is a smooth function, positive on the interval (a, b) and 0 elsewhere.
- (c) Sketch the graph of

$$h(x) = \frac{\int_{-\infty}^{x} g \, dx}{\int_{-\infty}^{\infty} g \, dx}$$

This is a smooth function satisfying h(x) = 0 for x < a, h(x) = 1 for x > b and 0 < h(x) < 1 for all $x \in (a, b)$ (no proof needed here).

- (d) Now construct a smooth "bump function" $\beta(x)$ on \mathbb{R}^n that equals 1 on the ball B(0, a), is zero outside the ball B(0, b) and is strictly between 0 and 1 at the intermediate points.
- 7. (a) The tangent space to the unit circle S^1 at p = (a, b) is a 1-dimensional subspace of R^2 . Use the definition of tangent space to prove that $T_p S^1$ is the span of (-b, a).
 - (b) Similarly use the definition of tangent space to find two vectors that are a basis of $T_p S^2$ at a point p = (a, b, c). (This can be done by simple geometry but don't do that. Use the definition of tangent space).