## Math 415

## Homework Set 2

due Friday, Jan 27

- 1. Let  $V = C^{\infty}(\mathbb{R})$  be the vector space of all functions that have derivatives of all orders. Let  $D: V \to V$  be the derivative (i.e.  $Df = \frac{df}{dx}$ ).
  - (a) What is the kernel of D?
  - (b) Let  $D^2$  be the second derivative. What is the kernel of  $D^2$ ?
  - (c) What is the kernel of  $D^n: V \to V$ ?
- 2. With V and D as above, let L = D I where I is the identity transformation of V to V.
  - (a) What is ker L? Answer by completing the sentence: ker L is the set of all functions in V such that ....
  - (b) Same question for L = D aI for any real number a.
- 3. Let  $L: V \to W$  be a linear transformation. Fix a vector in  $w_0$  and think about solving the equation  $Lv = w_0$  for the unknown v. Suppose that  $v_0$  is one solution. Show that every other solution is of the form  $v = v_0 + u$  where  $u \in \ker L$ .
- 4. Let V and D be as in Problem 1 and let g by an arbitrary element of V. Explain how the problem of solving the differential equation

$$a\frac{d^2f}{dx^2} + b\frac{df}{dx} + cf = g$$

fits into the abstract situation described in Problem 3.

The next 5 problems are Problems 6-10 for Section 2.3 in Sadun's book. Notation:  $\mathbb{R}_d[t]$  denotes the vector space of all polynomials of degree  $\leq d$  in the variable t with real coefficients, and  $M_{m,n}$  denotes the vector space of all  $m \times n$  matrices with real entries.

- 5. Let  $V = \mathbb{R}_2[t]$ . Determine whether the vectors  $\mathbf{b}_1 = 1 + t + t^2$ ,  $\mathbf{b}_2 = 1 + 2t + 3t^2$ ,  $\mathbf{b}_3 = 1 + 4t + 9t^2$  are linearly independent, span V, and/or are a basis.
- 6. Let V be the subspace of  $\mathbb{R}_3[t]$  consisting of all polynomials **p** with  $\mathbf{p}(0) = 0$ . Determine whether the vectors

$$\mathbf{b}_1 = t^2 - t$$
  $\mathbf{b}_2 = t^3 + t^2 + t$   $\mathbf{b}_3 = 2t^3 - 5t^2 - 7t$ 

are linearly independent, span V, and/or are a basis.

7. Let V be the subspace of  $\mathbb{R}_3[t]$  consisting of all polynomials **p** with  $\mathbf{p}(1) = 0$ . Determine whether the vectors

$$\mathbf{b}_1 = t^2 - t$$
  $\mathbf{b}_2 = t^3 + t^2 + t - 3$   $\mathbf{b}_3 = 2t^3 - 5t^2 - 7t + 10$ 

are linearly independent, span V, and/or are a basis.

- 8. In  $M_{2,2}$ , are the matrices  $\mathbf{A}_1 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ ,  $\mathbf{A}_2 = \begin{pmatrix} 1 & 2 \\ 2 & -1 \end{pmatrix}$ ,  $\mathbf{A}_3 = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$  linear independent, a spanning set, and/or a basis?
- 9. Let V be the subspace of  $M_{2,2}$  consisting of all symmetric matrices, i.e. those of the form

$$A = \begin{pmatrix} a & b \\ b & c \end{pmatrix}.$$

What is the dimension of V? Find a basis.

The remaining problems are taken from Section 3.2 of Sadun's book and Section 3 of Treil's book (your class notes form Monday should allow you to do these).

10. For each linear transformation below find its matrix.

(a) 
$$T : \mathbb{R}^2 \to \mathbb{R}^2$$
 defined by  $T\begin{pmatrix} x\\ y \end{pmatrix} = \begin{pmatrix} y\\ x \end{pmatrix}$ .  
(b)  $T : \mathbb{R}^2 \to \mathbb{R}^3$  defined by  $T\begin{pmatrix} x\\ y \end{pmatrix} = \begin{pmatrix} x+2y\\ 2x-5y\\ 7y \end{pmatrix}$ .

- (c)  $T: \mathbb{R}^2 \to \mathbb{R}^2$  by counterclockwise rotation through 45 degrees.
- 11. Find  $3 \times 3$  matrices representing the transformations of  $\mathbb{R}^3$  which:
  - (a) project every vector to the xy plane,
  - (b) reflect every vector through the xy plane
  - (c) rotate the xy plane counterclockwise through  $30^{\circ}$ , leaving the z-axis fixed.
- 12. Let  $V = \mathbb{R}_3[t]$  and let  $D: V \to V$  be the differentiation transformation  $Df = \frac{df}{dt}$ . Using the standard basis  $\{1, t, t^2, t^3\}$  of V (in that order!),
  - (a) Write down the matrix for D (done in class and in Sadun's Section 3.2).
  - (b) Write down the matrix for the second derivative transformation  $L(f) = \frac{d^2f}{dt^2}$ . Show by matrix multiplication that  $L = D^2$ .
  - (c) Use your answers to parts (a) and (b) to write down the matrix for the transformation T defined by

$$(Tf)(t) = 2f(t) + 3f'(t) - 4f''(t)$$