Sept. 21, 2018 Prof. T. Parker

## Math 309 §2 — Exam 1

Do all 7 problems. You must show your work to receive credit. No books, notes, or electronic devices.

- 1. (21 points) Consider the system  $\begin{cases} x+y-w = 0\\ 3x+2y-z = 1\\ 4x+5y+z-5w = -1 \end{cases}$ 
  - (a) Write the system as an augmented matrix and find the reduced row echelon form. Label your row operations.

$$\begin{pmatrix} 1 & 1 & 0 & -1 & | & 0 \\ 3 & 2 & -1 & 0 & | & 1 \\ 4 & 5 & 1 & -5 & | & -1 \end{pmatrix} \approx \begin{pmatrix} 1 & 1 & 0 & -1 & | & 0 \\ 0 & -1 & -1 & 3 & | & 1 \\ R_2 - 3R_1 & 0 & | & 1 & -1 & | & -1 \end{pmatrix} \approx \begin{pmatrix} 1 & 0 & -1 & 2 & | & 1 \\ 0 & 1 & | & -3 & | & -1 \\ R_1 + R_2 & 0 & | & 1 & -1 & | & -1 \end{pmatrix}$$

$$\begin{array}{l}
\approx \\
R_{3}-R_{2} & \begin{pmatrix} 1 & 0 & -1 & 2 & | & 1 \\
0 & 1 & 1 & 3 & | & -1 \\
0 & 0 & 0 & 2 & | & 0 \end{pmatrix}
\end{array}$$

$$\begin{array}{l}
\approx \\
R_{1}-R_{3} & \begin{pmatrix} 1 & 0 & -1 & 0 & | & 1 \\
0 & 1 & 1 & -3 & | & -1 \\
0 & 0 & 0 & | & | & 0 \end{pmatrix}$$

$$\begin{array}{l}
\approx \\
R_{2}+3R_{3} & \begin{pmatrix} 1 & 0 & -1 & 0 & | & 1 \\
0 & 1 & 1 & 0 & | & -1 \\
0 & 0 & 0 & | & | & 0 \end{pmatrix}$$

$$\begin{array}{l}
\approx \\
R_{1}-R_{3} & \begin{pmatrix} 1 & 0 & -1 & 0 & | & 1 \\
0 & 1 & 1 & 0 & | & -1 \\
0 & 0 & 0 & | & | & 0 \end{pmatrix}$$

$$\begin{array}{l}
\approx \\
R_{1}-R_{3} & \begin{pmatrix} 1 & 0 & -1 & 0 & | & 1 \\
0 & 0 & 0 & | & | & 0 \\
R_{1}-R_{3} & \begin{pmatrix} 1 & 0 & -1 & 0 & | & 1 \\
0 & 0 & 0 & | & | & 0 \\
R_{2}+3R_{3} & \begin{pmatrix} 0 & 0 & 0 & | & 1 \\
0 & 0 & 0 & | & | & 0 \\
R_{2}+3R_{3} & \begin{pmatrix} 0 & 0 & 0 & | & 1 \\
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R_{4}+3R_{3} & | & 0 & | & 0 & | & 0 & | & 0 \\
R_{4}+3R_{$$

(b) Write down the solution set S in terms of free variables. Use set notation.

- 2. (18 points) Write (T) if TRUE or (F) if FALSE.
  - (a) For a homogeneous linear system  $A\mathbf{x} = \mathbf{0}$ , the number of free variables in the solution set is equal to the number of non-pivot columns.
  - (b) If the augmented matrix of a linear system has only 0s in its bottom row, then the system is inconsistent.
  - (c) The product AB of matrices is defined only if A and B are both  $n \times n$  square matrices.
  - (d) For matrices A and B, AB = BA whenever both sides are defined.



(e) For matrices A, B and C, (AB)C = A(BC) whenever both sides are defined.



(f)  $(AB)^T = A^T B^T$  for all  $n \times n$  matrices A and B.



(g) If matrices A and B are row-equivalent, then A = EB for some elementary matrix E.



- (h) The xy plane is a vector subspace of  $\mathbb{R}^3$ .
- (i) If S is a subspace of a vector space V and  $\mathbf{x}, \mathbf{y}, \mathbf{z} \in S$ , then  $2\mathbf{x} + 8\mathbf{y} 3\mathbf{z} \in S$ .



- 3. (12 points) Complete the definition or statement. Make your wording precise.
  - (a) The inverse of an  $n \times n$  matrix A is an  $n \times n$  matrix B such that ...

(b) The **null space** of an  $n \times n$  matrix A is

$$N(A) = \left\{ \overrightarrow{\mathbf{x}} \in \mathbb{R}^n \middle| A\overrightarrow{\mathbf{x}} = \overrightarrow{\mathbf{D}} \right\}.$$

- (c) **Theorem.** For an  $n \times n$  matrix A, the following are equivalent:
  - (a) A is invertible.
  - (a) The linear system Ax = 0 has no solution except  $\vec{x} = \vec{0}$
  - (c) A is row equivalent to \_\_\_\_\_\_
- (d) The matrix  $\begin{pmatrix} 1 & \alpha \\ -3 & 4 \end{pmatrix}$  is non-singular for every value of  $\alpha$  except  $\alpha = \frac{-4/3}{3}$ Reason: Invertible unless 1.4 - x(-3) = 0 => 4+3x=0 = x=-4/3
- 4.(9 points) Complete the proof by filling in the blanks. The axioms A1 A8 are listed at the end of the exam.

Cancellation Law: If v + x = w + x then v = w.

Proof: 
$$v = v+0$$

$$= \underbrace{V + (x + -x)}$$

$$= (v+x) + -x$$

$$= \underbrace{(w+x) + (-x)}$$

$$= \underbrace{W + (x + -x)}$$

$$= \underbrace{W + (x + -x)}$$

$$= \underbrace{W + 2}$$

$$= w$$

$$= \underbrace{A3}$$

$$A4$$

$$A4$$

$$A3$$

5. (15 points) Find the inverse of 
$$B = \begin{pmatrix} 1 & 1 & 1 \\ -1 & 2 & -1 \\ 0 & 0 & 3 \end{pmatrix}$$
. Do not label row operations.

$$\begin{pmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ -1 & 2 & -1 & 0 & 1 & 0 \\ 0 & 0 & 3 & 0 & 0 & 1 \end{pmatrix} \approx \begin{pmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 3 & 0 & 1 & 1 & 0 \\ \frac{1}{3}R_3 & 0 & 0 & 1 & 0 & 0 & \frac{1}{3} \end{pmatrix} \approx \begin{pmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & \frac{1}{3}R_3 & 0 \\ 0 & 0 & 1 & 0 & 0 & \frac{1}{3} \end{pmatrix}$$

$$\stackrel{\sim}{R_1 - R_2 - R_3} \begin{pmatrix}
1 & 0 & 0 & | & \frac{2}{3} & -\frac{1}{3} & -\frac{1}{3} \\
0 & 1 & 0 & | & \frac{1}{3} & \frac{1}{3} & 0 \\
0 & 0 & 1 & | & 0 & 0 & \frac{1}{3}
\end{pmatrix}$$

$$\Rightarrow \mathcal{B}' = \frac{1}{3} \begin{pmatrix} 2 & -1 & -1 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

6. (10 points) A 2 × 2 matrix 
$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$
 is called *symmetric* if  $b = c$ .

Let V be the vector space of all  $2 \times 2$  matrices, and S the set of all symmetric  $2 \times 2$  matrices. Prove that S is a subspace of V. Use sentences to make your reasoning clear.

Proof. For any two elements A, B ∈ S, we can write  $A = \begin{pmatrix} a & b \\ b & e \end{pmatrix}$  and  $B = \begin{pmatrix} d & e \\ e & f \end{pmatrix}$  for some  $a,b,c,d,e,f \in \mathbb{R}$ .

Then

• 
$$A+B=\begin{pmatrix} a b \\ b c \end{pmatrix} + \begin{pmatrix} de \\ ef \end{pmatrix} = \begin{pmatrix} a+d & b+e \\ b+e & c+f \end{pmatrix}$$
 is Symmetric, so

• 
$$\alpha A = \alpha \begin{pmatrix} ab \\ b \end{pmatrix} = \begin{pmatrix} \alpha a & \alpha b \\ \alpha b & \alpha c \end{pmatrix}$$
 is also symmetric, so in S

- 7. (15 points) Suppose that a matrix X satisfies XA + B = A for some matrices A and B.
  - (a) Algebraically solve for X in terms of A and B.

$$XA + B = A$$

$$XA = A - B$$

$$XA \cdot A^{-1} = (A - B) A^{-1}$$

$$= Identity.$$

$$X = (A - B) A^{-1}$$

(b) Find X for in the case where  $A = \begin{pmatrix} 2 & 3 \\ 1 & 5 \end{pmatrix}$  and  $B = \begin{pmatrix} 2 & 1 \\ 0 & 7 \end{pmatrix}$ .

$$A^{-1} = \frac{1}{2 \cdot 5 - 3 \cdot 1} \begin{pmatrix} 5 - 3 \\ -1 \ 2 \end{pmatrix} = \frac{1}{7} \begin{pmatrix} 5 - 3 \\ -1 \ 2 \end{pmatrix}$$

$$A-B = \begin{pmatrix} 2-2 & 3-1 \\ 1-D & 5-7 \end{pmatrix} = \begin{pmatrix} 0 & 2 \\ 1 & -2 \end{pmatrix}$$

$$X = (A-B)A^{-1} = \begin{pmatrix} 0 & 2 \\ 1 & -2 \end{pmatrix} \cdot \frac{1}{7} \begin{pmatrix} 5 & -3 \\ -1 & 2 \end{pmatrix}$$

$$X = \frac{1}{7} \begin{pmatrix} -2 & 4 \\ 7 & -7 \end{pmatrix} \qquad \text{or} \qquad \begin{pmatrix} -\frac{2}{7} & \frac{4}{7} \\ 1 & -1 \end{pmatrix}.$$

The axioms of a vector space V: for all  $\mathbf{x}, \mathbf{y}, \mathbf{z} \in V$  and  $\alpha, \beta \in \mathbb{R}$ ,

**A1.** 
$$x + y = y + x$$

**A2.** (x + y) + z = y + (x + z)

**A3.** 
$$\exists$$
 a vector  $\mathbf{0} \in \mathbf{V}$  s.t.  $\mathbf{x} + \mathbf{0} = \mathbf{x}$  for all  $\mathbf{x} \in V$ .

**A4.** For each 
$$\mathbf{x} \in V$$
, there is a vector  $-\mathbf{x} \in V$  such that  $\mathbf{x} + (-\mathbf{x}) = \mathbf{0}$ 

**A5.** 
$$\alpha(\mathbf{x} + \mathbf{y}) = \alpha \mathbf{x} + \alpha \mathbf{y}$$

**A6.** 
$$(\alpha + \beta)\mathbf{x} = \alpha\mathbf{x} + \beta\mathbf{x}$$

**A7.** 
$$\alpha(\beta \mathbf{x}) = (\alpha \beta) \mathbf{x}$$

A8. 
$$1 \cdot \mathbf{x} = \mathbf{x}$$
.