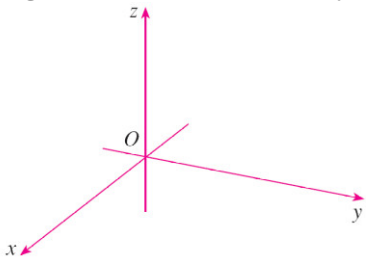
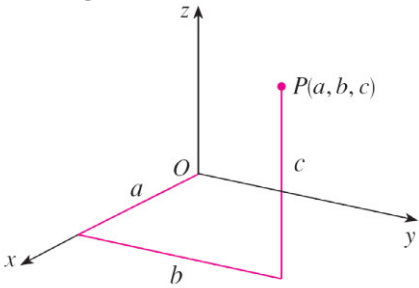
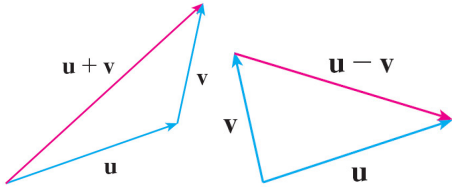
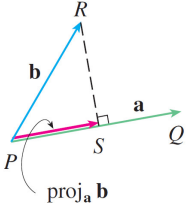


<p>Right-Hand Coordinate System</p> 	<p>Plotting Points in 3D</p> 
<p>Distance Formulas</p> <ul style="list-style-type: none"> For $P = (p_1, p_2, p_3)$ and $Q = (q_1, q_2, q_3)$, $ PQ = \sqrt{(p_1 - q_1)^2 + (p_2 - q_2)^2 + (p_3 - q_3)^2}$ <ul style="list-style-type: none"> The sphere centered at $P = (a, b, c)$ with radius r consists of the points (x, y, z) so that: $(x - a)^2 + (y - b)^2 + (z - c)^2 = r^2$	<p>Vector Formulas</p> <ul style="list-style-type: none"> The length of \vec{PQ} (written \vec{PQ}) is just PQ. (same as for line segment) The unit vector pointing in the direction \vec{v} is $\frac{\vec{v}}{ \vec{v} }$. (scale the vector by the reciprocal of its norm)
<p>Algebraic Vector Arithmetic</p> <p>Suppose that $\vec{v} = \langle v_1, v_2, v_3 \rangle$ and $\vec{w} = \langle w_1, w_2, w_3 \rangle$, and c is a scalar.</p> <ul style="list-style-type: none"> $\vec{v} + \vec{w} = \langle v_1 + w_1, v_2 + w_2, v_3 + w_3 \rangle$ $\vec{v} - \vec{w} = \langle v_1 - w_1, v_2 - w_2, v_3 - w_3 \rangle$ $c\vec{v} = \langle cv_1, cv_2, cv_3 \rangle$ 	<p>Geometric Vector Arithmetic</p> 
<p>The Dot Product</p> <ul style="list-style-type: none"> $\vec{v} \cdot \vec{w} = v_1 w_1 + v_2 w_2 + v_3 w_3$ $\vec{v} \cdot \vec{v} = \vec{v} ^2$ $\vec{v} \cdot \vec{w} = \vec{v} \vec{w} \cos(\theta)$ <p>or $\cos(\theta) = \frac{\vec{v} \cdot \vec{w}}{ \vec{v} \vec{w} }$</p> <p>($\theta$ is the angle between \vec{v} and \vec{w})</p> <ul style="list-style-type: none"> $\vec{v} \cdot \vec{w} = 0$ if and only if \vec{v} and \vec{w} are orthogonal. 	<p>Vector Projections</p>  <ul style="list-style-type: none"> $\text{comp}_{\vec{a}}(\vec{b}) = \text{proj}_{\vec{a}}(\vec{b}) = \vec{b} \cos(\theta) = \vec{b} \cdot \frac{\vec{a}}{ \vec{a} }$ $\text{proj}_{\vec{a}}(\vec{b}) = \text{comp}_{\vec{a}}(\vec{b}) \frac{\vec{a}}{ \vec{a} } = \left(\vec{b} \cdot \frac{\vec{a}}{ \vec{a} } \right) \frac{\vec{a}}{ \vec{a} }$