

S.1 Inner Product Spaces

• Recall that for $z = x+iy \in \mathbb{C}$, $\bar{z} = x-iy$ and $|z|^2 = \bar{z}z = x^2+y^2$.

• For $\vec{z} = \begin{pmatrix} z_1 \\ \vdots \\ z_n \end{pmatrix}, \vec{w} = \begin{pmatrix} w_1 \\ \vdots \\ w_n \end{pmatrix} \in \mathbb{C}^n$ we define the inner product of \vec{z} and \vec{w} by

$$\langle \vec{z}, \vec{w} \rangle := \sum_{i=1}^n \bar{w}_i z_i$$

• For $\vec{z} = \begin{pmatrix} z_1 \\ \vdots \\ z_n \end{pmatrix} \in \mathbb{C}^n$ we define the norm of \vec{z} by

$$\|\vec{z}\| = \langle \vec{z}, \vec{z} \rangle^{1/2} = \left(\sum_{i=1}^n \bar{z}_i z_i \right)^{1/2} = \left(\sum_{i=1}^n |z_i|^2 \right)^{1/2}$$

Ex Let $\vec{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in \mathbb{R}^2$. Then

$$\|\vec{x}\| = \sqrt{|x_1|^2 + |x_2|^2} = \underbrace{\sqrt{x_1^2 + x_2^2}}_{\text{length of vector}}$$



Def For $A \in M_{m \times n}(\mathbb{C})$, the adjoint of A is the matrix $A^* \in M_{n \times m}(\mathbb{C})$ with entries $(A^*)_{ij} = \overline{(A)_{ji}}$.

• For $\vec{w} = \begin{pmatrix} w_1 \\ \vdots \\ w_m \end{pmatrix} \in \mathbb{C}^m$, if we think of $\vec{w} \in M_{m \times 1}(\mathbb{C})$, then

$$\vec{w}^* = (\bar{w}_1, \dots, \bar{w}_m) \in M_{1 \times m}(\mathbb{C})$$

and for $\vec{z} \in \mathbb{C}^n$

$$\langle \vec{z}, \vec{w} \rangle = \bar{w}_1 z_1 + \dots + \bar{w}_m z_m = \vec{w}^* \vec{z} \quad \text{matrix multiplication.}$$

Rem Note that the inner product satisfies the following properties

$$① \langle \vec{w}, \vec{z} \rangle = \overline{\langle \vec{z}, \vec{w} \rangle}$$

$$② \langle \alpha \vec{z}_1 + \beta \vec{z}_2, \vec{w} \rangle = \alpha \langle \vec{z}_1, \vec{w} \rangle + \beta \langle \vec{z}_2, \vec{w} \rangle \text{ for all } \alpha, \beta \in \mathbb{C}$$

$$③ \langle \vec{z}, \vec{z} \rangle = \|\vec{z}\|^2 \geq 0$$

$$④ \langle \vec{z}, \vec{z} \rangle = 0 \Rightarrow \vec{z} = \vec{0}.$$

Def Let V be vector space. A inner product on V is a map that assigns to each pair of vectors $\vec{v}, \vec{w} \in V$ a scalar denoted $\langle \vec{v}, \vec{w} \rangle$ with the following properties:

$$① \text{Conjugate symmetry: } \langle \vec{w}, \vec{v} \rangle = \overline{\langle \vec{v}, \vec{w} \rangle} \text{ for all } \vec{v}, \vec{w} \in V.$$

(If $\mathbb{F} = \mathbb{R}$, then this replaced with symmetry: $\langle \vec{w}, \vec{v} \rangle = \langle \vec{v}, \vec{w} \rangle$ for all $\vec{v}, \vec{w} \in V$.)

$$② \text{Linearity: } \langle \alpha \vec{u} + \beta \vec{v}, \vec{w} \rangle = \alpha \langle \vec{u}, \vec{w} \rangle + \beta \langle \vec{v}, \vec{w} \rangle \text{ for scalars } \alpha, \beta \text{ and all } \vec{u}, \vec{v}, \vec{w} \in V.$$

$$③ \text{Non-negativity: } \langle \vec{v}, \vec{v} \rangle \geq 0 \text{ for all } \vec{v} \in V.$$

$$④ \text{Non-degeneracy: } \langle \vec{v}, \vec{v} \rangle = 0 \text{ if and only if } \vec{v} = \vec{0}.$$

We call V together with the map $\langle \cdot, \cdot \rangle$ an inner product space. For each $\vec{v} \in V$, the norm of \vec{v} is the quantity:

$$\|\vec{v}\| = \sqrt{\langle \vec{v}, \vec{v} \rangle}.$$

Ex 1 \mathbb{C}^n (and \mathbb{R}^n) is an inner product space with inner product

$$\langle \vec{z}, \vec{w} \rangle = \sum_{i=1}^n \bar{w}_i z_i.$$

2 Define

$$l^2(\mathbb{N}) = \left\{ (a_n)_{n \in \mathbb{N}} : a_n \in \mathbb{C}, \sum_{n=1}^{\infty} |a_n|^2 < \infty \right\}$$

Then this is a vector space with operations

$$(a_n)_{n \in \mathbb{N}} + (b_n)_{n \in \mathbb{N}} = (a_n + b_n)_{n \in \mathbb{N}}$$

$$\alpha (a_n)_{n \in \mathbb{N}} = (\alpha a_n)_{n \in \mathbb{N}}$$

Moreover, it has an inner product:

$$\langle (a_n)_{n \in \mathbb{N}}, (b_n)_{n \in \mathbb{N}} \rangle_2 := \sum_{n=1}^{\infty} \bar{b}_n a_n,$$

but one has to justify why the series on the right converges. Note that

$$\|(a_n)_{n \in \mathbb{N}}\|_2 = \left(\sum_{n=1}^{\infty} |a_n|^2 \right)^{1/2}.$$

3 Let $C[0,1]$ be the vector space of cts functions $f: [0,1] \rightarrow \mathbb{F}$ with operations

$$(f+g)(t) = f(t) + g(t)$$

$$(\alpha f)(t) = \alpha f(t)$$

This is an inner product space with inner product:

$$\langle f, g \rangle_2 := \int_0^1 f(t) \overline{g(t)} dt.$$

Note that for each $n \in \mathbb{N}$, $P_n \subseteq C[0,1]$.

4 M_{mn} can be made into an inner product space:

$$\langle A, B \rangle_2 := \text{Tr}(B^T A) = \sum_{i=1}^n \sum_{j=1}^m \bar{B}_{ij} A_{ij}$$

Note that

$$\|A\|_2 = \left(\sum_{i=1}^n \sum_{j=1}^m |A_{ij}|^2 \right)^{1/2}.$$

Properties of Inner Product Spaces

Fix an inner product space $(V, \langle \cdot, \cdot \rangle)$. Note that **1** and **2** imply:

$$\begin{aligned} \langle \vec{u}, \alpha \vec{v} + \beta \vec{w} \rangle &= \overline{\langle \alpha \vec{v} + \beta \vec{w}, \vec{u} \rangle} = \overline{\alpha \langle \vec{v}, \vec{u} \rangle + \beta \langle \vec{w}, \vec{u} \rangle} \\ &= \bar{\alpha} \langle \vec{v}, \vec{u} \rangle + \bar{\beta} \langle \vec{w}, \vec{u} \rangle = \bar{\alpha} \langle \vec{u}, \vec{v} \rangle + \bar{\beta} \langle \vec{u}, \vec{w} \rangle. \end{aligned}$$

Thus the inner product is conjugate linear in the second coordinate.

$$\text{2'} \quad \langle \vec{u}, \alpha \vec{v} + \beta \vec{w} \rangle = \bar{\alpha} \langle \vec{u}, \vec{v} \rangle + \bar{\beta} \langle \vec{u}, \vec{w} \rangle$$

2 also implies (Exercise)

$$\text{*} \quad \langle \vec{v}, \vec{0} \rangle = \langle \vec{0}, \vec{v} \rangle = 0 \quad \forall \vec{v} \in V.$$

Lemma For $\vec{v} \in V$, $\vec{v} = \vec{0}$ if and only if

$$\langle \vec{v}, \vec{w} \rangle = 0 \quad \forall \vec{w} \in V.$$

Proof (\Rightarrow) This follows from (*).

(\Leftarrow) Note $\|\vec{v}\| = (\langle \vec{v}, \vec{v} \rangle)^{1/2} = 0$. So $\vec{v} = \vec{0}$ by **1**

[Cor] For $\vec{x}, \vec{y} \in V$, $\vec{x} = \vec{y}$ if and only if

$$\langle \vec{x}, \vec{w} \rangle = \langle \vec{y}, \vec{w} \rangle \quad \forall \vec{w} \in V.$$

Moreover, if $A, B: U \rightarrow V$ are linear transformations, then $A = B$ if and only if

$$\langle A\vec{u}, \vec{w} \rangle = \langle B\vec{u}, \vec{w} \rangle \quad \forall \vec{u} \in U, \vec{w} \in W.$$

Proof For the first statement, apply the previous lemma to $\vec{v} := \vec{x} - \vec{y}$ and use linearity. For the second statement, the only if direction (\Rightarrow) is obvious. For the other direction, fix $\vec{u} \in U$. Then the first statement implies $A\vec{u} = B\vec{u}$. Since $\vec{u} \in U$ was arbitrary, we have $A = B$. \square

[Thm] (Cauchy-Schwarz Inequality)

Let V be an inner product space. Then for any $\vec{x}, \vec{y} \in V$

$$|\langle \vec{x}, \vec{y} \rangle| \leq \|\vec{x}\| \|\vec{y}\|.$$

Proof Let $t \in \mathbb{C}$ and consider

$$\begin{aligned} 0 &\leq \|\vec{x} - t\vec{y}\|^2 = \langle \vec{x} - t\vec{y}, \vec{x} - t\vec{y} \rangle \\ &= \langle \vec{x}, \vec{x} - t\vec{y} \rangle - t \langle \vec{y}, \vec{x} - t\vec{y} \rangle \\ &= \langle \vec{x}, \vec{x} \rangle - \bar{t} \langle \vec{x}, \vec{y} \rangle - t \langle \vec{y}, \vec{x} \rangle + |t|^2 \langle \vec{y}, \vec{y} \rangle \\ &\stackrel{\textcircled{1}}{=} \|\vec{x}\|^2 - \bar{t} \langle \vec{x}, \vec{y} \rangle - t \overline{\langle \vec{x}, \vec{y} \rangle} + |t|^2 \|\vec{y}\|^2. \end{aligned}$$

Set $t := \frac{\langle \vec{x}, \vec{y} \rangle}{\|\vec{y}\|^2}$. Then the above becomes

$$\begin{aligned} 0 &\leq \dots \stackrel{\textcircled{1}}{=} \|\vec{x}\|^2 - \frac{|\langle \vec{x}, \vec{y} \rangle|^2}{\|\vec{y}\|^2} - \frac{|\langle \vec{x}, \vec{y} \rangle|^2}{\|\vec{y}\|^2} + \frac{|\langle \vec{x}, \vec{y} \rangle|^2}{\|\vec{y}\|^2} \cdot \|\vec{y}\|^2 \\ &= \|\vec{x}\|^2 - \frac{|\langle \vec{x}, \vec{y} \rangle|^2}{\|\vec{y}\|^2} \end{aligned}$$

Thus

$$\frac{|\langle \vec{x}, \vec{y} \rangle|^2}{\|\vec{y}\|^2} \leq \|\vec{x}\|^2 \implies |\langle \vec{x}, \vec{y} \rangle|^2 \leq \|\vec{x}\|^2 \cdot \|\vec{y}\|^2. \quad \square$$

[Ex] For $V = \mathbb{R}^2$, you might recall

$$\langle \vec{v}, \vec{w} \rangle = \cos \theta \|\vec{v}\| \cdot \|\vec{w}\|$$

where θ is the angle between \vec{v} and \vec{w} . Since $-1 \leq \cos \theta \leq 1$, we have $|\cos \theta| \leq 1$, so the above formula implies the Cauchy-Schwarz inequality:

$$|\langle \vec{v}, \vec{w} \rangle| = |\cos \theta| \cdot \|\vec{v}\| \cdot \|\vec{w}\| \leq \|\vec{v}\| \|\vec{w}\|. \quad \square$$

[Thm] Let V be an inner product space, and let $\vec{x}, \vec{y} \in V$.

① (Triangle Inequality) $\|\vec{x} + \vec{y}\| \leq \|\vec{x}\| + \|\vec{y}\|$.

② (Polarization Identity)

$$\langle \vec{x}, \vec{y} \rangle = \frac{1}{4} (\underbrace{\|\vec{x} + \vec{y}\|^2 - \|\vec{x} - \vec{y}\|^2}_{\text{just three if } V \text{ is real vector space}} + i\|\vec{x} + i\vec{y}\|^2 - i\|\vec{x} - i\vec{y}\|^2) = \frac{1}{4} \sum_{k=1}^3 i^k \|\vec{x} + i\vec{y}\|^2$$

③ (Parallelogram Identity)

$$\|\vec{x} + \vec{y}\|^2 + \|\vec{x} - \vec{y}\|^2 = 2(\|\vec{x}\|^2 + \|\vec{y}\|^2)$$

Proof All three parts are proven by direct computation.

① We compute

$$\begin{aligned}\|\vec{x} + \vec{y}\|^2 &= \langle \vec{x} + \vec{y}, \vec{x} + \vec{y} \rangle = \|\vec{x}\|^2 + \langle \vec{x}, \vec{y} \rangle + \overline{\langle \vec{x}, \vec{y} \rangle} + \|\vec{y}\|^2 \\ &\stackrel{= 2 \cdot \text{real part of } \langle \vec{x}, \vec{y} \rangle}{=} \|\vec{x}\|^2 + 2 |\langle \vec{x}, \vec{y} \rangle| + \|\vec{y}\|^2 \\ &\stackrel{\text{Cauchy-Schwarz}}{\leq} \|\vec{x}\|^2 + 2 \|\vec{x}\| \cdot \|\vec{y}\| + \|\vec{y}\|^2 = (\|\vec{x}\| + \|\vec{y}\|)^2\end{aligned}$$

② We first compute

$$\begin{aligned}\|\vec{x} + i\vec{y}\|^2 + \|\vec{x} + i\vec{y}\|^2 &= \|\vec{x}\|^2 + \langle \vec{x}, \vec{y} \rangle + \overline{\langle \vec{x}, \vec{y} \rangle} + \|\vec{y}\|^2 + i(\|\vec{x}\|^2 - i \langle \vec{x}, \vec{y} \rangle + i \overline{\langle \vec{x}, \vec{y} \rangle} + \|\vec{y}\|^2) \\ &= (1+i)(\|\vec{x}\|^2 + \|\vec{y}\|^2) + 2 \langle \vec{x}, \vec{y} \rangle\end{aligned}$$

Swapping $-i\vec{y}$ for $i\vec{y}$ yields

$$\|\vec{x} - i\vec{y}\|^2 + i(\|\vec{x} - i\vec{y}\|^2) = (1+i)(\|\vec{x}\|^2 + \|\vec{y}\|^2) - 2 \langle \vec{x}, \vec{y} \rangle.$$

Thus

$$\sum_{k=1}^4 (i)^k \|\vec{x} + i^k \vec{y}\|^2 = 4 \langle \vec{x}, \vec{y} \rangle.$$

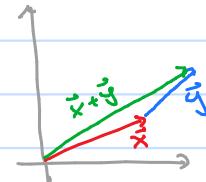
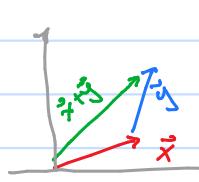
③ We compute

$$\begin{aligned}\|\vec{x} + \vec{y}\|^2 + \|\vec{x} - \vec{y}\|^2 &= \|\vec{x}\|^2 + \langle \vec{x}, \vec{y} \rangle + \overline{\langle \vec{x}, \vec{y} \rangle} + \|\vec{y}\|^2 + \|\vec{x}\|^2 - \langle \vec{x}, \vec{y} \rangle - \overline{\langle \vec{x}, \vec{y} \rangle} + \|\vec{y}\|^2 \\ &= 2(\|\vec{x}\|^2 + \|\vec{y}\|^2)\end{aligned}$$

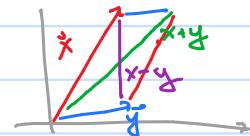
□

Ex For $V = \mathbb{R}^2$, ① says the length of $\vec{x} + \vec{y}$ is at most the length of \vec{x} plus the length of \vec{y} .

In other words, it's shorter to travel straight along $\vec{x} + \vec{y}$, rather than along \vec{x} then along \vec{y} .



② is a fact from geometry about parallelograms: the sum of the squares of the diagonals equals the sum of the squares of all four side lengths.



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Normed Vector Spaces

We have seen that all inner products give rise to norms, but these are objects that can be studied independently.

Def For a vector space V , a norm is a map from V to \mathbb{R} satisfying:

- ① (Homogeneity) $\|\alpha \vec{v}\| = |\alpha| \|\vec{v}\|$ for all scalars α and $\vec{v} \in V$.
- ② (Triangle Inequality) $\|\vec{u} + \vec{v}\| \leq \|\vec{u}\| + \|\vec{v}\|$ for all $\vec{u}, \vec{v} \in V$.
- ③ (Non-negativity) $\|\vec{v}\| \geq 0$ for all $\vec{v} \in V$
- ④ (Non-degeneracy) $\|\vec{v}\| = 0$ if and only if $\vec{v} = \vec{0}$.

We call V along with the map $\|\cdot\|$ a normed vector space.

• Clearly every inner product space is a normed vector space, but the converse is not true.

Ex. Fix $1 \leq p < \infty$. The following norms come from inner products iff $p=2$.

① For $\vec{x} = (x_1, \dots, x_n)^T \in \mathbb{F}^n$ define

$$\|\vec{x}\|_p := \left(\sum_{i=1}^n |x_i|^p \right)^{1/p} \quad \text{to ensure homogeneity}$$

② Define

$$\ell^p(\mathbb{N}) := \{ (a_n)_{n \in \mathbb{N}} : a_n \in \mathbb{C}, \sum_{n=1}^{\infty} |a_n|^p < \infty \}$$

with

$$\|(a_n)_{n \in \mathbb{N}}\|_p := \left(\sum_{n=1}^{\infty} |a_n|^p \right)^{1/p}$$

③ For $f \in C[0,1]$ define

$$\|f\|_p := \left(\int_0^1 |f(t)|^p dt \right)^{1/p}$$

④ For $A \in M_{m \times n}$ define

$$\|A\|_p := \text{Tr}((A^* A)^{p/2})^{1/p}$$

One can also make sense of $p=\infty$ for each of the above. For example

$$\|\vec{x}\|_\infty = \max_{1 \leq i \leq n} |x_i| \quad \text{and} \quad \|f\|_\infty = \max_{0 \leq t \leq 1} |f(t)|.$$

One way to tell if a norm comes from an inner product is the following theorem.

Thm Let V be a normed vector space with norm $\|\cdot\|$. Then the norm comes from an inner product if and only if it satisfies the parallelogram identity:

$$\|\vec{x} + \vec{y}\|^2 + \|\vec{x} - \vec{y}\|^2 = 2(\|\vec{x}\|^2 + \|\vec{y}\|^2) \quad \forall \vec{x}, \vec{y} \in V.$$

Proof (\Rightarrow) This is ③ from the previous theorem.

(\Leftarrow) Homework 10. □

5.2 Orthogonality

Def In an inner product space V , we say $\vec{v}, \vec{w} \in V$ are orthogonal if $\langle \vec{v}, \vec{w} \rangle = 0$, in which case we write $\vec{v} \perp \vec{w}$.

Ex ① In \mathbb{R}^3 ,

$$\langle \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \rangle = 1 \cdot 0 + 0 \cdot 0 + 0 \cdot 0 = 0$$

In particular $\vec{e}_1 \perp \vec{e}_2$ and $\vec{e}_1 \perp \vec{e}_3$

② For the std. basis $\vec{e}_1, \dots, \vec{e}_n \in \mathbb{R}^n$, $\vec{e}_i \perp \vec{e}_j$ whenever $i \neq j$.

③ $C[-1, 1]$ has inner product

$$\langle f, g \rangle_2 = \int_{-1}^1 f(t) \overline{g(t)} dt$$

Let $f(t) = t^n$, $g(t) = t^{2m+1}$. Then

$$\langle f, g \rangle_2 = \int_{-1}^1 t^n \overline{t^{2m+1}} dt = \int_{-1}^1 t^{2(n-m)+1} dt = 0$$

so $f \perp g$. □

• Observe that $\vec{v} \perp \vec{v} \iff \langle \vec{v}, \vec{v} \rangle = 0 \iff \vec{v} = \vec{0}$.

• If $\vec{v} \perp \vec{w}$ then

$$\|\vec{v} + \vec{w}\|^2 = \|\vec{v}\|^2 + \|\vec{w}\|^2 \quad (\text{Pythagorean Identity})$$

Indeed:

$$\|\vec{v} + \vec{w}\|^2 = \langle \vec{v} + \vec{w}, \vec{v} + \vec{w} \rangle = \|\vec{v}\|^2 + \langle \vec{v}, \vec{w} \rangle + \langle \vec{w}, \vec{v} \rangle + \|\vec{w}\|^2 = \|\vec{v}\|^2 + \|\vec{w}\|^2.$$

Def Let V be an inner product space. We say $\vec{v} \in V$ is orthogonal to a subspace $E \subset V$ if $\vec{v} \perp \vec{w}$ for all $\vec{w} \in E$. We write $\vec{v} \perp E$.

We say two subspaces $E, F \subset V$ are orthogonal if $\vec{v} \perp \vec{w}$ for all $\vec{v} \in E$ and $\vec{w} \in F$.

Ex Let $A \in M_{m \times n}(\mathbb{C})$. Then $\text{Ker}(A) \perp \text{Row}(A^*)$. Indeed, let $\vec{v} \in \text{Ker}(A)$ and $\vec{w} \in \text{Row}(A^*)$. Then $\vec{w} = A^* \vec{u}$ for some $\vec{u} \in \mathbb{C}^m$. Now

$$\langle \vec{v}, \vec{w} \rangle = \vec{w}^* \vec{v} = (A^* \vec{u})^* \vec{v} = (\vec{u}^* A) \vec{v} = \vec{u}^* (A \vec{v}) = \vec{u}^* \vec{0} = 0.$$

Thus $\vec{v} \perp \vec{w}$. □

Lemma Let $\vec{v}_1, \dots, \vec{v}_r \in V$ and let $E = \text{span}\{\vec{v}_1, \dots, \vec{v}_r\}$. Then for $\vec{v} \in V$, we have $\vec{v} \perp E$ if and only if $\vec{v} \perp \vec{v}_k$ for each $k = 1, \dots, r$.

Proof (\Rightarrow) Since $\vec{v}_1, \dots, \vec{v}_r \in E$, this follows by definition of $\vec{v} \perp E$.

(\Leftarrow) Suppose $\vec{v} \perp \vec{v}_k$ for each $k = 1, \dots, r$. Let $\vec{w} \in E$, then

$$\vec{w} = d_1 \vec{v}_1 + \dots + d_r \vec{v}_r$$

for some scalars d_1, \dots, d_r . We have

$$\langle \vec{v}, \vec{w} \rangle = \langle \vec{v}, \alpha_1 \vec{v}_1 + \dots + \alpha_r \vec{v}_r \rangle = \bar{\alpha}_1 \langle \vec{v}, \vec{v}_1 \rangle + \dots + \bar{\alpha}_r \langle \vec{v}, \vec{v}_r \rangle = 0$$

so $\vec{v} \perp \vec{w}$, and since $\vec{w} \in E$ was arbitrary we have $\vec{v} \perp E$. □

Def In an inner product space V , a system $\vec{v}_1, \dots, \vec{v}_n \in V$ is called orthogonal if $\vec{v}_i \perp \vec{v}_j$ whenever $i \neq j$. The system is said to be orthonormal if it is orthogonal and $\|\vec{v}_i\| = 1$ for each $i=1, \dots, n$.

Ex In \mathbb{R}^n , $\vec{e}_1, \dots, \vec{e}_n$ is orthonormal.

Lemma (Generalized Pythagorean Identity) Let $\vec{v}_1, \dots, \vec{v}_n$ be an orthogonal system. Then 11/21

$$\left\| \alpha_1 \vec{v}_1 + \dots + \alpha_n \vec{v}_n \right\|^2 = |\alpha_1|^2 \|\vec{v}_1\|^2 + \dots + |\alpha_n|^2 \|\vec{v}_n\|^2$$

for any scalars $\alpha_1, \dots, \alpha_n$.

Proof We compute

$$\begin{aligned} \left\| \sum_{j=1}^n \alpha_j \vec{v}_j \right\|^2 &= \left\langle \sum_{j=1}^n \alpha_j \vec{v}_j, \sum_{k=1}^n \alpha_k \vec{v}_k \right\rangle \\ &= \sum_{j=1}^n \sum_{k=1}^n \alpha_j \bar{\alpha}_k \langle \vec{v}_j, \vec{v}_k \rangle \\ &= \sum_{j=1}^n |\alpha_j|^2 \|\vec{v}_j\|^2 = \sum_{j=1}^n |\alpha_j|^2 \|\vec{v}_j\|^2. \end{aligned}$$
□

Cor Any orthogonal system $\vec{v}_1, \dots, \vec{v}_n$ of non-zero vectors is linearly independent.

Proof Suppose

$$\alpha_1 \vec{v}_1 + \dots + \alpha_n \vec{v}_n = \vec{0}$$

for some scalars $\alpha_1, \dots, \alpha_n$. Then using the lemma we have

$$0 = \|\vec{0}\|^2 = \|\alpha_1 \vec{v}_1 + \dots + \alpha_n \vec{v}_n\|^2 = |\alpha_1|^2 \|\vec{v}_1\|^2 + \dots + |\alpha_n|^2 \|\vec{v}_n\|^2$$

Note $\|\vec{v}_j\| \neq 0$ since $\vec{v}_j \neq \vec{0}$ for each $j=1, \dots, n$. So the only way the sum of non-negative numbers on the right equals zero is if $|\alpha_1|^2 = \dots = |\alpha_n|^2 = 0 \Rightarrow \alpha_1 = \dots = \alpha_n = 0$.

Thus $\vec{v}_1, \dots, \vec{v}_n$ are linearly independent. □

Ex In $C[-1, 1]$, consider

$$f_n(t) := e^{int} \quad n \in \mathbb{Z}$$

We claim $f_n \perp f_m$ for $n \neq m$. **Fact** $e^{ix} = \cos(x) + i \sin(x)$ for $x \in \mathbb{R}$. Thus

$$\begin{aligned} \langle f_n, f_m \rangle_2 &= \int_{-1}^1 f_n(t) \overline{f_m(t)} dt = \int_{-1}^1 e^{int} e^{-imt} dt = \int_{-1}^1 e^{i\pi(n-m)t} dt \\ &= \int_{-1}^1 \cos(\pi(n-m)t) + i \sin(\pi(n-m)t) dt \\ &\stackrel{n-m \neq 0}{=} \left[\frac{\sin(\pi(n-m)t)}{\pi(n-m)} - i \frac{\cos(\pi(n-m)t)}{\pi(n-m)} \right]_{-1}^1 = 0 \end{aligned}$$

Exercise: Compute $\langle f_n, f_n \rangle_2$.

Thus for any $N \in \mathbb{N}$, $f_{-N}, f_{-(N-1)}, \dots, f_{-1}, f_0, f_1, \dots, f_N$ is an orthogonal system, and so by

the lemma it is linearly independent. Since we can increase N to however large we want, it follows that $C[-1,1]$ is infinite dimensional.

Fact "Fourier Analysis" says $\{f_n : n \in \mathbb{Z}\}$ is generating for $C([-1,1])$ (in a certain sense). \square

Orthonormal Bases

Def An orthogonal (resp. orthonormal) basis is an orthogonal (resp. orthonormal) system that is also a basis (i.e. generating).

• Recall that given an arbitrary basis B for V , computing coordinate vectors can be hard. E.g. for $\vec{x} \in \mathbb{R}^n$

$$[\vec{x}]_B = [I]_S^B [\vec{x}]_S = ([I]_S^S)^{-1} \vec{x}$$

What makes orthogonal basis nice is that these are much easier to find.

Prop Let V be an inner product space, and let $B = \{\vec{v}_1, \dots, \vec{v}_n\}$ be an orthogonal basis. Then for any $\vec{x} \in V$,

$$[\vec{x}]_B = (\alpha_1, \dots, \alpha_n)^T$$

where

$$\alpha_k = \frac{\langle \vec{x}, \vec{v}_k \rangle}{\|\vec{v}_k\|^2} \quad k=1, \dots, n.$$

Proof Since B is a basis we know

$$\vec{x} = \alpha_1 \vec{v}_1 + \dots + \alpha_n \vec{v}_n$$

for some scalars $\alpha_1, \dots, \alpha_n$. We must show these scalars are as in (*). For $1 \leq k \leq n$, we have

$$\langle \vec{x}, \vec{v}_k \rangle = \left\langle \sum_{j=1}^n \alpha_j \vec{v}_j, \vec{v}_k \right\rangle = \sum_{j=1}^n \alpha_j \langle \vec{v}_j, \vec{v}_k \rangle = \alpha_k \langle \vec{v}_k, \vec{v}_k \rangle = \alpha_k \|\vec{v}_k\|^2.$$

Solving for α_k yields (*). \square

• Note that this proposition implies

$$\vec{x} = \sum_{k=1}^n \frac{\langle \vec{x}, \vec{v}_k \rangle}{\|\vec{v}_k\|^2} \vec{v}_k$$

for all $\vec{x} \in V$. If we further assume that $\vec{v}_1, \dots, \vec{v}_n$ is orthonormal, then this simplifies to

$$\vec{x} = \sum_{k=1}^n \langle \vec{x}, \vec{v}_k \rangle \vec{v}_k.$$

5.3 Orthogonal projections and Gram-Schmidt orthogonalization

Def Let V be an inner product space and let $E \subset V$ be a subspace. An orthogonal projection onto E is a linear transformation $P_E : V \rightarrow V$ satisfying

- ① $P_E(\vec{v}) \in E$ for all $\vec{v} \in V$.
- ② $(\vec{v} - P_E(\vec{v})) \perp E$ for all $\vec{v} \in V$.

Ex Let $E = \text{span}\{\vec{e}_2, \vec{e}_3\} \subseteq \mathbb{R}^3$. Then $P_E\left(\begin{pmatrix} x \\ y \\ z \end{pmatrix}\right) = \begin{pmatrix} 0 \\ y \\ z \end{pmatrix}$. Indeed, it clearly satisfies ① and

$$\left(\begin{pmatrix} x \\ y \\ z \end{pmatrix} - \begin{pmatrix} 0 \\ y \\ z \end{pmatrix}\right) = \begin{pmatrix} x \\ 0 \\ 0 \end{pmatrix} = x\vec{e}_1 \perp E.$$
□

Prop Let V be an inner product space and let E be a subspace. Suppose $\vec{v}_1, \dots, \vec{v}_n$ is an orthogonal basis for E . Then the orthogonal projection onto E is given by

$$P_E(\vec{v}) = \sum_{k=1}^n \frac{\langle \vec{v}, \vec{v}_k \rangle}{\|\vec{v}_k\|^2} \vec{v}_k.$$

Proof First note that P_E is linear by the linearity of the inner product. Also,

$$P_E(\vec{v}) \in \text{span}\{\vec{v}_1, \dots, \vec{v}_n\} = E$$

so P_E satisfies ①. So it remains to check ②. By the FNT Lemma in Section 5.2, it suffices to show $(\vec{v} - P_E(\vec{v})) \perp \vec{v}_k$ for each $k=1, \dots, n$. We have

$$\begin{aligned} \langle \vec{v} - P_E(\vec{v}), \vec{v}_k \rangle &= \langle \vec{v}, \vec{v}_k \rangle - \langle P_E(\vec{v}), \vec{v}_k \rangle \\ &= \langle \vec{v}, \vec{v}_k \rangle - \left\langle \sum_{j=1}^n \frac{\langle \vec{v}, \vec{v}_j \rangle}{\|\vec{v}_j\|^2} \vec{v}_j, \vec{v}_k \right\rangle \\ &= \langle \vec{v}, \vec{v}_k \rangle - \sum_{j=1}^n \frac{\langle \vec{v}, \vec{v}_j \rangle}{\|\vec{v}_j\|^2} \langle \vec{v}_j, \vec{v}_k \rangle \\ &= \langle \vec{v}, \vec{v}_k \rangle - \frac{\langle \vec{v}, \vec{v}_k \rangle}{\|\vec{v}_k\|^2} \langle \vec{v}_k, \vec{v}_k \rangle \\ &= \langle \vec{v}, \vec{v}_k \rangle - \langle \vec{v}, \vec{v}_k \rangle = 0. \end{aligned}$$
□

Ex Recall that in \mathbb{C}^n , $\langle \vec{x}, \vec{y} \rangle = \vec{y}^* \vec{x}$. Thus for a subspace $E \subset \mathbb{C}^n$ with orthogonal basis $\vec{v}_1, \dots, \vec{v}_n$ the Proposition says:

$$P_E(\vec{x}) = \sum_{k=1}^n \frac{1}{\|\vec{v}_k\|^2} (\vec{v}_k^* \vec{x}) \vec{v}_k = \sum_{k=1}^n \frac{1}{\|\vec{v}_k\|^2} \vec{v}_k (\vec{v}_k^* \vec{x})$$

Observe that $\vec{v}_k \vec{v}_k^* \in M_{n \times n} \cdot M_{n \times n} = M_{n \times n}$. It follows that

$$[P_E] = \sum_{k=1}^n \frac{1}{\|\vec{v}_k\|^2} \vec{v}_k \vec{v}_k^* \in M_{n \times n}.$$
□

Thm Let V be an inner product space and let P_E be an orthogonal projection onto a subspace E . Then for all $\vec{v} \in V$ and all $\vec{x} \in E$

$$\|\vec{v} - P_E(\vec{v})\| \leq \|\vec{v} - \vec{x}\|$$

That is, $P_E(\vec{v})$ minimizes the distance from \vec{v} to E . Moreover, if for some $\vec{x} \in E$

$$\|\vec{v} - P_E(\vec{v})\| = \|\vec{v} - \vec{x}\|$$

Then $P_E(\vec{v}) = \vec{x}$. Consequently, any orthogonal projection onto E is unique.

Proof For $\vec{v} \in V$ and $\vec{x} \in E$, note that

$$\vec{v} - \vec{x} = \underbrace{\vec{v} - P_E(\vec{v})}_{\perp E} + \underbrace{P_E(\vec{v}) - \vec{x}}_{\in E}$$

so by the Pythagorean theorem

$$\begin{aligned} \|\vec{v} - \vec{x}\|^2 &= \|(\vec{v} - P_E(\vec{v})) + (P_E(\vec{v}) - \vec{x})\|^2 \\ &= \|\vec{v} - P_E(\vec{v})\|^2 + \|P_E(\vec{v}) - \vec{x}\|^2 \geq \|\vec{v} - P_E(\vec{v})\|^2 \end{aligned}$$

which proves the first part. Note that $\|\vec{v} - \vec{x}\| = \|\vec{v} - P_E(\vec{v})\|$ is only possible if

$$\|P_E(\vec{v}) - \vec{x}\| = 0 \iff P_E(\vec{v}) - \vec{x} = \vec{0} \iff P_E(\vec{v}) = \vec{x}.$$

Finally, let P'_E be another orthogonal projection onto E . Then by the first part of the theorem

$$\|\vec{v} - P_E(\vec{v})\| \leq \|\vec{v} - P'_E(\vec{v})\|$$

and reversing the roles of P_E and P'_E we get $\|\vec{v} - P_E(\vec{v})\| = \|\vec{v} - P'_E(\vec{v})\|$. So by the second part of the theorem we have $P_E(\vec{v}) = P'_E(\vec{v})$. Since $\vec{v} \in V$ was arbitrary, this implies $P_E = P'_E$. □

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Gram-Schmidt Orthogonalization Algorithm

From the first proposition in this section, we see that we can always define P_E provided E has an orthogonal basis. In this subsection we show this is always the case.

The following algorithm takes in a linearly independent system $\vec{x}_1, \dots, \vec{x}_n$ and constructs an orthogonal system $\vec{v}_1, \dots, \vec{v}_n$ s.t.

$$\text{span}\{\vec{x}_1, \dots, \vec{x}_n\} = \text{span}\{\vec{v}_1, \dots, \vec{v}_n\}$$

Moreover, for each $r \leq n$ it satisfies

$$\text{span}\{\vec{x}_1, \dots, \vec{x}_r\} = \text{span}\{\vec{v}_1, \dots, \vec{v}_r\}$$

Step 1 Set $\vec{v}_1 := \vec{x}_1$ and denote $E_1 := \text{span}\{\vec{x}_1\} = \text{span}\{\vec{v}_1\}$

Step 2 Set

$$\vec{v}_2 := \vec{x}_2 - P_{E_1} \vec{x}_2 = \vec{x}_2 - \frac{\langle \vec{x}_2, \vec{v}_1 \rangle}{\|\vec{v}_1\|^2} \vec{v}_1$$

Note that $\vec{v}_2 \perp E_1$ by definition of P_{E_1} . In particular, $\vec{v}_2 \perp \vec{v}_1$.

Denote $E_2 := \text{span}\{\vec{v}_1, \vec{v}_2\} = \text{span}\{\vec{x}_1, \vec{x}_2\}$

Step 3 Set

$$\vec{v}_3 := \vec{x}_3 - P_{E_2} \vec{x}_3 = \vec{x}_3 - \frac{\langle \vec{x}_3, \vec{v}_1 \rangle}{\|\vec{v}_1\|^2} \vec{v}_1 - \frac{\langle \vec{x}_3, \vec{v}_2 \rangle}{\|\vec{v}_2\|^2} \vec{v}_2$$

Then $\vec{v}_3 \perp E_2$ and in particular $\vec{v}_3 \perp \vec{v}_1, \vec{v}_3 \perp \vec{v}_2$. Note that $\vec{x}_3 \notin E_2$ since $E_2 = \text{span}\{\vec{x}_1, \vec{x}_2\}$ and $\vec{x}_1, \vec{x}_2, \vec{x}_3$ are lin. indep. Thus $\vec{v}_3 \neq \vec{0}$.

⋮

Step r+1 Suppose we have already iterated the above process r times to construct an orthogonal system $\vec{v}_1, \dots, \vec{v}_r$ (of non-zero vectors) such that

$$E_r := \text{span}\{\vec{v}_1, \dots, \vec{v}_r\} = \text{span}\{\vec{x}_1, \dots, \vec{x}_r\}$$

Define

$$\vec{v}_{r+1} := \vec{x}_{r+1} - P_{E_r} \vec{x}_{r+1} = \vec{x}_{r+1} - \sum_{k=1}^r \frac{\langle \vec{x}_{r+1}, \vec{v}_k \rangle}{\|\vec{v}_k\|^2} \vec{v}_k$$

Then $\vec{v}_{r+1} \perp E_r$ and therefore $\vec{v}_{r+1} \perp \vec{v}_k$ for $k=1, \dots, r$. Also, since $\vec{x}_{r+1} \notin E_r$ by lin. indep. of $\vec{x}_1, \dots, \vec{x}_r, \vec{x}_{r+1}$, we have $\vec{v}_{r+1} \neq \vec{0}$.

Iterating this process n times yields the desired orthogonal system $\vec{v}_1, \dots, \vec{v}_n$. \square

Ex In \mathbb{R}^3

$$\vec{x}_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad \vec{x}_2 = \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} \quad \vec{x}_3 = \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}$$

Step 1 $\vec{v}_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$.

$$\text{Step 2 } \vec{v}_2 = \vec{x}_2 - \frac{\langle \vec{x}_2, \vec{v}_1 \rangle}{\|\vec{v}_1\|^2} \vec{v}_1 = \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} - \frac{0+1+2}{3} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} - \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

$$\begin{aligned} \text{Step 3 } \vec{v}_3 &= \vec{x}_3 - \frac{\langle \vec{x}_3, \vec{v}_1 \rangle}{\|\vec{v}_1\|^2} \vec{v}_1 - \frac{\langle \vec{x}_3, \vec{v}_2 \rangle}{\|\vec{v}_2\|^2} \vec{v}_2 = \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} - \frac{1+0+2}{3} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} - \frac{-1+0+2}{2} \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \\ &= \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} - \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} - \begin{pmatrix} -1/2 \\ 0 \\ 1/2 \end{pmatrix} = \begin{pmatrix} 1/2 \\ -1 \\ 1/2 \end{pmatrix} \end{aligned}$$

So

$$\vec{v}_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad \vec{v}_2 = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \quad \vec{v}_3 = \begin{pmatrix} 1/2 \\ -1 \\ 1/2 \end{pmatrix}$$

Let $E := \text{span}\{\vec{x}_1, \vec{x}_2\} = \text{span}\{\vec{v}_1, \vec{v}_2\}$. Then \vec{v}_1, \vec{v}_2 is an orthogonal basis for E and so we know the formula for P_E . Let's write out its matrix representation (with respect to the standard basis S):

$$\begin{aligned} [P_E]_S^S &= \frac{1}{\|\vec{v}_1\|^2} \vec{v}_1 \cdot \vec{v}_1^* + \frac{1}{\|\vec{v}_2\|^2} \vec{v}_2 \cdot \vec{v}_2^* = \frac{1}{3} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 1 & 1 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} -1 & 0 & 1 \end{pmatrix} \\ &= \frac{1}{3} \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 5/6 & 1/3 & -1/6 \\ 1/3 & 1/3 & 1/3 \\ -1/6 & 1/3 & 5/6 \end{pmatrix} \end{aligned}$$

Rem Note that if $\vec{u}_k := \frac{\vec{v}_k}{\|\vec{v}_k\|}$ for $k=1, \dots, n$ then $\vec{u}_1, \dots, \vec{u}_n$ is an orthonormal system which satisfies

$$\text{span}\{\vec{u}_1, \dots, \vec{u}_r\} = \text{span}\{\vec{x}_1, \dots, \vec{x}_r\} \quad r=1, \dots, n.$$

Orthogonal Complement

Def For a subset $S \subseteq V$, its orthogonal complement is the set
 $S^\perp := \{ \vec{x} \in V : \vec{x} \perp S \}$

Prop S^\perp is always a subspace (even if S is not). Also
 $(S^\perp)^\perp = \text{Span } S$

In particular, $S = (S^\perp)^\perp$ if and only if S is a subspace.

Proof Homework 11. □

Lemma Let $E \subseteq V$ be a subspace. Then $E \cap E^\perp = \{\vec{0}\}$.

Proof Let $\vec{x} \in E \cap E^\perp$ then
 $\vec{x} \in E \quad \vec{x} \in E^\perp$
 $\langle \vec{x}, \vec{x} \rangle = 0$

so $\vec{x} = \vec{0}$ by non-degeneracy. □

Theorem Let V be an inner product space and let $E \subseteq V$ be a subspace. Then for every $\vec{v} \in V$ there exists unique $\vec{v}_1 \in E$ and $\vec{v}_2 \in E^\perp$ s.t.
 $\vec{v} = \vec{v}_1 + \vec{v}_2$.

Proof Let P_E be the orthogonal projection onto E . Given $\vec{v} \in V$, set
 $\vec{v}_1 := P_E(\vec{v})$ and $\vec{v}_2 := \vec{v} - P_E(\vec{v})$. Then $\vec{v}_1 \in E$ and $\vec{v}_2 \in E^\perp$ by def. of P_E . Also
 $\vec{v}_1 + \vec{v}_2 = P_E(\vec{v}) + \vec{v} - P_E(\vec{v}) = \vec{v}$.

Suppose $\vec{w}_1 \in E$ and $\vec{w}_2 \in E^\perp$ also satisfy $\vec{w}_1 + \vec{w}_2 = \vec{v}$. Then

$$\vec{v}_1 + \vec{v}_2 = \vec{w}_1 + \vec{w}_2$$

$$\vec{v}_1 - \vec{w}_1 = \vec{w}_2 - \vec{v}_2$$

Note that $\vec{v}_1 - \vec{w}_1 \in E$ while $\vec{w}_2 - \vec{v}_2 \in E^\perp$. Thus $\vec{v}_1 - \vec{w}_1 = \vec{w}_2 - \vec{v}_2 \in E \cap E^\perp = \{\vec{0}\}$ by the lemma.

So $\vec{v}_1 - \vec{w}_1 = \vec{0} \Rightarrow \vec{v}_1 = \vec{w}_1$ and $\vec{w}_2 - \vec{v}_2 = \vec{0} \Rightarrow \vec{w}_2 = \vec{v}_2$. Hence \vec{v}_1 and \vec{v}_2 are unique. □

- Whenever $E_1, E_2 \subseteq V$ are subspaces s.t. every $\vec{v} \in V$ can be written uniquely as $\vec{v} = \vec{v}_1 + \vec{v}_2$ for $\vec{v}_1 \in E_1$ and $\vec{v}_2 \in E_2$, we write

$$V = E_1 \oplus E_2.$$

The above theorem says

$$V = E \oplus E^\perp.$$

Cor For a subspace $E \subseteq V$,

$$\dim(E) + \dim(E^\perp) = \dim(V)$$

Proof Using Gram-Schmidt, we can find orthogonal bases B and C for E and E^\perp respectively. Then $B \cup C$ is orthogonal and therefore lin. indep. The theorem tells us $B \cup C$ is generating. Hence $B \cup C$ is a basis for V . □

5.4 Method of Least Squares

- Let $A\vec{x} = \vec{b}$ be an inconsistent linear system. Since there is no solution, we cannot solve it exactly, but we can solve it approximately. That is, we can find \vec{x} s.t. $\|A\vec{x} - \vec{b}\|$ is as small as possible

Note:

$$\|A\vec{x} - \vec{b}\|^2 = \sum_{i=1}^n |(A\vec{x})_i - b_i|^2 = \sum_{i=1}^n \left| \sum_{j=1}^n (A)_{ij} x_j - b_i \right|^2$$

"least squares"

- Obviously $A\vec{x} \in \text{Ran}(A)$ for all $\vec{x} \in \mathbb{F}^n$. Let P be the orthogonal projection onto $\text{Ran}(A)$. Then by a theorem from Section 5.3 we have:

$$\|\vec{b} - P\vec{b}\| \leq \|\vec{b} - A\vec{x}\| \quad \forall \vec{x} \in \mathbb{F}^n.$$

So we want to find \vec{x} s.t. $A\vec{x} = P\vec{b}$.

Thm Let $A \in \mathbb{R}^{m \times n}$ and let P be the orthogonal projection onto $\text{Ran}(A)$. For $\vec{x} \in \mathbb{F}^n$, $A\vec{x} = P\vec{b}$ if and only if $A^*A\vec{x} = A^*\vec{b}$.

Proof Since $A\vec{x} \in \text{Ran}(A)$, $A\vec{x} = P\vec{b}$ iff $(\vec{b} - A\vec{x}) \perp \text{Ran}(A)$. Let $\vec{a}_1, \dots, \vec{a}_n$ be the columns of A . Then $\text{Ran}(A)$ (the column space of A) is generated by $\vec{a}_1, \dots, \vec{a}_n$, and so $(\vec{b} - A\vec{x}) \perp \text{Ran}(A)$ iff

$$\langle \vec{b} - A\vec{x}, \vec{a}_j \rangle = 0 \quad \text{for each } j=1, \dots, n.$$

$$\vec{a}_j^* (\vec{b} - A\vec{x}) = 0$$

iff

$$\vec{0} = \begin{pmatrix} \vec{a}_1^* (\vec{b} - A\vec{x}) \\ \vdots \\ \vec{a}_n^* (\vec{b} - A\vec{x}) \end{pmatrix} = A^* (\vec{b} - A\vec{x})$$

iff $A^*A\vec{x} = A^*\vec{b}$.

□

- Suppose we are given data points (x_i, y_i) , $i=1, \dots, n$ and want to find the line $y = ax + b$ that "best fits" our data. That means find the values a, b that minimize:

$$\sum_{i=1}^n |y_i - (ax_i + b)|^2$$

This is equivalent to applying the method of least squares to the linear system

$$\begin{pmatrix} x_1 & 1 \\ x_2 & 1 \\ \vdots & \\ x_n & 1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}$$

The theorem tells us this is equivalent to solving $A^*A\vec{x} = A^*\vec{b}$.

Ex Suppose our data set is:

$$(-2, 4), (-1, 2), (0, 1), (2, 1), (3, 1)$$

So we will find the least squares solution to

$$\begin{pmatrix} -2 & 1 \\ -1 & 1 \\ 0 & 1 \\ 2 & 1 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} 4 \\ 2 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

we have

$$A^* A = \begin{pmatrix} -2 & -1 & 0 & 2 & 3 \\ 1 & 1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -2 & 1 \\ -1 & 1 \\ 0 & 1 \\ 2 & 1 \\ 3 & 1 \end{pmatrix} = \begin{pmatrix} 18 & 2 \\ 2 & 5 \end{pmatrix}$$

and

$$A^* b = \begin{pmatrix} -2 & -1 & 0 & 2 & 3 \\ 1 & 1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 4 \\ 2 \\ 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -5 \\ 9 \end{pmatrix}$$

So we must solve:

$$\begin{pmatrix} 18 & 2 \\ 2 & 5 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} -5 \\ 9 \end{pmatrix} \Rightarrow \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} -12 \\ 2 \end{pmatrix}$$

Thus the line $y = -\frac{1}{2}x + 2$ best fits the data. □

- Note that a typical reason for a lin. sys. $A\tilde{x} = \tilde{b}$ to be inconsistent is that it is "overdetermined"; that is, it has more equations than unknowns: $m > n$ for $A \in \mathbb{R}^{m \times n}$. That is, A is tall. But then $A^* A$ is $n \times n$ and so has been compressed.
- There was not anything special about trying to fit a line to our data. If we wanted to find a parabola $y = ax^2 + bx + c$ that best fits our data, we would apply the least squares method to

$$\begin{pmatrix} x_1^2 & x_1 & 1 \\ \vdots & & \\ x_n^2 & x_n & 1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$$

Ex Using the same data as before, we have

$$\begin{pmatrix} 4 & -2 & 1 \\ 1 & -1 & 1 \\ 0 & 0 & 1 \\ 4 & 2 & 1 \\ 9 & 3 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 4 \\ 2 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

Then

$$A^* A = \begin{pmatrix} 14 & 26 & 18 \\ 26 & 18 & 2 \\ 18 & 2 & 5 \end{pmatrix} \quad \text{and} \quad A^* b = \begin{pmatrix} 31 \\ -5 \\ 1 \end{pmatrix}$$

And $A^* A \tilde{x} = A^* b$ has solution

$$\begin{pmatrix} 43/154 \\ -62/77 \\ 86/77 \end{pmatrix}$$

so that the parabola best fitting our data is $y = \frac{43}{154}x^2 + \frac{-62}{77}x + \frac{86}{77}$. □

- More generally, if we think our data should be best modeled by a curve

of the form

$$y = a_1 f_1(x) + a_2 f_2(x) + \cdots + a_n f_n(x)$$

for functions f_1, \dots, f_n , then we would apply the least squares method to

$$\begin{pmatrix} f_1(x_1) & f_2(x_1) & \cdots & f_n(x_1) \\ \vdots & \vdots & & \vdots \\ f_1(x_n) & f_2(x_n) & \cdots & f_n(x_n) \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}$$

- An issue we might run into is that A^*A need not be invertible. However, since it is square, we know it is invertible iff it has a pivot in every column iff $\text{Ker}(A^*A) = \{\vec{0}\}$.

[Thm] For $A \in \mathbb{R}^{m,n}$, $\text{Ker}(A) = \text{Ker}(A^*A)$

Proof Clearly $\text{Ker}(A) \subset \text{Ker}(A^*A)$. Now, suppose $\vec{x} \in \text{Ker}(A^*A)$. Then

$$\|A\vec{x}\|^2 = \langle A\vec{x}, A\vec{x} \rangle = \langle \vec{x}, A^*A\vec{x} \rangle = \langle \vec{x}, \vec{0} \rangle = 0$$

(where we have used an exercise on homework 12. Thus $A\vec{x} = \vec{0} \Rightarrow \vec{x} \in \text{Ker}(A)$).

It follows that $\text{Ker}(A^*A) \subset \text{Ker}(A)$ and so we have equality. □

[Cor] A^*A is invertible if and only if $\text{rank}(A) = n$.

Proof From the discussion preceding the theorem, we know A^*A is invertible iff $\text{Ker}(A^*A) = \{\vec{0}\}$. By the theorem, this is equivalent to $\text{Ker}(A) = \{\vec{0}\}$, and by rank-nullity this is in turn equivalent to $\text{rank}(A) = n$. □

[Cor] If $\text{rank}(A) = n$, then $P_{\text{rank}(A)} = A(A^*A)^{-1}A^*$.

Proof By the previous corollary, A^*A is invertible. By the first theorem in this section, for any $\vec{b} \in \mathbb{R}^m$ we have $P_{\text{rank}(A)}\vec{b} = A\vec{x}$ where \vec{x} is a solution of $A^*A\vec{x} = A^*\vec{b}$. Thus

$$\vec{x} = (A^*A)^{-1}A^*\vec{b}$$

and so

$$P_{\text{rank}(A)}\vec{b} = A\vec{x} = A(A^*A)^{-1}A^*\vec{b}.$$

Since $\vec{b} \in \mathbb{R}^m$ was arbitrary, we obtain $P_{\text{rank}(A)} = A(A^*A)^{-1}A^* \vec{b}$. □

Polar Decomposition and Singular Values

Def A self-adjoint matrix $A \in M_{n \times n}(\mathbb{C})$ is called positive semi-definite if $\langle A\vec{x}, \vec{x} \rangle \geq 0 \quad \forall \vec{x} \in \mathbb{C}^n$

In this case we write $A \geq 0$. A is called positive definite if

$$\langle A\vec{x}, \vec{x} \rangle > 0 \quad \forall \vec{x} \in \mathbb{C}^n \text{ with } \vec{x} \neq \vec{0}.$$

In this case we write $A > 0$.

Ex Let $A \in M_{n \times n}(\mathbb{C})$ (not necessarily square). Then by Homework 12 Exercise 4, for any $\vec{x} \in \mathbb{C}^n$

$$\langle A^*A\vec{x}, \vec{x} \rangle = \langle A\vec{x}, A\vec{x} \rangle = \|A\vec{x}\|^2 \geq 0.$$

Thus $A^*A \in M_{n \times n}(\mathbb{C})$ is positive semi-definite. □

Thm Let $A \in M_{n \times n}(\mathbb{C})$ be self-adjoint.

- ① A is positive semi-definite if and only if $\sigma(A) \subset [0, \infty)$
- ② A is positive definite if and only if $\sigma(A) \subset (0, \infty)$

Proof By Homework 12 Exercise 4, A is diagonalizable

$$A = U \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix} U^*$$

with U a unitary matrix.

By Homework 12 Exercise 2,

$$\langle A\vec{x}, \vec{x} \rangle = \langle UDU^*\vec{x}, \vec{x} \rangle = \langle D U^*\vec{x}, U^*\vec{x} \rangle$$

Thus A is positive (semi-)definite if and only if D is positive (semi-)definite.

For $\vec{x} = (x_1, \dots, x_n)^T \in \mathbb{C}^n$ we have

$$\langle D\vec{x}, \vec{x} \rangle = \left\langle \begin{pmatrix} \lambda_1 x_1 \\ \vdots \\ \lambda_n x_n \end{pmatrix}, \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \right\rangle = \lambda_1 x_1 \bar{x}_1 + \dots + \lambda_n x_n \bar{x}_n = \lambda_1 |x_1|^2 + \dots + \lambda_n |x_n|^2$$

This is > 0 (≥ 0) for all \vec{x} if and only if $\lambda_1, \dots, \lambda_n > 0$ (≥ 0). □

Cor If $A \in M_{n \times n}(\mathbb{C})$ is positive semi-definite then there exists a positive semi-definite matrix $\sqrt{A} \in M_{n \times n}(\mathbb{C})$ such that $A = (\sqrt{A})^2$.

Proof with U and D as in the theorem, take

$$\sqrt{A} := U \begin{pmatrix} \lambda_1^{1/2} & & \\ & \ddots & \\ 0 & & \lambda_n^{1/2} \end{pmatrix} U^*$$

(not square)

Def For $A \in M_{n \times n}(\mathbb{C})$, the absolute value of A is

$$|A| := \sqrt{A^*A} \in M_{n \times n}(\mathbb{C})$$

The eigenvalues of $|A|$ are called the singular values of A .

Rem Note that the eigenvalues of $|A| = \sqrt{A^*A}$ are the square-roots of the eigenvalues of A^*A .

• Suppose A has singular values $\sigma_1, \dots, \sigma_n$. Let $\vec{v}_1, \dots, \vec{v}_n$ be an orthonormal basis of eigenvectors for $|A|$ corresponding to eigenvalues $\sigma_1, \dots, \sigma_n$ (respectively). Observe

$$A^*A\vec{v}_i = |A|^2\vec{v}_i = |A|(|A|\vec{v}_i) = |A|(\sigma_i \vec{v}_i) = \sigma_i^2 \vec{v}_i.$$

so \vec{v}_i is an eigenvector of A^*A with eigenvalue σ_i^2 .

Lemma 1 Assume $\sigma_1, \dots, \sigma_r$ are the non-zero singular values of A for some $r \leq n$. If

$$\vec{w}_k := \frac{1}{\sigma_k} A\vec{v}_k \quad k=1, \dots, r$$

then $\vec{w}_1, \dots, \vec{w}_r$ is an orthonormal system.

Proof For $j, k = 1, \dots, r$ we have

$$\langle \vec{w}_j, \vec{w}_k \rangle = \frac{1}{\sigma_j \sigma_k} \langle A\vec{v}_j, A\vec{v}_k \rangle = \frac{1}{\sigma_j \sigma_k} \langle A^*A\vec{v}_j, \vec{v}_k \rangle = \frac{1}{\sigma_j \sigma_k} \langle \sigma_j^2 \vec{v}_j, \vec{v}_k \rangle = \frac{\sigma_j^2}{\sigma_j \sigma_k} \langle \vec{v}_j, \vec{v}_k \rangle.$$

If $j \neq k$, this is zero. Otherwise $j = k$ and we obtain $\frac{\sigma_j^2}{\sigma_j \sigma_j} \|\vec{v}_j\|^2 = 1$. □

Lemma 2 For any $\vec{x} \in \mathbb{C}^n$

$$\| |A| \vec{x} \| = \| A\vec{x} \|$$

Consequently, $\text{Ker}(|A|) = \text{Ker}(A)$

Proof we compare

$$\| |A| \vec{x} \|^2 = \langle |A| \vec{x}, |A| \vec{x} \rangle = \langle |A|^2 \vec{x}, \vec{x} \rangle = \langle A^*A \vec{x}, \vec{x} \rangle = \langle A\vec{x}, A\vec{x} \rangle = \| A\vec{x} \|^2.$$

In particular, $|A|\vec{x} = \vec{0}$ iff $\| |A|\vec{x} \| = 0$ iff $\| A\vec{x} \| = 0$ iff $A\vec{x} = \vec{0}$. □

Thm (Polar Decomposition) For a square matrix $A \in M_{n \times n}(\mathbb{C})$ there exists a unitary matrix $U \in M_{n \times n}(\mathbb{C})$ such that

$$A = U|A|$$

Proof Let $\vec{v}_1, \dots, \vec{v}_n$ be an orthonormal basis of eigenvectors of $|A|$ corresponding to eigenvalues $\sigma_1, \dots, \sigma_n$. Assume $\sigma_1, \dots, \sigma_r$ are the non-zero eigenvalues. Then $\vec{v}_{r+1}, \dots, \vec{v}_n$ is a basis for $\text{Ker}(|A|) = \text{Ker}(A)$ (by Lemma 2). By the rank-nullity theorem, since A is square

$$\dim(\text{Ker}(A^*)) = \dim(\text{Ker}(A)) = n - r$$

Let $\vec{w}_{r+1}, \dots, \vec{w}_n$ be an orthonormal basis for $\text{Ker}(A^*)$ and for $k=1, \dots, r$ let

$$\vec{w}_k := \frac{1}{\sigma_k} A\vec{v}_k.$$

Then $\vec{w}_1, \dots, \vec{w}_r$ is an orthonormal system by Lemma 1 and are orthogonal to $\text{Ker}(A^*)$ by an example from Section 5.2. Hence $\vec{w}_1, \dots, \vec{w}_r, \vec{w}_{r+1}, \dots, \vec{w}_n$ is an orthonormal basis for \mathbb{C}^n .

Define $U: \mathbb{C}^n \rightarrow \mathbb{C}^n$ by $U(\vec{v}_i) = \vec{w}_i$. Since U takes an orthonormal basis to an orthonormal basis, U is unitary (Exercise: Prove this).

It remains to show $U|A| = A$. For any $\vec{x} \in \mathbb{C}^n$ we have

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$$\vec{x} = \sum_{i=1}^r \alpha_i \vec{v}_i$$

for some scalars α_i . Recall the \vec{v}_i 's are eigenvectors of $|A|$. Thus

$$\begin{aligned} U|A|\vec{x} &= U\left(\sum_{i=1}^r \alpha_i |A|\vec{v}_i\right) = U\left(\sum_{i=1}^r \alpha_i \sigma_i \vec{v}_i\right) = U\left(\sum_{i=1}^r \alpha_i \sigma_i v_i\right) \\ &= \sum_{i=1}^r \alpha_i \sigma_i Uv_i = \sum_{i=1}^r \alpha_i \sigma_i w_i = \sum_{i=1}^r \alpha_i Av_i = A\left(\sum_{i=1}^r \alpha_i v_i\right) = A\vec{x} \end{aligned}$$

where we have used $\vec{v}_{r+1}, \dots, \vec{v}_n \in \text{Ker}(A)$ in the last equality. □

Rem Compare the above theorem to the fact that for any $z \in \mathbb{C}$, $z = e^{i\theta} |z|$ for some $\theta \in [0, 2\pi)$. Note that $\overline{e^{i\theta}} = e^{-i\theta} = (e^{i\theta})^{-1}$.