

Math 105

A Second Course in Analysis

5 Multivariable Calculus

5.1 Linear Algebra

We begin by recalling some basic ideas from linear algebra. Recall that a vector space V is a set whose elements we can add together and multiply by scalars ($\lambda \in \mathbb{R}$). Such sets have a dimension determined by the size of (any) basis (a linearly independent, spanning set).

Ex ① For $n \in \mathbb{N}$, n -dimensional Euclidean space

$$\mathbb{R}^n = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} : x_1, x_2, \dots, x_n \in \mathbb{R} \right\} = \{(x_1, \dots, x_n) : x_1, \dots, x_n \in \mathbb{R}\}$$

is a vector space with pointwise operations:

$$\begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} + \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix} = \begin{pmatrix} x_1 + y_1 \\ x_2 + y_2 \\ \vdots \\ x_n + y_n \end{pmatrix}, \quad \lambda \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} \lambda x_1 \\ \lambda x_2 \\ \vdots \\ \lambda x_n \end{pmatrix}.$$

The standard basis for \mathbb{R}^n is $\{e_1, e_2, \dots, e_n\}$

where $e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, e_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}, \dots, e_n = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{pmatrix},$

thus $\dim(\mathbb{R}^n) = |\{e_1, \dots, e_n\}| = n$.

so $v \in \mathbb{R}^n$
 $\Leftrightarrow v = \sum c_i e_i$

Ex ② For $n, m \in \mathbb{N}$ denote by $M(m, n)$ ($= M$) the $m \times n$ matrices with real entries. Is a vector space also with pointwise operations.

Notation: For $A \in M$ with (i,j) -entry a_{ij} , we write

$$A = (a_{ij})_{\substack{1 \leq i \leq m \\ 1 \leq j \leq n}}$$

and $[A]_{ij} = a_{ij}$.

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M has ~~standard~~ basis $\{E_{ij} : 1 \leq i \leq m, 1 \leq j \leq n\}$
 where $[E_{ij}]_{k\ell} = \delta_{i=k} \delta_{j=\ell}$.

Thus $\dim(M(m,n)) = m \cdot n$. In fact, $M(m,n) \cong \mathbb{R}^{m \cdot n}$.

- Recall that every $A \in M(m,n)$ defines a linear transformation

$$T_A : \mathbb{R}^n \rightarrow \mathbb{R}^m \quad (\text{warning: } \text{non} \text{--} \text{inv})$$

by

$$T_A \left(\begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \right) = \begin{pmatrix} \sum_{j=1}^n a_{1j} x_j \\ \vdots \\ \sum_{j=1}^n a_{mj} x_j \end{pmatrix}$$

$$T_A \left(\sum_{i=1}^m x_i e_i \right) = \sum_{i=1}^m \sum_{j=1}^n (a_{ij} x_j) e_i$$

In fact, denoting by $L(\mathbb{R}^n, \mathbb{R}^m) (= L)$ the set of linear transformations from \mathbb{R}^n to \mathbb{R}^m
 (another vector space),

$$\varphi : L \rightarrow L$$

$$A \mapsto T_A$$

defines an isomorphism of vector spaces.
 Hence we can always think of matrices as linear transformations and vice versa. (The former are better for computing, the latter for theory).

- Recall that matrices also have a multiplication operation, for $A = (a_{ij}) \in M(m,n)$, $B = (b_{ij}) \in M(n,p)$

$AB \in M(m,p)$ with

$$[AB]_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

Also, for linear transformations we have composition.

Thm: For $A \in M(m,n)$ and $B \in M(n,p)$

$$T_A \circ T_B = T_{AB}$$

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If Exercise - check on the std basis for \mathbb{R}^p . \square

• Recall that a norm on a vector space V is a map $| \cdot | : V \rightarrow \mathbb{R}$ satisfying:

- (a) $\forall v \in V, |v| \geq 0$ with equality iff $v=0$
- (b) $|xv| = |x| \cdot |v| \quad \forall x \in \mathbb{R}$
- (c) $|v+w| \leq |v| + |w|$

When V is equipped with a norm, we call it a normed space. ~~and~~ If we need to specify the space on which the norm is defined, we may write $| \cdot |_V$.

Observe that:

$$d(v, w) = |v - w|$$

defines a metric for V .

Ex: $\mathbb{R}^n \ni \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = v \iff |v| = \sqrt{x_1^2 + \dots + x_n^2}$.

Recall that in this case, the norm reduces

to the ~~Euclidean~~ dot product (inner product):

$$\langle \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}, \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} \rangle = x_1 y_1 + \dots + x_n y_n$$

$$\text{and } |v| = \langle v, v \rangle^{1/2}.$$

$$\text{Also observe that } x_j = \langle \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}, e_j \rangle.$$

Def: Let V and W be normed spaces. For a linear transformation $T: V \rightarrow W$, its operator norm is the quantity:

$$\|T\| := \sup \left\{ \frac{|Tv|_W}{|v|_V} : v \in V \setminus \{0\} \right\}$$

We can think of $\|T\|$ has the maximum amount it stretches a vector. Consequently:

$$\|T \circ S\| \leq \|T\| \cdot \|S\|$$

for $T: V \rightarrow W, S: U \rightarrow V$. Exercise: check rigorously

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Ex For $A \in M$, can consider $\|T_A\|$.

Exercise: For $A \in M(n, n)$, $A^T = A$, show

$$\|A\| = \max_{1 \leq i \leq n} |\lambda_i|$$

where $\lambda_1, \dots, \lambda_n$ are eigenvalues of A
(use problems 4 and 5 from HW#1)

Thm: Let $T: V \rightarrow W$ be a lin. trans between two normed spaces. The following are equivalent (CTFAE):

- (a) $\|T\| < \infty$,
- (b) T is uniformly continuous,
- (c) T is continuous
- (d) T is continuous at the origin.

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Pf: (a) \Rightarrow (b) As T is linear, for $v, v' \in V$ we have

$$|Tv - Tv'| = |T(v - v')| \leq \|T\| |v - v'|$$

Thus for $\epsilon > 0$, we take $\delta = \frac{\epsilon}{\|T\|}$ in defn. of uniform continuity.

(b) \Rightarrow (c) Immediate.

(c) \Rightarrow (d) Immediate.

(d) \Rightarrow (a) Taking $\epsilon = 1$, let $\delta > 0$ be s.t. if $u \in V$ satisfies $|u| = |u - 0| < \delta$, then $|Tu| = |Tu - 0| < 1$.

Now, for arbitrary $v \in V$, set

$$\lambda = \frac{s}{2|v|}$$

and

$$u := \lambda v.$$

$$\text{Then } |u| = \frac{s}{2|v|} \cdot |v| = \frac{s}{2} < s$$

Thus

$$\frac{|Tv|}{|v|} = \frac{|T\lambda v|}{|\lambda v|} = \frac{|Tu|}{|u|} < \frac{1}{|u|} = \frac{2}{s}.$$

which implies $\|T\| \leq \frac{2}{s} < \infty$. □

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Thm Every lin. trans. $T: \mathbb{R}^n \rightarrow W$ is cts, and every isomorphism $T: \mathbb{R}^n \rightarrow W$ is a homeomorphism (inverse is cts)

Pf: Letting $\{e_1, \dots, e_n\}$ be the std basis for \mathbb{R}^n , set

$$M = \max \{ \|Te_1\|_W, \dots, \|Te_n\|_W \}.$$

For $v = \sum v_j e_j \in \mathbb{R}^n$, note that

$$\|v_j\| \leq \sqrt{\|v_j\|^2} \leq \sqrt{v_1^2 + \dots + v_n^2} = \|v\|$$

Thus

$$\begin{aligned} \|Tv\|_W &= \left\| \sum_{j=1}^n v_j Te_j \right\|_W \leq \sum_{j=1}^n \|v_j\| \|Te_j\|_W \\ &\leq \sum_{j=1}^n \|v\| \cdot M = \|v\| \cdot M. \end{aligned}$$

Thus $\|T\| \leq n \cdot M < \infty$. By the previous thm, T is cts.

Now, let $T: \mathbb{R}^n \rightarrow W$ be an isomorphism.

Then by the above T is cts. It remains to show T^{-1} is cts. Consider the unit sphere

$$S^{n-1} := \{ u \in \mathbb{R}^n : \|u\| = 1 \}.$$

As a closed and bounded set, we know S^{n-1} is compact (Heine-Borel). Since T is cts, $T(S^{n-1})$ is compact. Since T is injective, and $0 \notin S^{n-1}$, $0 \notin T(0) \notin T(S^{n-1})$.

~~This means $T(S^{n-1})$ has no boundary, compact set in the normed vector space W . Consequently~~

$$c := \inf \{ \|Tu - 0\|_W : u \in S^{n-1} \} > 0.$$

That is, $\|Tu\| = \|Tu - 0\| \geq c \quad \forall u \in S^{n-1}$.

For $v \in \mathbb{R}^n$ write $v = \lambda u$ where

$$\lambda = \|v\| \quad \text{and} \quad u = \frac{v}{\|v\|}$$

Imaging of T yields $Tv = \lambda Tu$ and so $\|Tv\| \geq |\lambda| \cdot c = \frac{\|v\|}{\|v\|} \cdot c = c$, that is, $\|Tv\| \geq c$.

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Hence, for $w \in W$ if $v = T^{-1}(w)$, then

$$\frac{|T^{-1}(w)|}{|w|} = \frac{|v|}{|Tv|} \leq c$$

$\Rightarrow \|T^{-1}\| \leq \frac{1}{c} < \infty$. The previous theorem therefore implies T^{-1} iscts. \square

Remark: $\|T^{-1}\|$ is called the coercivity of T and represents the smallest factor by which T shrinks a vector.

Cor: For finite dim'l normed spaces, all lin. trans. are cts. and isomorphisms are homeomorphisms. In particular, if a finite dim'l vector space has two norms, then the identity map yields a homeomorphism between the normed spaces. In particular, $T: M \rightarrow L$ is a homeomorphism.

PF Exercise: \square

5.2 Derivatives

Recall that for $U \subseteq \mathbb{R}$ open, ~~and~~ $f: U \rightarrow \mathbb{R}$ a function, and $x \in U$ ~~and~~ f has derivative $f'(x)$ at x if

$$\lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h} = f'(x)$$

We want to adapt this definition to functions of the form

$$f: U \rightarrow \mathbb{R}^m$$

where $U \subseteq \mathbb{R}^n$ is open. However, if $h \in \mathbb{R}^n$, we have no notion of division. Fortunately, we have the following alternative definition:

$$f(x+h) = f(x) + f'(x) \cdot h + R(h) \quad \text{with} \quad \lim_{h \rightarrow 0} \frac{|R(h)|}{|h|} = 0$$