

Name: ANSWER KEY

Instructions:

- You only need a pen, or a pencil and eraser.
- In particular, this means no calculator or any electronic devices, nor notes, textbooks, etc.
- You must show appropriate legible work and justify your answer to receive full credit.
- There are ~~50~~<sup>38</sup> possible points. Point values for each problem are as indicated.
- Check and make sure there are four total pages including the cover page, when you begin the exam.
- You must read and sign the honor code below before your test will be graded.

Good Luck!

Problem	Score	Out of
1		7
2		6
3		6
4		11
5		8
Total		38

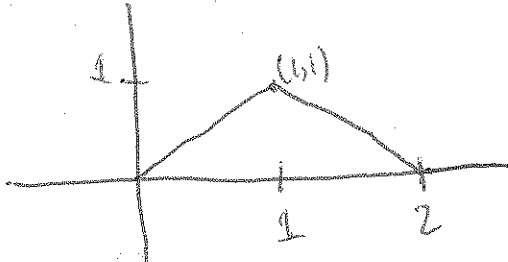
ACADEMIC HONOR CODE

*As a student and citizen of the Michigan State University Community I pledge to not lie, cheat, or steal in my academic endeavors.*

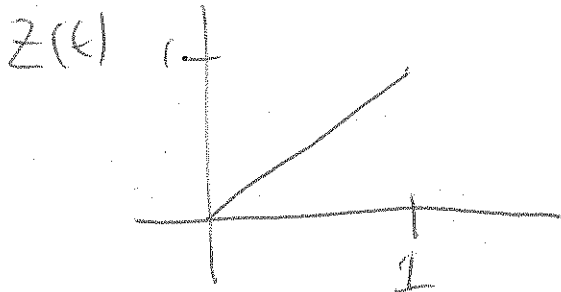
SIGNED: ANSWER KEY

1. **Basic Signals:** Let  $x(t) = r(t) - 2r(t-1) + r(t-2)$ , where  $r(t) = t u(t)$  is the ramp function. [7 points]

(a) Plot  $x(t)$ . Label all important values on your plot axes. [3 points]



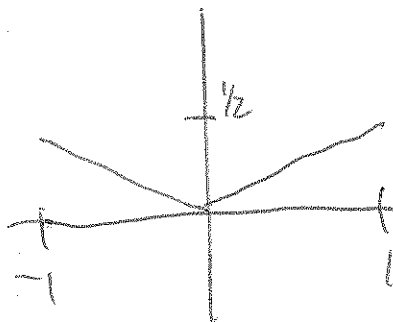
(b) Plot both the even and the odd parts of  $z(t) = t[u(t) - u(t-1)]$ . Label all important values on your plot axes. [4 points]



$$z_{\text{even}} = \frac{z(t) + z(-t)}{2}$$

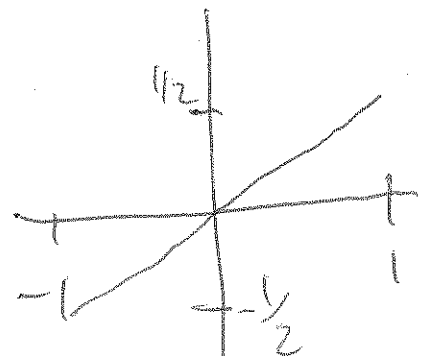
$$z_{\text{odd}} = \frac{z(t) - z(-t)}{2}$$

$z_{\text{even}}$



2

$z_{\text{odd}}$



2. Signal Properties: Answer both questions below. [6 points]

(a) Is  $x(t) = u(t+4) \exp(-t)$  a power signal? Show your work. [3 points]

$$\lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T}^T (u(t+4)e^{-t})^2 dt = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T}^T e^{-2t} u(t+4) dt$$

$$= \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-4}^T e^{-2t} dt = \lim_{T \rightarrow \infty} \left. -\frac{1}{2T} e^{-2t} \right|_{-4}^T$$

$$= \lim_{T \rightarrow \infty} \frac{-e^{-2T}}{2T} + \frac{e^8}{2T} = 0 + 0$$

Not  
a power  
signal

(b) Is  $x(t) = 5 \cos(2t) + \cos(\frac{3}{4}t) + \sin^2(5t)$  periodic? Show your work. [3 points]

$$T_1 = \frac{2\pi}{2} ; T_2 = \frac{2\pi}{3/4} ; T_3 = \frac{2\pi}{5}$$

$$\frac{T_1}{T_2} = \frac{4}{3} \cdot \frac{1}{2} = \frac{2}{3}, \quad \frac{T_1}{T_3} = \frac{5}{2}$$

Rationals!  $\Rightarrow$  this  
signal is periodic

3. **Linearity and Time-Invariance:** For the system described by the following input-output relationship,

$$\frac{d}{dt} [y(t)] = \int_{-\infty}^{t+2} 5x(\tau) d\tau$$

determine the following. [6 points]

(a) Is the system linear? Explain your answer, and show all work. [3 points]

$$\text{If } \frac{d}{dt} [y_1(t)] = \int_{-\infty}^{t+2} 5x_1(\tau) d\tau$$

$$\frac{d}{dt} [y_2(t)] = \int_{-\infty}^{t+2} 5x_2(\tau) d\tau$$

Then,

$$\frac{d}{dt} [y_1(t) + y_2(t)] = \int_{-\infty}^{t+2} 5(x_1(\tau) + x_2(\tau)) d\tau$$

∴ the system is linear!

(b) Is the system time-invariant? Explain your answer, and show all work. [3 points]

~~$$\frac{d}{dt} [y(t+t_0)] = \frac{d}{dt} [y(t)]$$~~

$$\int_{-\infty}^{t+2} 5x(\tau+t_0) d\tau = \int_{-\infty}^{t+t_0+2} 5x(\bar{\tau}) d\bar{\tau}$$

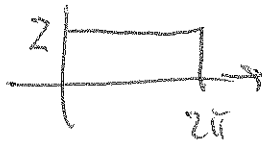
$$\text{Let } \bar{\tau} = \tau + t_0$$

$$d\bar{\tau} = d\tau$$

$$\frac{d}{dt} [y_1(t+t_0)] = \int_{-\infty}^{(t+t_0)+2} 5x(\bar{\tau}) d\bar{\tau} = \int_{-\infty}^{t+2} 5x(\tau+t_0) d\tau$$

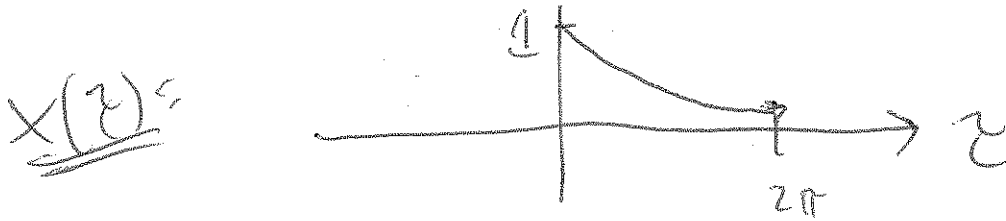
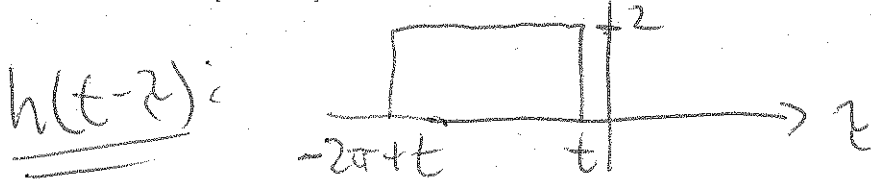
∴ it is time-invariant!

WCF1



4. LTI System Responses: A Linear Time-Invariant System  $T$  has the impulse response  $h(t) = 2[u(t) - u(t - 2\pi)]$ , where  $u(t)$  is the step function. Find the system response  $y(t)$  for the input  $x(t) = \exp(-t)[u(t) - u(t - 2\pi)]$  by completing parts (a) - (d) below. [11 points]

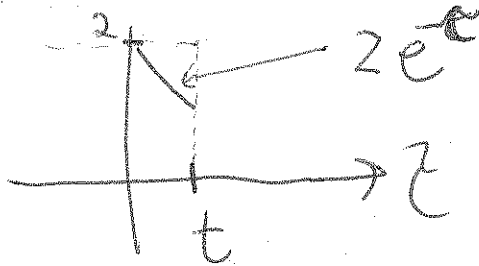
(a) Plot both  $h(t - \tau)$  and  $x(\tau)$  as functions of  $\tau$  for a fixed  $t$ . Label all important values on your plot axes. [6 points]



(b) Find the system response of  $T$  to  $x(t)$  for times  $t \leq 0$  and  $t \geq 4\pi$ . Justify your answer. [1 point]

0 When  $t \leq 0$  or  $t \geq 4\pi$  then the nonzero parts of  $x(\tau)$  &  $h(t - \tau)$  don't overlap.

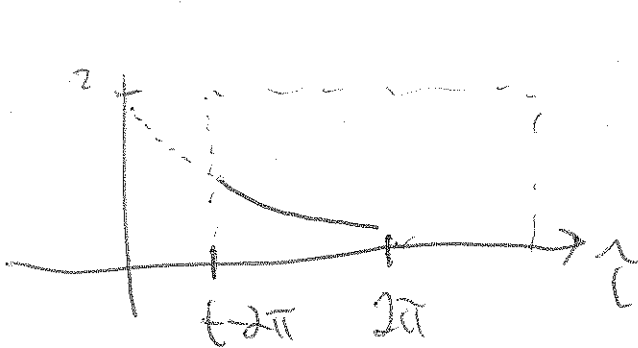
(c) Find the system response of  $T$  to  $x(t)$  for times  $0 \leq t \leq 2\pi$ . Show your work. [2 points]



$$\int_0^t 2e^{-\tau} d\tau$$

$$= -2e^{-\tau} \Big|_0^t = -2e^{-t} + 2.$$

(d) Find the system response of  $T$  to  $x$  for times  $2\pi \leq t \leq 4\pi$ . Show your work. [2 points]



$$\int_{t-2\pi}^{2\pi} 2e^{-\tau} d\tau = -2e^{-\tau} \Big|_{t-2\pi}^{2\pi}$$

$$= [e^{t-2\pi} - e^{-2\pi}] 2.$$

5. **Other System Properties:** Consider the Linear Time-Invariant (LTI) system with the following input/output relationship,

$$y(t) = \int_{-\infty}^t e^{-(t-\tau)} x(\tau - 2) d\tau.$$

Answer the following questions about this system. Justify your answers. [8 points]

(a) Find the impulse response for this system,  $h(t)$ . Show your work. [3 points]

$$\begin{aligned}
 h(t) &= \int_{-\infty}^t e^{-(t-\tau)} \delta(\tau - 2) d\tau \\
 &= e^{-(t-2)} \int_{-\infty}^t \delta(\tau - 2) d\tau = e^{-(t-2)} \int_{-\infty}^{t-2} \delta(\tau) d\tau \\
 &= \boxed{e^{-(t-2)} u(t-2)}
 \end{aligned}$$

(b) Is this system BIBO stable? Justify your answer. [3 points]

Suppose  $|x(\tau - 2)| \leq M \forall \tau$ . Then...

$$\begin{aligned}
 |y(t)| &\leq \int_{-\infty}^t e^{-(t-\tau)} |x(\tau - 2)| d\tau \\
 &\leq M \int_{-\infty}^t e^{-(t-\tau)} d\tau = M \int_{-\infty}^0 e^{\tau} d\tau = M e^{\tau} \Big|_{-\infty}^0 \\
 &= M - (1) = M
 \end{aligned}$$

Yes - Stable!

(c) Is this system causal? Why, or why not? [1 point]

Yes -  $x(t)$  is only evaluated at times  $< t$

(d) Is this system instantaneous/memoryless? Why, or why not? [1 point]

No -  $x(t)$  is evaluated over all previous times up to  $t$