TECHNICAL NOTE: A MINOR CORRECTION OF THEOREM 1.3 FROM [1]

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ABSTRACT. In this short note we correct and simplify the proof of equation (1.8) in Theorem 1.3 of [1]. In the new version (see Theorem 1 below) the noise-to-signal ratio need not be smaller than an absolute constant in order for the stated error guarantee to hold. In the process of proving Theorem 1 we also correct a small (re)normalization issue with Corollary 4 of [2].

We wish to reconstruct a given vector $\mathbf{x}_0 \in \mathbb{C}^n$, up to a global phase factor, from magnitude measurements of the form

(1)
$$b_i := |\langle \mathbf{p}_i, \mathbf{x}_0 \rangle|^2 + n_i$$

where $\mathbf{p}_i \in \mathbb{C}^n$ and $n_i \in \mathbb{R}$ for $i = 1, \ldots, m$. Vectorizing (1) yields

$$\mathbf{b} := \left| \mathcal{P} \mathbf{x}_0 \right|^2 + \mathbf{n}$$

where $\mathbf{b}, \mathbf{n} \in \mathbb{R}^m, \mathcal{P} \in \mathbb{C}^{m \times n}$, and $|\cdot|^2 : \mathbb{C}^m \to \mathbb{R}^m$ computes the componentwise squared magnitude of each vector entry. We aim to prove the following corrected version of equation (1.8) in Theorem 1.3 from [1] concerning this problem.

Theorem 1. Let $\mathcal{P} \in \mathbb{C}^{m \times n}$ have its m rows be independently drawn either uniformly at random from the sphere of radius \sqrt{n} in \mathbb{C}^n , or else as complex normal random vectors from $\mathcal{N}(0, \mathcal{I}_n/2) + i\mathcal{N}(0, \mathcal{I}_n/2)$. Then, \exists universal constants $\tilde{B}, \tilde{C}, \tilde{D} \in \mathbb{R}^+$ such that the PhaseLift procedure $\Phi_{\mathcal{P}} : \mathbb{R}^m \to \mathbb{C}^n$ satisfies

(3)
$$\min_{\theta \in [0,2\pi]} \left\| \Phi_{\mathcal{P}} \left(\mathbf{b} \right) - e^{\mathbf{i}\theta} \mathbf{x}_{0} \right\|_{2} \leq \tilde{C} \cdot \frac{\|\mathbf{n}\|_{1}}{m \|\mathbf{x}_{0}\|_{2}}$$

for all $\mathbf{x} \in \mathbb{C}^n$ with probability $1 - \mathcal{O}(e^{-\tilde{B}m})$, provided that $m \geq \tilde{D}n$. Here $\mathbf{b}, \mathbf{n} \in \mathbb{R}^m$ are as in (2).

Our proof relies on a modified version of Corollary 4 from [2]. It reads:

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Corollary 1. Let $\mathbf{x}_0 \in \mathbb{C}^n$, set $\mathbf{X}_0 = \mathbf{x}_0 \mathbf{x}_0^*$, and let $\mathbf{X} \succeq 0$ be such that $\|\mathbf{X} - \mathbf{X}_0\|_F \leq \eta \|\mathbf{X}_0\|_F = \eta \|\mathbf{x}_0\|_2^2$ for some $\eta > 0$, where $\|\cdot\|_F$ denotes the Frobenius norm. Furthermore, let λ_i be the *i*-th largest eigenvalue of \mathbf{X} and \mathbf{v}_i an associated eigenvector, such that the \mathbf{v}_i form an orthonormal eigenbasis. Then

$$\min_{\theta \in [0,2\pi]} \| e^{i\theta} \mathbf{x}_0 - \sqrt{\lambda}_1 \mathbf{v}_1 \|_2 \le (1 + 2\sqrt{2})\eta \| \mathbf{x}_0 \|_2.$$

See Section 1 for the proof of Corollary 1.

We can now use Corollary 1 to prove Theorem 1:

Proof. Beginning with Equation (1.7) in Theorem 1.3 of [1], we have that

$$\|\mathbf{X} - \mathbf{x}_0 \mathbf{x}_0^*\|_F \le C_0 \cdot \left(\frac{\|\mathbf{n}\|_1}{m\|\mathbf{x}_0\|_2^2}\right) \|\mathbf{x}_0\|_2^2,$$

where $\mathbf{X} \succeq 0$ is the solution to (1.6) in [1], and $C_0 \in \mathbb{R}^+$ is a universal constant. Returning the leading eigenvector of \mathbf{X} reweighed by the square root of its associated eigenvalue now establishes the desired error bound by Corollary 1.

Please note that no assumptions need to be made concerning the magnitude of the noise vector, \mathbf{n} , in Theorem 1.

1. Proof of Corollary 1

Proof. Note that by construction, the rank one matrix \mathbf{X}_0 has one eigenvalue $\nu := \|\mathbf{x}_0\|_2^2$ and all other eigenvalues 0. By Weyl's inequality,

(4)
$$\max\{|\nu - \lambda_1|, \lambda_2, \dots, \lambda_n\} \le \eta \nu.$$

By orthonormality of the \mathbf{v}_i , the spectral norm of the matrix $\mathbf{X} - \nu \mathbf{v}_1 \mathbf{v}_1^*$ satisfies

$$\|\mathbf{X} - \nu \mathbf{v}_1 \mathbf{v}_1^*\| = \left\| (\lambda_1 - \nu) \mathbf{v}_1 \mathbf{v}_1^* + \sum_{j=2}^n \lambda_j \mathbf{v}_j \mathbf{v}_j^* \right\| \le \eta \nu,$$

where the last inequality uses (4). Consequently, by the triangle inequality,

$$\|\mathbf{X}_0 - \nu \mathbf{v}_1 \mathbf{v}_1^*\| \le \|\mathbf{X}_0 - \mathbf{X}\| + \|\mathbf{X} - \nu \mathbf{v}_1 \mathbf{v}_1^*\| \le 2\eta\nu.$$

Thus, we can see that

(5)
$$\nu^2 - \nu |\langle \mathbf{x}_0, \mathbf{v}_1 \rangle|^2 = \frac{1}{2} ||\mathbf{X}_0 - \nu \mathbf{v}_1 \mathbf{v}_1^*||_F^2 \le ||\mathbf{X}_0 - \nu \mathbf{v}_1 \mathbf{v}_1^*||^2 \le 4\eta^2 \nu^2,$$

where the second to last inequality follows from the fact that $\mathbf{X}_0 - \nu \mathbf{v}_1 \mathbf{v}_1^*$ is at most rank 2.

We next choose $\phi \in [0, 2\pi]$ such that $\langle e^{i\phi} \mathbf{x}_0, \mathbf{v}_1 \rangle = |\langle \mathbf{x}_0, \mathbf{v}_1 \rangle|$, and then note that

(6)
$$\|e^{i\phi}\mathbf{x}_{0} - \sqrt{\nu}\mathbf{v}_{1}\|_{2}^{2} = 2\nu - 2\sqrt{\nu}\langle e^{i\phi}\mathbf{x}_{0}, \mathbf{v}_{1}\rangle = 2\nu - 2\sqrt{\nu} \cdot |\langle \mathbf{x}_{0}, \mathbf{v}_{1}\rangle|$$
$$\leq \left(2\nu - 2\sqrt{\nu} \cdot |\langle \mathbf{x}_{0}, \mathbf{v}_{1}\rangle|\right) \left(\frac{\nu + \sqrt{\nu} \cdot |\langle \mathbf{x}_{0}, \mathbf{v}_{1}\rangle|}{\nu}\right)$$
$$= \frac{2}{\nu} \left(\nu^{2} - \nu |\langle \mathbf{x}_{0}, \mathbf{v}_{1}\rangle|^{2}\right) \leq 8\eta^{2}\nu,$$

where the last inequality follows from (5). Finally, by the triangle inequality, (4), and (6), we have

$$\begin{split} \| e^{i\phi} \mathbf{x}_0 - \sqrt{\lambda}_1 \mathbf{v}_1 \|_2 &\leq \| e^{i\phi} \mathbf{x}_0 - \sqrt{\nu} \mathbf{v}_1 \|_2 + \| \sqrt{\nu} \mathbf{v}_1 - \sqrt{\lambda}_1 \mathbf{v}_1 \|_2 \\ &\leq 2\sqrt{2}\eta\sqrt{\nu} + \left| \sqrt{\nu} - \sqrt{\lambda}_1 \right| \\ &\leq 2\sqrt{2}\eta\sqrt{\nu} + \frac{|\nu - \lambda_1|}{\sqrt{\nu} + \sqrt{\lambda}_1} \\ &\leq 2\sqrt{2}\eta\sqrt{\nu} + \frac{\eta\nu}{\sqrt{\nu} + \sqrt{\lambda}_1} \\ &\leq 2\sqrt{2}\eta\sqrt{\nu} + \eta\sqrt{\nu} = (1 + 2\sqrt{2})\eta\sqrt{\nu}. \end{split}$$

The desired result now follows.

References

- E. J. Candes and X. Li. Solving quadratic equations via phaselift when there are about as many equations as unknowns. *Foundations of Computational Mathematics*, 14(5):1017–1026, 2014.
- [2] L. Demanet and P. Hand. Stable optimizationless recovery from phaseless linear measurements. *Journal of Fourier Analysis and Applications*, 20(1):199–221, 2014.