

2a. Consider functions the form:

$$\begin{aligned} \mathbf{f} : \mathbb{R}^2 &\rightarrow \mathbb{R}^2 & \mathbf{c} : \mathbb{R} &\rightarrow \mathbb{R}^2 & g : \mathbb{R}^2 &\rightarrow \mathbb{R} \\ \mathbf{f}(x, y) &= (f_1(x, y), f_2(x, y)) & \mathbf{c}(t) &= (c_1(t), c_2(t)) & g(x, y) &= g(x, y). \end{aligned}$$

The Jacobian matrices of partial derivatives at $\mathbf{v} = \mathbf{a}$ or $t = a$ are:

$$[D\mathbf{f}_{\mathbf{a}}] = \left[\begin{array}{c|c} \frac{\partial \mathbf{f}}{\partial x} & \frac{\partial \mathbf{f}}{\partial y} \end{array} \right] = \left[\begin{array}{c} \nabla f_1(\mathbf{a}) \\ \nabla f_2(\mathbf{a}) \end{array} \right] = \left[\begin{array}{cc} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{array} \right]$$

$$[D\mathbf{c}_a] = \left[\frac{d\mathbf{c}}{dt} \right] = [\mathbf{c}'(a)] = \left[\begin{array}{c} \frac{dc_1}{dt} \\ \frac{dc_2}{dt} \end{array} \right]$$

$$[Dg_{\mathbf{a}}] = [\nabla g(\mathbf{a})] = \left[\begin{array}{cc} \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{array} \right].$$

Each of these represents a linear function which approximates the original function near a specific point $\mathbf{v} = \mathbf{a}$ or $t = a$, and it is a matrix of *numbers*, not of functions.

We form all possible compositions between these functions, and write out the matrix form of the Chain Rule.

- $g \circ \mathbf{c} : \mathbb{R} \xrightarrow{\mathbf{c}} \mathbb{R}^2 \xrightarrow{g} \mathbb{R}$. The most important case of multivariable Chain Rule.

$$\begin{aligned} [D(g \circ \mathbf{c})_a] &= \left[\frac{d}{dt}(g(\mathbf{c}(t))) \right] \\ &= [Dg_{\mathbf{c}(a)}] \cdot [D\mathbf{c}_a] = [\nabla g(\mathbf{c}(a)) \cdot \mathbf{c}'(a)] \\ &= \left[\begin{array}{cc} \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{array} \right] \cdot \left[\begin{array}{c} \frac{dc_1}{dt} \\ \frac{dc_2}{dt} \end{array} \right] = \left[\frac{\partial g}{\partial x} \frac{dc_1}{dt} + \frac{\partial g}{\partial y} \frac{dc_2}{dt} \right]. \end{aligned}$$

We usually write this without matrices, and denoting $\mathbf{c}(t) = (x(t), y(t))$:

$$\frac{d}{dt}(g(\mathbf{c}(t))) = \nabla g(\mathbf{c}(t)) \cdot \mathbf{c}'(t) = \frac{\partial g}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial g}{\partial y} \frac{\partial y}{\partial t},$$

where it is understood that we plug in $t = a$, $x = x(a)$, $y = y(a)$.

- $\mathbf{c} \circ g : \mathbb{R}^2 \xrightarrow{g} \mathbb{R} \xrightarrow{\mathbf{c}} \mathbb{R}^2$.

$$\begin{aligned}
[D(\mathbf{c} \circ g)_{\mathbf{a}}] &= \begin{bmatrix} \frac{\partial}{\partial x} c_1(g(x, y)) & \frac{\partial}{\partial y} c_1(g(x, y)) \\ \frac{\partial}{\partial x} c_2(g(x, y)) & \frac{\partial}{\partial y} c_2(g(x, y)) \end{bmatrix} \\
&= [D\mathbf{c}_{g(\mathbf{a})}] \cdot [Dg_{\mathbf{a}}] = [\mathbf{c}'(g(\mathbf{a}))] \cdot [\nabla g(\mathbf{a})] \\
&= \begin{bmatrix} \frac{dc_1}{dt} \\ \frac{dc_2}{dt} \end{bmatrix} \cdot \begin{bmatrix} \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{bmatrix} = \begin{bmatrix} \frac{dc_1}{dt} \frac{\partial g}{\partial x} & \frac{dc_1}{dt} \frac{\partial g}{\partial y} \\ \frac{dc_2}{dt} \frac{\partial g}{\partial x} & \frac{dc_2}{dt} \frac{\partial g}{\partial y} \end{bmatrix}.
\end{aligned}$$

- $\mathbf{f} \circ \mathbf{c} : \mathbb{R} \xrightarrow{\mathbf{c}} \mathbb{R}^2 \xrightarrow{\mathbf{f}} \mathbb{R}^2$.

$$\begin{aligned}
[D(\mathbf{f} \circ \mathbf{c})_a] &= \begin{bmatrix} \frac{d}{dt} f_1(\mathbf{c}(t)) \\ \frac{d}{dt} f_2(\mathbf{c}(t)) \end{bmatrix} \\
&= [D\mathbf{f}_{\mathbf{c}(a)}] \cdot [D\mathbf{c}_a] = \begin{bmatrix} \nabla f_1(\mathbf{c}(a)) \cdot \mathbf{c}'(a) \\ \nabla f_2(\mathbf{c}(a)) \cdot \mathbf{c}'(a) \end{bmatrix} \\
&= \begin{bmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{bmatrix} \cdot \begin{bmatrix} \frac{dc_1}{dt} \\ \frac{dc_2}{dt} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1}{\partial x} \frac{dc_1}{dt} + \frac{\partial f_1}{\partial y} \frac{dc_2}{dt} \\ \frac{\partial f_2}{\partial x} \frac{dc_1}{dt} + \frac{\partial f_2}{\partial y} \frac{dc_2}{dt} \end{bmatrix}.
\end{aligned}$$

- $g \circ \mathbf{f} : \mathbb{R}^2 \xrightarrow{\mathbf{f}} \mathbb{R}^2 \xrightarrow{g} \mathbb{R}$.

$$\begin{aligned}
[D(g \circ \mathbf{f})_{\mathbf{a}}] &= \begin{bmatrix} \frac{\partial}{\partial x} g(\mathbf{f}(x, y)) & \frac{\partial}{\partial y} g(\mathbf{f}(x, y)) \end{bmatrix} \\
&= [Dg_{\mathbf{f}(a)}] \cdot [D\mathbf{f}_{\mathbf{a}}] = \begin{bmatrix} \nabla g(\mathbf{f}(a)) \cdot \frac{\partial \mathbf{f}}{\partial x} & \nabla g(\mathbf{f}(a)) \cdot \frac{\partial \mathbf{f}}{\partial y} \end{bmatrix} \\
&= \begin{bmatrix} \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{bmatrix} \cdot \begin{bmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{bmatrix} = \begin{bmatrix} \frac{\partial g}{\partial x} \frac{\partial f_1}{\partial x} + \frac{\partial g}{\partial y} \frac{\partial f_1}{\partial y} & \frac{\partial g}{\partial x} \frac{\partial f_2}{\partial x} + \frac{\partial g}{\partial y} \frac{\partial f_2}{\partial y} \end{bmatrix}.
\end{aligned}$$

2b. We illustrate $\mathbf{f}(\mathbf{c}(t))$ for the case: $\mathbf{f}(x, y) = (xe^{x^2+y^2}, ye^{x^2+y^2})$, $\mathbf{c}(t) = (t \cos(t), t \sin(t))$, and $a = \pi$. Then: $\mathbf{c}(a) = (\pi, 0)$, $\mathbf{c}'(a) = (\cos(t) - t \sin(t), \sin(t) + t \cos(t))|_{t=\pi} = (1, \pi)$, and:

$$[D\mathbf{f}_{\mathbf{c}(a)}] = \begin{bmatrix} (2x^2+1)e^{x^2+y^2} & 2xye^{x^2+y^2} \\ 2xye^{x^2+y^2} & (2y^2+1)e^{x^2+y^2} \end{bmatrix} \Big|_{(x,y)=(\pi,0)} = \begin{bmatrix} (2\pi^2+1)e^{\pi^2} & 0 \\ 0 & e^{\pi^2} \end{bmatrix}$$

Thus:

$$[D(\mathbf{f} \circ \mathbf{c})(a)] = \begin{bmatrix} (2\pi^2+1)e^{\pi^2} & 0 \\ 0 & e^{\pi^2} \end{bmatrix} \cdot \begin{bmatrix} 1 \\ \pi \end{bmatrix} = \begin{bmatrix} (2\pi^2+1)e^{\pi^2} \\ \pi e^{\pi^2} \end{bmatrix}$$