

Exercises: (Chapter 1 and Chapter 2 §1, §2, and §3)

- Download <https://math.msu.edu/~iwenmark/Teaching/MTH451/HwandCode/TaylorExample.zip> and then modify the Matlab script “TaylorExample.m” to approximate $f(x) = \cos(\exp(2x))$.¹ You should graph the first, second, and third degree Taylor polynomial approximations of f (based at 0) over the interval $(-0.5, 0.5)$, together with f itself. If you modify the MATLAB script “TaylorExample.m” to do this, make sure to either disable the portion of the code that reads in and plots “TaylorExamp.txt”, or, better yet, modify the C code that produces “TaylorExamp.txt” too so that it produces a new “TaylorExamp.txt” that contains the correct third degree Taylor polynomial for this f . **In any case, turn in a printout of both your graph, and of the (modified) code you used to produce it.**
- Download and run “Round.m” in MATLAB (available at <https://math.msu.edu/~iwenmark/Teaching/MTH451/HwandCode/HW2scripts.zip>).² The script approximates the value $2^k\pi$ to single precision accuracy for each of $k = 1, 2, 3, \dots, 20$ in two different ways:
 - “Approx1” is calculated by computing $2^k\pi$ directly (note that this can be implemented by simply shifting the decimal point in the binary representation of π back k times)
 - “Approx2” is calculated by adding π to itself $2^k - 1$ times

The plot produced by the script contains two relative error curves: the relative error $E1(k) = \frac{|\text{Approx1} - 2^k\pi|}{2^k\pi}$ as a function of k , and the relative error $E2(k) = \frac{|\text{Approx2} - 2^k\pi|}{2^k\pi}$ as a function of k . Which error curve increases fastest as k increases (i.e., which approximation is least accurate), one or two? **Explain why the worse approximation is so much worse.**

- Compute the dot product of the following two vectors (available already typed in into MATLAB at <https://math.msu.edu/~iwenmark/Teaching/MTH451/HwandCode/HW2scripts.zip>):

$$x = [2.718281828, -3.141592654, 1.414213562, 0.5772156649, 0.3010299957], \text{ and}$$

$$y = [1486.2497, 8.78366.9879, -22.37492, 4773714.647, 0.000185049].$$

Compute the summation in four ways:

- Forward order $\sum_{i=1}^n x_i y_i$
- Reverse order $\sum_{i=n}^1 x_i y_i$
- Largest-to-smallest order (add all positive numbers in order from largest to smallest, then add negative numbers in order from smallest to largest, and then add the two partial sums)
- Smallest-to-largest order (reverse the order of the adding in the previous method)

Use both single (“single()” in MATLAB) and double (“double()” in MATLAB) precision for a total of eight answers. Compare the results with the *correct* value to seven decimal places, $1.006571 * 10^{-9}$. Which method of computing the dot product is most accurate? Which method of computing the dot product is least accurate? **Explain your answers.**

- Using the definition $\sinh(x) := \frac{\exp(x) - \exp(-x)}{2}$, discuss the problem of computing $\sinh(x)$ without loss of significance. For what values of $x \in \mathbb{R}$ will loss of significance be an issue? How can you modify the computation of $\sinh(x)$ for those values of x to avoid loss of significance (e.g., write out a truncated series you could use to compute $\sinh(x)$ to help you keep significance for those values of x)?
- The condition number of the function $f(x) = x^\alpha$ is independent of x . What is the condition number?
- What is the condition number of $\ln(x)$? For what values of $x \in \mathbb{R}$ is it largest?

¹Alternatively, as always, you may instead recode this script in a different coding language of your choice.

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