

HIGHER ORDER LINEAR ODES

n^{th} order linear ODE: $a_n(x) \frac{d^n y}{dx^n} + a_{n-1}(x) \frac{d^{n-1} y}{dx^{n-1}} + \dots + a_1(x) \frac{dy}{dx} + a_0(x)y = g(x)$

IVP: The dependent variable y and its derivatives are specified at the same value x_0 of x (indp. var.):

$$y(x_0) = b_0; y'(x_0) = b_1; \dots; y^{(n-1)}(x_0) = b_{n-1}$$

for some numbers b_0, b_1, \dots, b_{n-1}

BVP: The dependent variable y and its derivatives are specified at different values of x (indp. var.)

Ex: For a 2nd order linear eq n:

$$a_2(x)y'' + a_1(x)y' + a_0(x)y = g(x)$$

one can have the following possibilities for the boundary value conditions:

- $y(a) = b_0; y(b) = b_1$
- $y'(a) = b_0; y(b) = b_1$
- $y(a) = b_0; y'(b) = b_1$
- $y'(a) = b_0; y'(b) = b_1$

Homogeneous if $g=0$
(different meaning of the word "homogeneous")

Non-Homogeneous if $g \neq 0$

Ex: $y''' + 2y'' - e^x y = x^2$ (non-homogeneous)
 $y^{(4)} - x e^x y'' + y = 0$ (homogeneous)

• To solve a non-homogeneous linear ODE, we must first solve the homogeneous one.

Existence & Uniqueness for IVPs:

Let an n^{th} order linear ODE: $a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_0 y = g$; $y(x_0) = b_0, \dots, y^{(n-1)}(x_0) = b_{n-1}$

Suppose that an interval $I \subset \mathbb{R}$ satisfies:

- $a_n(x), a_{n-1}(x), \dots, a_0(x)$ and $g(x)$ are continuous on I .
- $a_n(x) \neq 0$ for all $x \in I$.

Then, for every $x_0 \in I$, there exists a unique solution to the IVP.

Ex: $y = 3e^{2x} + e^{-2x} - 3x$ is a solution to: $y'' - 4y = 12x$; $y(0) = 4$; $y'(0) = 1$

By the Theorem above, it is the unique solution.

$a_2(x) = 1$ continuous, never 0
 $a_1(x) = 0$ continuous
 $a_0(x) = -4$ continuous
 $g(x) = 12x$ continuous.

Ex: $y = Cx^2 - x$ is a solution to $x^2 y'' - 2xy' + 2y = 0$; $y(0) = 0$; $y'(0) = -1$ for any value of C
(an IVP with ∞ -many solutions).
(the assumptions of the Thm. are not met: $a_2(x) = x^2$; $a_2(0) = 0$.)

- Even when the assumptions of the Thm. above are satisfied, a BVP can have
 - * several solutions (∞ -many)
 - * one solution
 - * no solutions.

Ex: $y'' + 16y = 0$

$y = C_1 \cos(4x) + C_2 \sin(4x)$ - general solution -

Impose different boundary conditions:

- **BVP 1**: $y(0) = 0$; $y(\pi/2) = 0 \Rightarrow$ ∞ -many solutions ($y = C_2 \sin(4x)$ is a sol. for all C_2)
- **BVP 2**: $y(0) = 0$; $y(\pi/8) = 0 \Rightarrow$ one solution ($y = 0$)
- **BVP 3**: $y(0) = 0$; $y(\pi/2) = 1 \Rightarrow$ no solutions

Linear Independence

Def.: A set of n functions $f_1(x), \dots, f_n(x)$ are called linearly dependent on some interval $I \subset \mathbb{R}$ if there exist constants c_1, c_2, \dots, c_n (not all zero) such that:

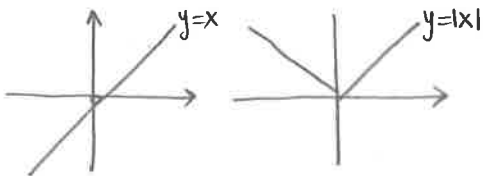
$$c_1 f_1(x) + c_2 f_2(x) + \dots + c_n f_n(x) = 0, \forall x \in I$$

Otherwise, they are called linearly independent.

Ex1: $f_1(x) = x^2; f_2(x) = 3x^2$
 $-3f_1(x) + f_2(x) = -3x^2 + 3x^2 = 0, \forall x \in \mathbb{R}$
 \Rightarrow linearly dependent on \mathbb{R}

Two functions $f_1(x), f_2(x)$ are lin. dep. if and only if they are constant multiples of one another.

Ex2: $f_1(x) = x; f_2(x) = |x|$



\rightarrow lin. indep. on \mathbb{R} (cannot be expressed as constant multiples of each other on \mathbb{R})

\rightarrow lin. dep. on $(0, \infty)$ $x = 1 \cdot |x|$ on $(0, \infty)$

\rightarrow lin. dep. on $(-\infty, 0)$ $x = -1 \cdot |x|$ on $(-\infty, 0)$

Ex3: $f_1(x) = \sqrt{x} + 3$
 $f_2(x) = \sqrt{x} + 3x$
 $f_3(x) = x - 1$
 $f_4(x) = x^2$

$$(f_2 - f_1)(x) = 3x - 3 = 3(x-1) = 3f_3(x)$$

$$\Rightarrow f_1(x) - f_2(x) + 3f_3(x) + 0 \cdot f_4(x) = 0 \Rightarrow \text{lin. dep. on } (0, \infty)$$

\hookrightarrow the constants can't all be 0 but it's allowed for some to be 0.

Wronskian

Suppose f_1, f_2, \dots, f_n have at least $(n-1)$ derivatives. Define their Wronskian as:

$$W(f_1, \dots, f_n)(x) = \begin{vmatrix} f_1(x) & f_2(x) & \dots & f_n(x) \\ f_1'(x) & f_2'(x) & \dots & f_n'(x) \\ \vdots & \vdots & \ddots & \vdots \\ f_1^{(n-1)}(x) & f_2^{(n-1)}(x) & \dots & f_n^{(n-1)}(x) \end{vmatrix}$$

• If f_1, f_2, \dots, f_n are linearly dependent on I , then $W(f_1, \dots, f_n)(x) = 0, \forall x \in I$.

\Rightarrow If $W(f_1, \dots, f_n)(x) \neq 0$ for at least one value of x on I , then f_1, \dots, f_n are linearly independent.

Proof ($n=2$): Suppose $W(f_1, f_2)(x) \neq 0$ for at least one $x \in I$, and also that f_1, f_2 are lin. dep. $\Rightarrow \exists$ constants (not both 0) c_1, c_2 s.t. $c_1 f_1 + c_2 f_2 = 0$ on I .

Assume $c_1 \neq 0$.

$$c_1 f_1 + c_2 f_2 = 0 \quad | \cdot f_2' \quad c_1 f_1 f_2' + c_2 f_2 f_2' = 0$$

$$c_1 f_1' + c_2 f_2' = 0 \quad | \cdot f_2 \quad c_1 f_1' f_2 + c_2 f_2' f_2 = 0$$

$$\ominus \quad c_1 (f_1 f_2' - f_1' f_2) = 0$$

$$\Rightarrow f_1 f_2' - f_1' f_2 = 0$$

$$W(f_1, f_2) = 0$$

\Rightarrow contradiction,

Higher Order Linear ODEs

A n^{th} Order Linear Homogeneous Equations

$$a_n(x)y^{(n)}(x) + a_{n-1}(x)y^{(n-1)}(x) + \dots + a_1(x)y'(x) + a_0(x)y(x) = 0 \quad (*)$$

(assume throughout that we are working on an interval I where the Existence & Uniqueness Thm. hold)

Superposition Principle:

If y_1, y_2, \dots, y_k are solutions to $(*)$, where k is some positive integer, then any linear combination:

$$y = c_1 y_1 + c_2 y_2 + \dots + c_k y_k$$

is also a solution to $(*)$.

To see this, look at the case $k=2$, so suppose y_1 and y_2 are solutions to $(*)$:

$$\begin{cases} a_n y_1^{(n)} + a_{n-1} y_1^{(n-1)} + \dots + a_1 y_1' + a_0 y_1 = 0 & | \cdot c_1 \text{ (some constant)} \\ a_n y_2^{(n)} + a_{n-1} y_2^{(n-1)} + \dots + a_1 y_2' + a_0 y_2 = 0 & | \cdot c_2 \text{ (some constant)} \end{cases}$$

$$\Rightarrow \begin{cases} a_n (c_1 y_1)^{(n)} + a_{n-1} (c_1 y_1)^{(n-1)} + \dots + a_1 (c_1 y_1)' + a_0 (c_1 y_1) = 0 \\ a_n (c_2 y_2)^{(n)} + a_{n-1} (c_2 y_2)^{(n-1)} + \dots + a_1 (c_2 y_2)' + a_0 (c_2 y_2) = 0 \end{cases}$$

$$\oplus \quad a_n (c_1 y_1 + c_2 y_2)^{(n)} + \dots + a_1 (c_1 y_1 + c_2 y_2)' + a_0 (c_1 y_1 + c_2 y_2) = 0$$

$\Rightarrow c_1 y_1 + c_2 y_2$ is also a solution!

Take a moment to remark why this can only work for homogeneous ODEs!

Some Useful Consequences:

① If y_1 is a solution to $(*)$, then any constant multiple $y = c y_1$ is also a solution. (Take $k=1$ above)

② The trivial solution $y=0$ satisfies any homogeneous linear ODE. (Take $c_1 = \dots = c_k = 0$ or just verify).

Fundamental Sets

Def.: A fundamental set of solutions to an n^{th} order linear homogeneous ODE (*) on some interval I is a set:

$$\{y_1, y_2, \dots, y_n\}$$

of n solutions that are linearly independent on I .

- Two very important facts about fundamental sets:
 - 1). If we have a fundamental set, we have all the solutions.
 - 2). An "if and only if" relationship to the Wronskian.

① Let $\{y_1, y_2, \dots, y_n\}$ be a fundamental set of solutions to (*) on some interval I . Then ANY solution to (*) on I is a linear combination of y_1, \dots, y_n .

For this reason, if $\{y_1, \dots, y_n\}$ is a fundamental set, then

$$y = c_1 y_1 + c_2 y_2 + \dots + c_n y_n$$

is called the general solution to (*) on I .

This is actually a simple consequence of the Existence & Uniqueness Theorem and a result from linear algebra, which we recall below:

Recall that a system of n linear algebraic equations:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \vdots \\ a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n = b_n \end{cases}$$

can be expressed in matrix form as $A\vec{x} = \vec{b}$, where A is the $n \times n$ matrix of coefficients, \vec{x} is the vector of unknowns.

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix}; \quad \vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}; \quad \vec{b} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$$

Possible behaviors of such a system, in terms of the determinant $\det(A)$:

• $\det(A) \neq 0 \Rightarrow$ unique solution

• $\det(A) = 0 \Rightarrow$ either no solution or infinitely many solutions.

[Important special case: if the system is homogeneous, i.e. $\vec{b} = \vec{0}$ and $\det(A) = 0$, then there are infinitely many solutions]

Back to our homogeneous ODEs, look at the case $n=2$.

Equation:

$$a_2(x)y''(x) + a_1(x)y'(x) + a_0(x)y(x) = 0 \quad (*)$$

(assume a_2, a_1, a_0 are continuous on I and $a_2(x) \neq 0, \forall x \in I \rightsquigarrow \exists!$)

Suppose: \bullet $y(x)$ is a solution to $(*)$

\bullet $\{y_1(x), y_2(x)\}$ is a fundamental set for $(*)$ (i.e. lin. indep. solutions).

Why should y be a linear combination of y_1 and y_2 ?

\bullet Let $x_0 \in I$ be a point where the Wronskian $W(y_1, y_2)(x_0) \neq 0$

(we know such a point must exist, since y_1, y_2 are linearly independent).

\bullet Let $b_1 = y(x_0), b_2 = y'(x_0)$ and look at the system:

$$\begin{cases} y_1(x_0)c_1 + y_2(x_0)c_2 = b_1 \\ y_1'(x_0)c_1 + y_2'(x_0)c_2 = b_2 \end{cases} \quad \begin{array}{l} (c_1, c_2 = \text{the unknowns}) \\ y_{1,2}(x_0), y'_{1,2}(x_0) = \text{the coefficients} \end{array}$$

The determinant of coefficients:

$$\begin{vmatrix} y_1(x_0) & y_2(x_0) \\ y_1'(x_0) & y_2'(x_0) \end{vmatrix} = W(y_1, y_2)(x_0) \neq 0$$

\Rightarrow the system has a unique solution c_1, c_2 .

\bullet Then look at the function $z(x) = c_1 y_1(x) + c_2 y_2(x)$:

* z is a solution to $(*) \rightsquigarrow$ superposition

* $z(x_0) = b_1$ and $z'(x_0) = b_2$

$\Rightarrow y$ and z are both solutions on I to the IVP $\begin{cases} a_2 y'' + a_1 y' + a_0 y = 0 \\ y(x_0) = b_1; y'(x_0) = b_2 \end{cases}$

$\Rightarrow \boxed{y = z}$ by the Existence & Uniqueness Theorem

$\Rightarrow y = c_1 y_1 + c_2 y_2$.

$\textcircled{2}$ A set $\{y_1, \dots, y_n\}$ of solutions to $(*)$ is a fundamental set (i.e. they are linearly independent) on an interval I if and only if the Wronskian:

$$\boxed{W(y_1, y_2, \dots, y_n)(x) \neq 0, \forall x \in I.}$$

* What is special here? One implication is easy: we know from last time that if $W(f_1, \dots, f_n)(x) \neq 0$ for at least one $x \in I$, then $\{f_1, \dots, f_n\}$ are lin. indep. (no obviously also if $W \neq 0$ for all x).

* Special: If $\{y_1, \dots, y_n\}$ = fundamental set $\Rightarrow W(y_1, \dots, y_n)(x) \neq 0$ for all $x \in I$.

(B) n^{th} Order Linear Non-Homogeneous Equations

$$a_n(x)y^{(n)}(x) + a_{n-1}(x)y^{(n-1)}(x) + \dots + a_1(x)y'(x) + a_0(x)y(x) = g(x) \quad (**)$$

- Particular Solution: A particular solution to (**) is any solution y_p that is free of any arbitrary constants.
- Complementary Solution: Every non-homogeneous linear equation (**) has an associated homogeneous linear equation (*)

$$a_n(x)y^{(n)}(x) + \dots + a_1(x)y'(x) + a_0(x)y(x) = 0 \quad (*)$$

A general solution $y_c = C_1y_1 + \dots + C_ny_n$ to the homogeneous equation (*) is called a complementary solution (or complementary function).

Any solution of the non-homogeneous equation (**) is of the form

$$y = y_c + y_p = (C_1y_1 + \dots + C_ny_n) + y_p$$

where y_c is the complementary solution and y_p is any particular solution.

Ex: Consider the equation $y'' - 9y = 27$
 Given that the general solution to $y'' - 9y = 0$ is $y_c = C_1e^{3x} + C_2e^{-3x}$ (check)
 you can easily see that $y_p = -3$ (constant function) is a particular solution.
 Then $y = C_1e^{3x} + C_2e^{-3x} - 3$ is the general solution to this non-homogeneous equation.

Proof: Let y be any solution to (**). Since y_p is also a solution:

$$\begin{aligned} a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_1 y' + a_0 y &= g \\ a_n y_p^{(n)} + a_{n-1} y_p^{(n-1)} + \dots + a_1 y_p' + a_0 y_p &= g \end{aligned}$$

$$\ominus \quad a_n (y - y_p)^{(n)} + \dots + a_1 (y - y_p)' + a_0 (y - y_p) = \underline{\underline{0}}$$

$\Rightarrow (y - y_p) =$ solution to the homogeneous equation

$\Rightarrow (y - y_p) =$ linear combination of fundamental set

$\Rightarrow y - y_p = y_c$

Homogeneous Linear ODEs with Constant Coefficients

$$a_n y^{(n)} + \dots + a_1 y' + a_0 y = 0$$
$$a_n, a_{n-1}, \dots, a_1, a_0 \in \mathbb{R}$$

n=2: $ay'' + by' + c = 0$

Characteristic Equation: $am^2 + bm + c = 0$

→ 2 distinct real roots m_1, m_2 : $y = c_1 e^{m_1 x} + c_2 e^{m_2 x}$

→ 1 repeated real root m_1 : $y = c_1 e^{m_1 x} + c_2 x e^{m_1 x}$

→ 2 complex roots $m_{1,2} = \alpha \pm i\beta$: $y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$

General n: $a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_1 y' + a_0 y = 0$

Characteristic Equation: $a_n m^n + a_{n-1} m^{n-1} + \dots + a_1 m + a_0 = 0$

→ For any real root m_1 of multiplicity $\underline{1}$, the general solution must contain $c_1 e^{m_1 x}$

→ For any real root m_1 of multiplicity \underline{k} , the general solution must contain $c_1 e^{m_1 x} + c_2 x e^{m_1 x} + \dots + c_k x^{k-1} e^{m_1 x}$

→ For any pair of complex roots $\alpha \pm i\beta$, the general solution must contain $e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$

→ If a complex root $\alpha + i\beta$ has multiplicity \underline{k} , then so does its conjugate $\alpha - i\beta$, and the general solution must contain linear combinations of $\left\{ \begin{array}{l} e^{\alpha x} \cos(\beta x), e^{\alpha x} \sin(\beta x) \\ x e^{\alpha x} \cos(\beta x), x e^{\alpha x} \sin(\beta x) \\ \vdots \\ x^{k-1} e^{\alpha x} \cos(\beta x), x^{k-1} e^{\alpha x} \sin(\beta x) \end{array} \right\}$

Examples:

• $y'' - 2y' + y = 0$

$$m^2 - 2m + 1 = 0$$

$$(m-1)^2 = 0 \Rightarrow m=1$$

(repeated root)

$$\Rightarrow y = c_1 e^x + c_2 x e^x$$

• $y'' + y' + y = 0$

$$m^2 + m + 1 = 0$$

$$\Delta = 1 - 4 = -3 \Rightarrow m = \frac{-1 \pm i\sqrt{3}}{2} = -\frac{1}{2} \pm i\frac{\sqrt{3}}{2} \Rightarrow$$

$$y = e^{-x/2} \left(c_1 \cos\left(\frac{\sqrt{3}}{2}x\right) + c_2 \sin\left(\frac{\sqrt{3}}{2}x\right) \right)$$

• $y'' + y' - 2y = 0$

$$m^2 + m - 2 = 0$$

$$(m+2)(m-1) = 0$$

$$m_1 = -2; m_2 = 1$$

$$y = c_1 e^{-2x} + c_2 e^x$$

Characteristic Equation:

$$(m-2)(m^2+m+1)$$

(2)

$$\left(-\frac{1}{2} \pm \frac{\sqrt{3}}{2}i\right)$$

General Solution:

$$c_1 e^{2x} + e^{-x/2} \left(c_2 \sin\left(\frac{\sqrt{3}}{2}x\right) + c_3 \cos\left(\frac{\sqrt{3}}{2}x\right) \right)$$

$$(m-2)^3 (m^2+16)$$

(2) x 3

$$\pm 4i$$

$$c_1 e^{2x} + c_2 x e^{2x} + c_3 x^2 e^{2x} + c_4 \sin(4x) + c_5 \cos(4x)$$

$$(m+3)(m-2)^2 (m-5)^3$$

(-3)

(2) x 2

(5) x 3

$$c_1 e^{-3x} + c_2 e^{2x} + c_3 x e^{2x} + c_4 e^{5x} + c_5 x e^{5x} + c_6 x^2 e^{5x}$$

$$(m^2+m+1)^2$$

$$\left(-\frac{1}{2} \pm \frac{\sqrt{3}}{2}i\right) \times 2$$

$$e^{-x/2} \left(c_1 \sin\left(\frac{\sqrt{3}}{2}x\right) + c_2 \cos\left(\frac{\sqrt{3}}{2}x\right) \right) + e^{-x/2} x \left(c_3 \sin\left(\frac{\sqrt{3}}{2}x\right) + c_4 \cos\left(\frac{\sqrt{3}}{2}x\right) \right)$$

Non-homogeneous Linear ODEs with Constant Coefficients

- Method of Undetermined Coefficients -

Method applies to equations of the form:

$$a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_1 y' + a_0 y = g(x)$$

where:

- $a_n, a_{n-1}, \dots, a_1, a_0$ are constants
- $g(x)$ is:
 - a polynomial (includes constant functions)
 - exponential $e^{\alpha x}$
 - $\sin(\beta x)$ or $\cos(\beta x)$
 - sums and products of these

General Idea: This method is for finding a particular solution y_p .

- Make an assumption about the form of y_p (some type of function with unknown coefficients), then find the coefficients.
- General rule for the assumption: linear combination of all the linearly independent types of functions that arise from repeated differentiations of $g(x)$.
- Polynomials, exponentials, and \sin & \cos work because any sum or product of them gives a sum or product of these same types of functions through repeated differentiation.

Superposition Principle for Non-Homogeneous Linear ODEs:

Suppose that for every $j \in \{1, 2, \dots, k\}$, y_{p_j} is a particular solution for

$$a_n(x) y^{(n)} + \dots + a_1(x) y' + a_0(x) y = g_j(x).$$

Then $y_{p_1} + \dots + y_{p_k}$ is a particular solution for

$$a_n(x) y^{(n)} + \dots + a_1(x) y' + a_0(x) y = g_1(x) + \dots + g_k(x).$$

Case (1): No function in the assumed y_p duplicates any part of y_c (i.e. no function in the assumed y_p is a solution to the associated homogeneous equation),

$g(x)$	y_p
Polynomial $p(x)$ of degree $k \geq 0$	Polynomial of same degree k
$g(x) = x + 1$	$y_p = Ax + B$
$g(x) = x^3 + x - 4$	$y_p = Ax^3 + Bx^2 + Cx + D$
$g(x) = 2$	$y_p = A$
Exponential $e^{\alpha x}$	$Ae^{\alpha x}$
$g(x) = e^{7x}$	$y_p = Ae^{7x}$
$\sin(\beta x)$ or $\cos(\beta x)$	$A \sin(\beta x) + B \cos(\beta x)$
$g(x) = \sin(2x)$	$y_p = A \sin(2x) + B \cos(2x)$
$g(x) = \cos(7x)$	$y_p = A \sin(7x) + B \cos(7x)$
$p(x)e^{\alpha x}$	(Same degree polynomial) $\cdot e^{\alpha x}$
$g(x) = (x+1)e^{3x}$	$y_p = (Ax+B)e^{3x}$
$p(x)\sin(\beta x)$ or $p(x)\cos(\beta x)$	(Same deg. poly) $\cdot \sin(\beta x) +$ (Same deg. poly) $\cdot \cos(\beta x)$
$g(x) = (x-1)\sin(2x)$	$y_p = (Ax+B)\sin(2x) + (Cx+D)\cos(2x)$
$g(x) = x^2 \cos(3x)$	$y_p = (Ax^2+Bx+C)\sin(3x) + (Dx^2+Ex+F)\cos(3x)$
$e^{\alpha x} \sin(\beta x)$ or $e^{\alpha x} \cos(\beta x)$	$Ae^{\alpha x} \sin(\beta x) + Be^{\alpha x} \cos(\beta x)$
$g(x) = e^{2x} \sin(7x)$	$y_p = Ae^{2x} \sin(7x) + Be^{2x} \cos(7x)$
$p(x)e^{\alpha x} \sin(\beta x)$ or $p(x)e^{\alpha x} \cos(\beta x)$	(Same deg. poly) $e^{\alpha x} \sin(\beta x) +$ (Same deg. poly) $e^{\alpha x} \cos(\beta x)$
$g(x) = (x+1)e^{2x} \cos(3x)$	$y_p = (Ax+B)e^{2x} \sin(3x) + (Cx+D)e^{2x} \cos(3x)$
SUMS OF FUNCTIONS OF THE TYPES ABOVE	SUM OF INDIVIDUAL GUESSES FOR y_p (SUPERPOSITION)
$g(x) = x^2 + e^{7x} \cos(\pi x)$	$y_p = Ax^2 + Bx + C + De^{7x} \sin(\pi x) + Ee^{7x} \cos(\pi x)$
$g(x) = x \sin(2x) + e^{3x} + x^3$	$y_p = (Ax+B)\sin(2x) + (Cx+D)\cos(2x) + Ee^{3x} + Fx^3 + Gx^2 + Hx + I.$

Example 1: $y'' - 2y' - 3y = e^{2x} + 3x^2 + 4x - 5 + 5\cos(2x)$

Complementary Solution: $y'' - 2y' - 3y = 0$

$y_c = c_1 e^{-x} + c_2 e^{3x}$

$m^2 - 2m - 3 = 0 \Rightarrow (m-3)(m+1) = 0 \Rightarrow m \in \{-1, 3\}$

Particular Solution: $y_p = Ae^{2x} + Bx^2 + Cx + D + E\cos(2x) + F\sin(2x)$

$y_p' = 2Ae^{2x} + 2Bx + C - 2E\sin(2x) + 2F\cos(2x)$

$y_p'' = 4Ae^{2x} + 2B - 4E\cos(2x) - 4F\sin(2x)$

$\Rightarrow y_p'' - 2y_p' - 3y_p = e^{2x} \left(\underbrace{4A - 4A - 3A}_1 \right) + X^2 \left(\underbrace{-3B}_3 \right) + X \left(\underbrace{-4B - 3C}_4 \right) + \left(\underbrace{2B - 2C - 3D}_{-5} \right)$
 $+ \cos(2x) \left(\underbrace{-4E - 4F - 3E}_5 \right) + \sin(2x) \left(\underbrace{-4F + 4E - 3F}_0 \right)$

$-3A = 1 \Rightarrow A = -\frac{1}{3}$

$-3B = 3 \Rightarrow B = -1$

$-4B - 3C = 4 \Rightarrow C = 0$

$2B - 2C - 3D = -5 \Rightarrow D = 1$

$-7E - 4F = 5$

$4E - 7F = 0 \Rightarrow F = \frac{4}{7}E$

$\Rightarrow 7E + \frac{16}{7}E = -5 \Rightarrow \frac{65}{7}E = -5 \Rightarrow E = -\frac{7}{13} \Rightarrow F = -\frac{4}{13}$

$y_p = -\frac{1}{3}e^{2x} - x^2 + 1 - \frac{7}{13}\cos(2x) - \frac{4}{13}\sin(2x)$

General Solution: $y = c_1 e^{-x} + c_2 e^{3x} - \frac{1}{3}e^{2x} - x^2 + 1 - \frac{7}{13}\cos(2x) - \frac{4}{13}\sin(2x)$

Remark: with superposition problems like this, you can also solve each non-homogeneous equation individually and add the results at the end. For example:

$y'' - 2y' - 3y = e^{2x} \Rightarrow y_{p_1} = -\frac{1}{3}e^{2x}$

$y'' - 2y' - 3y = 3x^2 + 4x - 5 \Rightarrow y_{p_2} = -x^2 + 1$

$y'' - 2y' - 3y = 5\cos(2x) \Rightarrow y_{p_3} = -\frac{7}{13}\cos(2x) - \frac{4}{13}\sin(2x)$

$\Rightarrow y_p = y_{p_1} + y_{p_2} + y_{p_3}$

Case (2): Suppose $g(x) = g_1(x) + \dots + g_k(x)$, where each function $g_j(x)$ is of the type previously discussed, with corresponding guess y_{p_j} for its particular solution. If any y_{p_j} contains a function in Y_c , then multiply this y_{p_j} by the lowest power (x^n) of x that eliminates the duplication.

Example (2):

$$y'' - y' - 2y = g(x)$$

Complementary Solution: $Y_c = C_1 e^{2x} + C_2 e^{-x}$

$$m^2 - m - 2 = 0 \Rightarrow (m-2)(m+1) = 0 \Rightarrow m_1 = 2; m_2 = -1$$

$g(x)$	y_p
$g(x) = e^{3x}$	$y_p = Ae^{3x}$ (no duplication)
$g(x) = e^{2x}$	$y_p = Axe^{2x}$ Original guess: Ae^{2x} duplicates part of Y_c Multiplication by x eliminates duplication
$g(x) = 3e^{2x} + \cos(7x)$	$y_p = Axe^{2x} + B\cos(7x) + C\sin(7x)$ <u>Superposition</u> : $g_1(x) = 3e^{2x}$; as above, multiply by x $g_2(x) = \cos(7x)$; original guess $y_{p2} = B\cos(7x) + C\sin(7x)$ does not duplicate any part of Y_c . <u>Careful</u> : $y_p = x[Ae^{2x} + B\cos(7x) + C\sin(7x)]$ is <u>wrong</u> !
$g(x) = xe^{2x}$	$y_p = (Ax^2 + Bx)e^{2x}$ Original guess: $(Ax+B)e^{2x} = Axe^{2x} + Be^{2x}$ Multiply original guess by x (removes duplication) \rightarrow duplicates Y_c
$g(x) = \sin(3x)e^{2x}$	$y_p = A\sin(3x)e^{2x} + B\cos(3x)e^{2x}$ (no duplication)
$g(x) = x^2e^{2x} + e^{\pi x}$	$y_p = (Ax^3 + Bx^2 + Cx)e^{2x} + De^{\pi x}$ (Superposition + Duplication)

Example ③: $y'' + 16 = g(x)$

Complementary Solution: $y_c = C_1 \cos(4x) + C_2 \sin(4x)$
 $m^2 + 16 = 0; m = \pm 4i$

$g(x)$	y_p
$g(x) = x^2 e^x$	$y_p = (Ax^2 + Bx + C)e^x$ (no duplication)
$g(x) = e^x \sin(4x)$	$y_p = Ae^x \sin(4x) + Be^x \cos(4x)$ (no duplication)
$g(x) = 2\cos(4x)$	$y_p = Ax \cos(4x) + Bx \sin(4x)$ Original guess $(A \cos(4x) + B \sin(4x))$ duplicates part of y_c .
$g(x) = x^3 \cos(4x) + e^{2x} \sin(4x)$	$y_p = (Ax^4 + Bx^3 + Cx^2 + Dx) \cos(4x) + (Ex^4 + Fx^3 + Gx^2 + Hx) \sin(4x) + [Ie^{2x} \sin(4x) + Je^{2x} \cos(4x)]$ <u>Superposition</u> : $g_1(x) = x^3 \cos(4x)$, original guess: $(Ax^3 + Bx^2 + Cx + D) \cos(4x) + (Ex^3 + Fx^2 + Gx + H) \sin(4x)$ duplicates part of y_c because of the terms $D \cos(4x)$ and $H \sin(4x)$ \Rightarrow multiply by x , duplication eliminated. $g_2(x) = e^{2x} \sin(4x) \Rightarrow y_{p2} = Ie^{2x} \sin(4x) + Je^{2x} \cos(4x)$ (no duplication)

Example ④: $y'' - 2y' + y = 2e^x + x$

Complementary Solution: $y_c = C_1 e^x + C_2 x e^x$

Particular Solution:

$y_p = Ax^2 e^x + (Bx + C)$

$g_1(x) = 2e^x; y_{p1} = Ae^x \cdot x^2$
 $g_2(x) = x; y_{p2} = Bx + C$ ✓
 duplicates y_c ; $x y_{p1} = Ax^3 e^x$ also does

Reduction of Order

Start with a 2nd order linear ODE
 $y'' + P(x)y' + Q(x)y = 0$ (*)
and suppose y_1 is a known solution.

(Assume we are working on an interval I
where $y_1(x) \neq 0$ for all $x \in I$.)

Look for another solution, of the form
 $y = uy_1$
where u is some unknown function of x

$$\begin{aligned} y = uy_1 &\Rightarrow y' = u'y_1 + uy_1' \\ &\Rightarrow y'' = u''y_1 + 2u'y_1' + uy_1'' \\ \Rightarrow y'' + P(x)y' + Q(x)y &= u''y_1 + 2u'y_1' + uy_1'' \\ &\quad + P(x)u'y_1 + P(x)uy_1' \\ &\quad + Q(x)uy_1 \\ &= u \underbrace{(y_1'' + P(x)y_1' + Q(x)y_1)}_0 + u''y_1 + (2y_1' + P(x)y_1)u' \\ \Rightarrow y = uy_1 &\text{ is a solution to (*) if and only if} \end{aligned}$$

$$y_1 u'' + (2y_1' + P(x)y_1)u' = 0$$

Obtain an equation in u of the form:

$$y_1 u'' + (2y_1' + P(x)y_1)u' = 0$$

$$w = u' \Rightarrow y_1 w' + (2y_1' + P(x)y_1)w = 0$$

$$\Rightarrow \frac{dw}{dx} + \left(\frac{2y_1'}{y_1} + P(x)\right)w = 0$$

$$\Rightarrow \frac{1}{w} dw = -\left(\frac{2y_1'}{y_1} + P(x)\right) dx$$

$$\Rightarrow \ln|w| = -2 \ln|y_1| - \int P(x) dx + C$$

$$\Rightarrow \ln|wy_1^2| = -\int P(x) dx + C$$

$$\Rightarrow wy_1^2 = C e^{-\int P(x) dx}$$

$$\Rightarrow w = u' = C \frac{1}{y_1^2} e^{-\int P(x) dx}$$

Make the substitution $w = u'$:

$$y_1 w' + (2y_1' + P(x)y_1)w = 0$$

(linear & separable)

Solve and find w

$$\Rightarrow w = C_2 \int \frac{1}{y_1^2} e^{-\int P(x) dx} dx + C_1$$

From $w = u'$, find u

$$\Rightarrow y = C_1 y_1 + C_2 y_1 \underbrace{\int \frac{1}{y_1^2} e^{-\int P(x) dx} dx}_{y_2 \text{ (new solution)}}$$

Finally, find $y = uy_1$:
You will obtain

$$y = C_1 y_1 + C_2 y_2$$

(the general solution)

(y_2 is another solution,
and $\{y_1, y_2\}$ are
linearly independent)

Example: Given that $y=e^x$ is a solution to $y''-y=0$, find the general solution.

- Look for a solution $y=ue^x$ for some unknown function of u .

$$y' = u'e^x + ue^x$$

$$y'' = u''e^x + 2u'e^x + ue^x$$

$$\Rightarrow y'' - y = u''e^x + 2u'e^x = (u'' + 2u')e^x$$

$$\Rightarrow y = ue^x \text{ is a solution if and only if } \boxed{u'' + 2u' = 0}$$

(because $e^x \neq 0$ for all real x).

- Solve $u'' + 2u' = 0$

Substitution: $w = u'$

$$\Rightarrow \boxed{w' + 2w = 0}$$

(Separable)

$$\frac{dw}{dx} = -2w \Rightarrow \frac{1}{w} dw = -2dx$$

$$\Rightarrow \ln|w| = -2x + C \Rightarrow$$

$$\boxed{w = ce^{-2x}}$$

$$\downarrow w = u'$$

$$u' = ce^{-2x} \Rightarrow u = \int ce^{-2x} dx$$

$$\boxed{u = -\frac{1}{2}ce^{-2x} + c_1}$$

- Find $y = ue^x$: $y = ue^x = -\frac{1}{2}ce^{-x} + c_1e^x$

$$\Rightarrow \boxed{y = c_1e^x + c_2e^{-x}}$$
 General solution

4.7 Variation of Parameters

$$y'' + P(x)y' + Q(x)y = g(x) \rightarrow \underline{\text{Standard Form}}$$

① Find the complementary solution $y_c = C_1 y_1 + C_2 y_2$

② Compute the determinants:

$$W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} \quad (\text{the Wronskian, never } 0)$$

$$W_1 = \begin{vmatrix} 0 & y_2 \\ g(x) & y_2' \end{vmatrix}$$

$$W_2 = \begin{vmatrix} y_1 & 0 \\ y_1' & g(x) \end{vmatrix}$$

linearly independent
(fundamental set)

These come from Cramer's Rule

③ Find the functions $u_1(x), u_2(x)$ given by:

$$u_1' = \frac{W_1}{W}; \quad u_2' = \frac{W_2}{W}$$

④ Particular Solution:

$$y_p = u_1 y_1 + u_2 y_2$$

⑤ General Solution: $y = C_1 y_1 + C_2 y_2 + u_1 y_1 + u_2 y_2$

General Higher Order:

$$y^{(n)} + P_{n-1}(x)y^{(n-1)} + \dots + P_1(x)y' + P_0(x)y = g(x)$$

① Find complementary solution: $y_c = C_1 y_1 + C_2 y_2 + \dots + C_n y_n$

② Compute the Wronskian of the fundamental set:

$$W = \begin{vmatrix} y_1 & y_2 & \dots & y_n \\ y_1' & y_2' & \dots & y_n' \\ \vdots & \vdots & \ddots & \vdots \\ y_1^{(n-1)} & y_2^{(n-1)} & \dots & y_n^{(n-1)} \end{vmatrix}$$

And for every $k \in \{1, 2, \dots, n\}$, compute the determinant W_k obtained by replacing the k^{th} column of W by:

$$\begin{bmatrix} 0 \\ \vdots \\ 0 \\ g(x) \end{bmatrix}$$

③ Find the functions $u_1(x), \dots, u_n(x)$ given by: $u_k' = \frac{W_k}{W}$ for every $k \in \{1, \dots, n\}$

④ Particular Solution: $y_p = u_1 y_1 + u_2 y_2 + \dots + u_n y_n$

⑤ General Solution: $y = y_c + y_p$

Example: $y''' - 2y'' - y' + 2y = e^{3x}$

① Complementary Solution: $m^3 - 2m^2 - m + 2 = 0$

$(m^2 - 1)(m - 2) = 0 \Rightarrow m \in \{-1, 1, 2\}$

$y_c = c_1 e^{-x} + c_2 e^x + c_3 e^{2x}$

② Determinants:

$W = \begin{vmatrix} e^{-x} & e^x & e^{2x} \\ -e^{-x} & e^x & 2e^{2x} \\ e^{-x} & e^x & 4e^{2x} \end{vmatrix} \xrightarrow[\substack{R_2 \rightarrow R_2 \\ R_3 \rightarrow R_3}]{R_1 + R_2} \begin{vmatrix} e^{-x} & e^x & e^{2x} \\ 0 & 2e^x & 3e^{2x} \\ 0 & 0 & 3e^{2x} \end{vmatrix} = e^{-x} \begin{vmatrix} 2e^x & 3e^{2x} \\ 0 & 3e^{2x} \end{vmatrix} = 6e^{2x}$

$W_1 = \begin{vmatrix} 0 & e^x & e^{2x} \\ 0 & e^x & 2e^{2x} \\ e^{3x} & e^x & 4e^{2x} \end{vmatrix} = e^{3x} \begin{vmatrix} e^x & e^{2x} \\ e^x & 2e^{2x} \end{vmatrix} = e^{6x}$

$W_2 = \begin{vmatrix} e^{-x} & 0 & e^{2x} \\ -e^{-x} & 0 & 2e^{2x} \\ e^{-x} & e^{3x} & 4e^{2x} \end{vmatrix} = -e^{3x} \begin{vmatrix} e^{-x} & e^{2x} \\ -e^{-x} & 2e^{2x} \end{vmatrix} = -3e^{4x}$

! position (-1) $\begin{matrix} 3 \cdot 2 \\ 3+2 = -1 \end{matrix}$

$W_3 = \begin{vmatrix} e^{-x} & e^x & 0 \\ -e^{-x} & e^x & 0 \\ e^{-x} & e^x & e^{3x} \end{vmatrix} = e^{3x} \begin{vmatrix} e^{-x} & e^x \\ -e^{-x} & e^x \end{vmatrix} = 2e^{3x}$

③ $u_1' = \frac{e^{6x}}{6e^{2x}} = \frac{1}{6} e^{4x} \Rightarrow u_1 = \frac{1}{24} e^{4x}$

$u_2' = \frac{-3e^{4x}}{6e^{2x}} = -\frac{1}{2} e^{2x} \Rightarrow u_2 = -\frac{1}{4} e^{2x}$

$u_3' = \frac{2e^{3x}}{6e^{2x}} = \frac{1}{3} e^x \Rightarrow u_3 = \frac{1}{3} e^x$

④ $y_p = \left(\frac{1}{24} e^{4x}\right) e^{-x} + \left(-\frac{1}{4} e^{2x}\right) e^x + \left(\frac{1}{3} e^x\right) e^{2x} = \frac{1}{8} e^{3x} \quad y_p = \frac{1}{8} e^{3x}$

⑤ $y = c_1 e^{-x} + c_2 e^x + c_3 e^{2x} + \frac{1}{8} e^{3x}$

4.3 Cauchy-Euler Equation

$$ax^2y'' + bxy' + cy = 0$$

Solve on $(0, \infty)$

• Characteristic Equation:

$$am^2 + (b-a)m + c = 0$$

• 3 Cases:

① 2 distinct real roots m_1, m_2 :

$$y = C_1 X^{m_1} + C_2 X^{m_2}$$

② 1 repeated real root m_1 :

$$y = C_1 X^{m_1} + C_2 X^{m_1} \ln X$$

③ 2 complex roots $\alpha \pm i\beta$:

$$y = X^\alpha (C_1 \cos(\beta \ln X) + C_2 \sin(\beta \ln X))$$

Why?

Solve $ax^2y'' + bxy' + cy = 0$ on $(0, \infty)$.

Substitution: $x = e^t$, or $\ln x = t$

$$\Rightarrow \frac{dy}{dx} = \frac{dy}{dt} \frac{dt}{dx} = \frac{1}{x} \frac{dy}{dt}$$

$$\begin{aligned} \Rightarrow \frac{d^2y}{dx^2} &= \frac{d}{dx} \left(\frac{1}{x} \frac{dy}{dt} \right) \\ &= -\frac{1}{x^2} \frac{dy}{dt} + \frac{d}{dx} \frac{dy}{dt} \cdot \frac{1}{x} \\ &= -\frac{1}{x^2} \frac{dy}{dt} + \frac{d^2y}{dt^2} \cdot \frac{dt}{dx} \cdot \frac{1}{x} \\ &= \frac{1}{x^2} \left(\frac{d^2y}{dt^2} - \frac{dy}{dt} \right) \end{aligned}$$

$$ax^2 \cdot \frac{1}{x^2} \left(\frac{d^2y}{dt^2} - \frac{dy}{dt} \right) + bx \cdot \left(\frac{1}{x} \frac{dy}{dt} \right) + cy = 0$$

$$a \frac{d^2y}{dt^2} - a \frac{dy}{dt} + b \cdot \frac{dy}{dt} + cy = 0$$

$$a \frac{d^2y}{dt^2} + (b-a) \frac{dy}{dt} + cy = 0 \quad \text{Constant coeff. w/ Char. eqn.}$$

$$am^2 + (b-a)m + c = 0$$

- 2 distinct real roots $m_1, m_2 \Rightarrow y = C_1 e^{m_1 t} + C_2 e^{m_2 t} = C_1 X^{m_1} + C_2 X^{m_2}$
($t = \ln X$)
- 1 repeated real root $m_1 \Rightarrow y = C_1 e^{m_1 t} + C_2 t e^{m_1 t} = C_1 X^{m_1} + C_2 X^{m_1} \ln X$.
- 2 complex roots $\alpha \pm i\beta \Rightarrow y = e^{\alpha t} (C_1 \cos(\beta t) + C_2 \sin(\beta t))$
 $= X^\alpha (C_1 \cos(\beta \ln X) + C_2 \sin(\beta \ln X))$.