

Diagonalizable Matrices

Diagonalizable matrices and their exponential

Objectives

To better understand matrix functions, exponentials, and solutions of linear differential system.

Solutions to Recitation Worksheet Problems: Sections 5.4, 5.5, 5.6

(1) (1a)

$$0 = \begin{vmatrix} (2-\lambda) & 4 \\ 1 & (-1-\lambda) \end{vmatrix} = (2-\lambda)(-1-\lambda) - 4 = \lambda^2 - \lambda - 6$$

$$\lambda_{\pm} = \frac{1}{2}(1 \pm \sqrt{1+24}) = \frac{1}{2}(1 \pm 5) = \begin{cases} \lambda_+ = 3 \\ \lambda_- = -2. \end{cases}$$

For $\lambda_+ = 3$ we get

$$(A - 3I)\mathbf{v} = \mathbf{0} \Rightarrow \begin{bmatrix} -1 & 4 \\ 1 & -4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow v_1 = 4v_2 \Rightarrow \mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 4v_2 \\ v_2 \end{bmatrix} = v_2 \begin{bmatrix} 4 \\ 1 \end{bmatrix}$$

So first eigenpair: $\lambda_+ = 3$, $\mathbf{v}_+ = \begin{bmatrix} 4 \\ 1 \end{bmatrix}$

For $\lambda_- = -2$ we get

$$(A + 2I)\mathbf{v} = \mathbf{0} \Rightarrow \begin{bmatrix} 4 & 4 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow v_1 = -v_2 \Rightarrow \mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} -v_2 \\ v_2 \end{bmatrix} = v_2 \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

So second eigenpair: $\lambda_- = -2$, $\mathbf{v}_- = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$

Therefore, we can write

$$A = PDP^{-1}, \quad P = \begin{bmatrix} 4 & -1 \\ 1 & 1 \end{bmatrix}, \quad D = \begin{bmatrix} 3 & 0 \\ 0 & -2 \end{bmatrix}, \quad P^{-1} = \frac{1}{5} \begin{bmatrix} 1 & 1 \\ -1 & 4 \end{bmatrix},$$

Since $At = P(Dt)P^{-1}$, then

$$e^{At} = P(e^{Dt})P^{-1} = \begin{bmatrix} 4 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} e^{3t} & 0 \\ 0 & e^{-2t} \end{bmatrix} \frac{1}{5} \begin{bmatrix} 1 & 1 \\ -1 & 4 \end{bmatrix},$$

$$e^{At} = \frac{1}{5} \begin{bmatrix} 4e^{3t} & -e^{-2t} \\ e^{3t} & e^{-2t} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & 4 \end{bmatrix}$$

$$e^{At} = \frac{1}{5} \begin{bmatrix} (4e^{3t} + e^{-2t}) & (4e^{3t} - 4e^{-2t}) \\ (e^{3t} - e^{-2t}) & (e^{3t} + 4e^{-2t}) \end{bmatrix}.$$

(1b) Short Version of the Proof:

$$\begin{aligned}(e^{At})' &= (Pe^{Dt}P^{-1})' = P(e^{Dt})'P^{-1} = Pe^{Dt}DP^{-1} = Pe^{Dt}P^{-1}PDP^{-1} = e^{At}A. \\ &= PDe^{Dt}P^{-1} = PDP^{-1}Pe^{Dt}P^{-1} = Ae^{At}.\end{aligned}$$

Long Version of the Proof:

$$\begin{aligned}(e^{At})' &= \frac{1}{5} \begin{bmatrix} (12e^{3t} - 2e^{-2t}) & (12e^{3t} + 8e^{-2t}) \\ (3e^{3t} + 2e^{-2t}) & (3e^{3t} - 8e^{-2t}) \end{bmatrix} \\ e^{At}A &= \frac{1}{5} \begin{bmatrix} (4e^{3t} + e^{-2t}) & (4e^{3t} - 4e^{-2t}) \\ (e^{3t} - e^{-2t}) & (e^{3t} + 4e^{-2t}) \end{bmatrix} \begin{bmatrix} 2 & 4 \\ 1 & -1 \end{bmatrix} \\ &= \frac{1}{5} \begin{bmatrix} ((8+4)e^{3t} + (2-4)e^{-2t}) & ((16-4)e^{3t} + (4+4)e^{-2t}) \\ ((2+1)e^{3t} + (-2+4)e^{-2t}) & ((4-1)e^{3t} + (-4-4)e^{-2t}) \end{bmatrix} \\ &= \frac{1}{5} \begin{bmatrix} (12e^{3t} - 2e^{-2t}) & (12e^{3t} + 8e^{-2t}) \\ (3e^{3t} + 2e^{-2t}) & (3e^{3t} - 8e^{-2t}) \end{bmatrix} \\ &= (e^{At})'.\end{aligned}$$

We leave Ae^{At} as exercise.

(2) Eigenpairs:

$$\lambda = 2, \quad \mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \quad \text{and} \quad \lambda = 3, \quad \mathbf{v}_3 = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}.$$

- (3)**
- Matrix A is diagonalizable with $D_A = \begin{bmatrix} 5 & 0 \\ 0 & -5 \end{bmatrix}$ and $P_A = \begin{bmatrix} 1 & 3 \\ 2 & 1 \end{bmatrix}$.
 - Matrix B is not diagonalizable, because it has only one eigenvalue $\lambda = 3$ and the corresponding set of eigenvectors is only a line in the direction of $\mathbf{v} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$.
 - If matrix C is a function on real vectors only, then C is not diagonalizable, since it does not have any real eigenvalues.
 - If matrix C is a function on complex vectors, then C is diagonalizable with $D_C = \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix}$ and $P_C = \begin{bmatrix} 1 & 1 \\ i & -i \end{bmatrix}$.

(4) Extra Problem from Section 6.1:**(4a)**

$$\mathbf{x}(t) = c_1 \begin{bmatrix} 4 \\ 1 \end{bmatrix} e^{3t} + c_2 \begin{bmatrix} -1 \\ 1 \end{bmatrix} e^{-2t}, \quad c_1, c_2 \in \mathbb{R}.$$

(4b)

$$\mathbf{x}(t) = \frac{2}{5} \begin{bmatrix} 4 \\ 1 \end{bmatrix} e^{3t} + \frac{3}{5} \begin{bmatrix} -1 \\ 1 \end{bmatrix} e^{-2t} \iff \mathbf{x}(t) = e^{At}\mathbf{x}(0) = \frac{1}{5} \begin{bmatrix} (4e^{3t} + e^{-2t}) & (4e^{3t} - 4e^{-2t}) \\ (e^{3t} - e^{-2t}) & (e^{3t} + 4e^{-2t}) \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$