# Section Objective(s):

- The Dirac's Delta.
- Main Properties.
- Applications.
- The Impulse Response Function.

### 4.4.1. The Dirac Delta.

**Definition 4.4.1.** The *Dirac delta* generalized function is the limit

for every fixed  $t \in \mathbb{R}$  of the sequence functions  $\{\delta_n\}_{n=1}^{\infty}$ ,

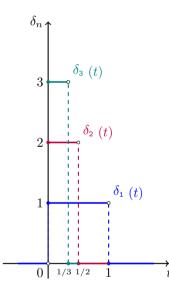
Remark: The sequence of bump functions introduced above can be rewritten as follows,

$$\delta_n(t) = \begin{cases} \underline{\hspace{1cm}}, & t < 0 \\ \underline{\hspace{1cm}}, & 0 \leqslant t < \frac{1}{n} \\ \underline{\hspace{1cm}}, & t \geqslant \frac{1}{n}. \end{cases}$$

We then obtain the equivalent expression,

$$\delta(t) = \begin{cases} \underline{\phantom{a}} & \text{for } t \neq 0, \\ \underline{\phantom{a}} & \text{for } t = 0. \end{cases}$$

**Remark:** There are infinitely many sequences  $\{\delta_n\}$  of functions with the Dirac delta as their limit as  $n \to \infty$ .



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#### Remarks:

- (a) The Dirac delta is \_\_\_\_\_ on the domain .
- (b) The Dirac delta is \_\_\_\_\_ on \_\_\_\_.

**Theorem**. Every function in the sequence  $\{\delta_n\}$  above satisfies

## 4.4.2. Main Properties.

Remark: We use \_\_\_\_\_\_ to define operations on Dirac's deltas.

**Definition 4.4.2.** We introduce the following operations on the Dirac delta:

$$f(t) \, \delta(t-c) + g(t) \, \delta(t-c) = \underline{\hspace{2cm}}.$$

$$\int_{a}^{b} \delta(t-c) dt = \underline{\hspace{2cm}}$$

$$\mathcal{L}[\delta(t-c)] = \underline{\hspace{1cm}}.$$

**Theorem 4.4.3.** For every  $c \in \mathbb{R}$  and  $\epsilon > 0$  holds,

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Proof of Theorem 4.4.3:

**Theorem 4.4.4.** If f is continuous on (a,b) and  $c \in (a,b)$ , then

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Proof of Theorem 4.4.4:

**Theorem 4.4.5.** For all  $s \in \mathbb{R}$  holds

$$\mathcal{L}[\delta(t-c)] = \begin{cases} -c & \text{for } c \ge 0, \\ & \text{for } c < 0. \end{cases}$$

Proof of Theorem 4.4.5:

# 4.4.3. Applications of the Dirac Delta.

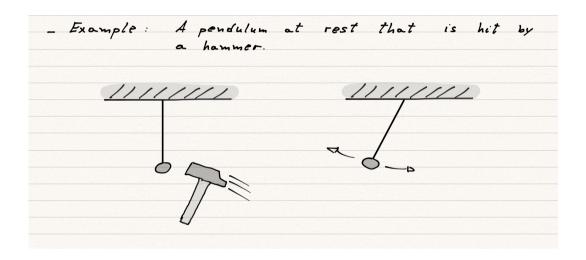
#### Remarks:

(a) Dirac's delta generalized function is useful to describe

(b) An impulsive force transfers a \_\_\_\_\_

in an

(c) For example, a pendulum at rest that is hit by a hammer.



EXAMPLE 4.4.3: Use Newton's equation of motion and Dirac's delta to describe the change of momentum when a particle is hit by a hammer.

SOLUTION:

## 4.4.4. The Impulse Response Function.

<b>Definition 4.4.6.</b> The <i>impulse response function</i> at the point $c \ge 0$ of the linear operator			
with $a_1$ , $a_0$ constan	ats, is the solution $y_{\delta}$ of		
	,	,	· · ·

**Theorem 4.4.7.** The function  $y_{\delta}$  is the impulse response function at  $c \ge 0$  of the constant coefficients operator  $L(y) = y'' + a_1 y' + a_0 y$  iff holds

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where

of L.

**Remark:** The impulse response function  $y_{\delta}$  at c=0 satisfies

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Proof of Theorem 4.4.7:

Example Similar to 4.4.6: Find the solution y to the initial value problem  $y''-y=\delta(t-3), \qquad y(0)=0, \qquad y'(0)=0.$ 

SOLUTION: