

On linear and non-linear equations. (Sect. 1.6).

- ▶ Review: Linear differential equations.
- ▶ Non-linear differential equations.
- ▶ Properties of solutions to non-linear ODE.
- ▶ Direction Fields.

Review: Linear differential equations.

Theorem (Variable coefficients)

Given continuous functions $a, b : (t_1, t_2) \rightarrow \mathbb{R}$, with $t_2 > t_1$, and given constants $t_0 \in (t_1, t_2)$, $y_0 \in \mathbb{R}$, the IVP

$$y' = -a(t)y + b(t), \quad y(t_0) = y_0,$$

has the unique solution $y : (t_1, t_2) \rightarrow \mathbb{R}$ given by

$$y(t) = \frac{1}{\mu(t)} \left[y_0 + \int_{t_0}^t \mu(s) b(s) ds \right], \quad (1)$$

where the integrating factor function is given by

$$\mu(t) = e^{A(t)}, \quad A(t) = \int_{t_0}^t a(s) ds.$$

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Proof: Based on the integration factor method.

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 - (c) For every initial condition $y_0 \in \mathbb{R}$ the corresponding solution $y(t)$ of a linear IVP is defined for all $t \in (t_1, t_2)$.
- ▶ None of these properties holds for solutions to non-linear differential equations.

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- ▶ **Non-linear differential equations.**
- ▶ Properties of solutions to non-linear ODE.
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Non-linear differential equations.

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An ordinary differential equation $y'(t) = f(t, y(t))$ is called *non-linear* iff the function $(t, u) \mapsto f(t, u)$ is non-linear in the second argument.

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Properties of solutions to non-linear ODE.

Theorem (Non-linear ODE)

Fix a non-empty rectangle $R = (t_1, t_2) \times (u_1, u_2) \subset \mathbb{R}^2$ and fix a function $f : R \rightarrow \mathbb{R}$ denoted as $(t, u) \mapsto f(t, u)$. If the functions f and $\partial_u f$ are continuous on R , and $(t_0, y_0) \in R$, then there exists a smaller open rectangle $\hat{R} \subset R$ with $(t_0, y_0) \in \hat{R}$ such that the IVP

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Remarks:

- (i) There is no general explicit expression for the solution $y(t)$ to a non-linear ODE.

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- (ii) Non-uniqueness of solution to the IVP above may happen at points $(t, u) \in \mathbb{R}^2$ where $\partial_u f$ is not continuous.
- (iii) Changing the initial data y_0 may change the domain on the variable t where the solution $y(t)$ is defined.

Properties of solutions to non-linear ODE.

Example

Given non-zero constants a_1, a_2, a_3, a_4 , find every solution y of

$$y' = \frac{t^2}{(y^4 + a_4 y^3 + a_3 y^2 + a_2 y + a_1)}.$$

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Introduce the substitution $u = y(t)$, so $du = y'(t) dt$,

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Integrate, and in the result substitute back the function y :

$$\frac{1}{5} y^5(t) + \frac{a_4}{4} y^4(t) + \frac{a_3}{3} y^3(t) + \frac{a_2}{2} y^2(t) + a_1 y(t) = \frac{t^3}{3} + c.$$

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There is **no explicit expression** for solutions y of the ODE.



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$$y_1(t) = 0.$$

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Solution: This is a separable equation.

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Find the solution y to the initial value problem

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The solution domain depends on the values of the initial data y_0 . ◀

Properties of solutions to non-linear ODE.

Summary:

- ▶ Linear ODE:
 - (a) There is an explicit expression for the solution of a linear IVP.
 - (b) For every initial condition $y_0 \in \mathbb{R}$ there exists a unique solution to a linear IVP.
 - (c) The domain of the solution of a linear IVP is defined for every initial condition $y_0 \in \mathbb{R}$.

- ▶ Non-linear ODE:
 - (i) There is no general explicit expression for the solution $y(t)$ to a non-linear ODE.
 - (ii) Non-uniqueness of solution to a non-linear IVP may happen at points $(t, u) \in \mathbb{R}^2$ where $\partial_u f$ is not continuous.
 - (iii) Changing the initial data y_0 may change the domain on the variable t where the solution $y(t)$ is defined.

On linear and non-linear equations. (Sect. 1.6).

- ▶ Review: Linear differential equations.
- ▶ Non-linear differential equations.
- ▶ Properties of solutions to non-linear ODE.
- ▶ **Direction Fields.**

Direction Fields.

Remarks:

- ▶ One does not need to solve a differential equation $y'(t) = f(t, y(t))$ to have a qualitative idea of the solution.

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Definition

A *Direction Field* for the differential equation $y'(t) = f(t, y(t))$ is the graph on the yt -plane of the values $f(t, y)$ as slopes of a small segments.

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We know that the solution of $y' = y$ are the exponentials $y(t) = y_0 e^t$.

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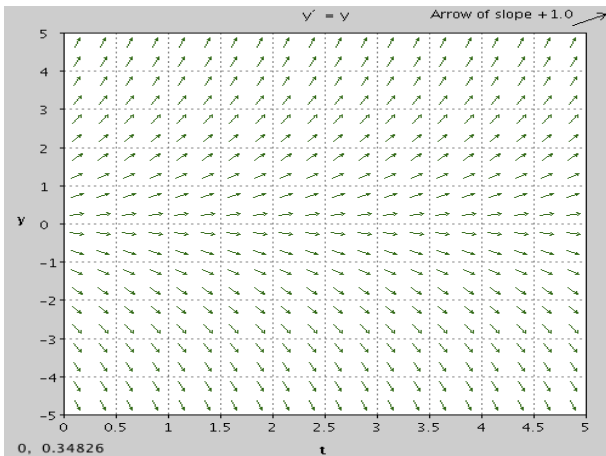
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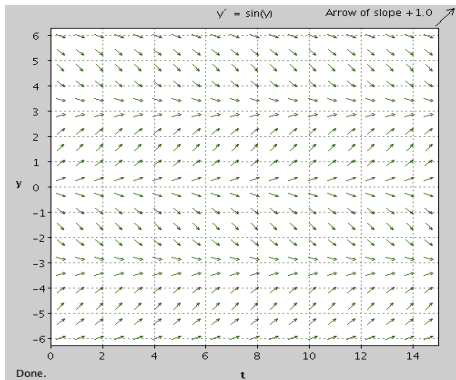
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