

Non-homogeneous equations (Sect. 2.6).

- ▶ We study: $y'' + a_1 y' + a_0 y = b(t)$.
- ▶ Review and preliminary results.
- ▶ Summary of the undetermined coefficients method.
- ▶ Using the method in few examples.
- ▶ The guessing solution table.

Review and preliminary results.

Operator notation: The differential equation

$$y'' + p(t)y' + q(t)y = f(t)$$

will be written as $L(y) = f$, with

$$L(y) = y'' + p(t)y' + q(t)y.$$

The homogeneous equation is $L(y) = 0$.

Remark: The operator L is a linear function of y .

Theorem

For every continuously differentiable functions y_1, y_2 and every constants c_1, c_2 holds that

$$L(c_1 y_1 + c_2 y_2) = c_1 L(y_1) + c_2 L(y_2).$$

Review and preliminary results.

Theorem

Let $L(y) = y'' + p(t)y' + q(t)y$. with p and q given functions. If y_1 and y_2 are fundamental solutions of

$$L(y) = 0,$$

and y_p is any solution of the non-homogeneous equation

$$L(y_p) = f, \quad (1)$$

for a given source f , then any other solution y of the non-homogeneous equation above is given by

$$y(t) = c_1 y_1(t) + c_2 y_2(t) + y_p(t), \quad (2)$$

where $c_1, c_2 \in \mathbb{R}$.

Notation: The expression for y in Eq. (2) is called the **general solution** of the non-homogeneous Eq. (1).

Review and preliminary results.

Theorem

The function $y_p = y_{p_1} + \cdots + y_{p_n}$ is a particular solution to

$$L(y_p) = f$$

where $L(y) = y'' + p(t)y' + q(t)y$ is a linear operator and

$$f(t) = f_1(t) + \cdots + f_n(t),$$

and each function y_{p_1}, \cdots, y_{p_n} , is a solution of the equation

$$L(y_{p_i}) = f_i. \quad \text{with } i = 1, \cdots, n.$$

Non-homogeneous equations (Sect. 2.6).

- ▶ We study: $y'' + a_1 y' + a_0 y = b(t)$.
- ▶ Operator notation and preliminary results.
- ▶ **Summary of the undetermined coefficients method.**
- ▶ Using the method in few examples.
- ▶ The guessing solution table.

Summary of the undetermined coefficients method.

Problem: Given a constant coefficients linear operator $L(y) = y'' + a_1 y' + a_0 y$, with $a_1, a_2 \in \mathbb{R}$, find every solution of the non-homogeneous differential equation

$$L(y) = f.$$

Remarks:

- ▶ The undetermined coefficients is a method to find solutions to linear, non-homogeneous, constant coefficients, differential equations.
- ▶ It consists in **guessing** the solution y_p of the non-homogeneous equation

$$L(y_p) = f,$$

for particularly simple source functions f .

Summary of the undetermined coefficients method.

Summary:

- (1) Find the general solution of the homogeneous equation $L(y_h) = 0$.
- (2) If f has the form $f = f_1 + \cdots + f_n$, with $n \geq 1$, then look for solutions y_{p_i} , with $i = 1, \dots, n$ to the equations

$$L(y_{p_i}) = f_i.$$

Once the functions y_{p_i} are found, then construct

$$y_p = y_{p_1} + \cdots + y_{p_n}.$$

- (3) Given the source functions f_i , guess the solutions functions y_{p_i} following the [Table](#) below.

Summary of the undetermined coefficients method.

Summary (cont.):

$f_i(t)$ (K, m, a, b , given.)	$y_{p_i}(t)$ (Guess) (k not given.)
Ke^{at}	ke^{at}
Kt^m	$k_m t^m + k_{m-1} t^{m-1} + \cdots + k_0$
$K \cos(bt)$	$k_1 \cos(bt) + k_2 \sin(bt)$
$K \sin(bt)$	$k_1 \cos(bt) + k_2 \sin(bt)$
$Kt^m e^{at}$	$e^{at}(k_m t^m + \cdots + k_0)$
$Ke^{at} \cos(bt)$	$e^{at}[k_1 \cos(bt) + k_2 \sin(bt)]$
$Ke^{at} \sin(bt)$	$e^{at}[k_1 \cos(bt) + k_2 \sin(bt)]$
$Kt^m \cos(bt)$	$(k_m t^m + \cdots + k_0)[a_1 \cos(bt) + a_2 \sin(bt)]$
$Kt^m \sin(bt)$	$(k_m t^m + \cdots + k_0)[a_1 \cos(bt) + a_2 \sin(bt)]$

Summary of the undetermined coefficients method.

Summary (cont.):

- (4) If any guessed function y_{p_i} satisfies the homogeneous equation $L(y_{p_i}) = 0$, then change the guess to the function

$$t^s y_{p_i}, \quad \text{with } s \geq 1,$$

and s sufficiently large such that $L(t^s y_{p_i}) \neq 0$.

- (5) Impose the equation $L(y_{p_i}) = f_i$ to find the undetermined constants k_1, \dots, k_m , for the appropriate m , given in the table above.

- (6) The general solution to the original differential equation $L(y) = f$ is then given by

$$y(t) = y_h(t) + y_{p_1} + \dots + y_{p_n}.$$

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Using the method in few examples.

Example

Find all solutions to the non-homogeneous equation

$$y'' - 3y' - 4y = 3e^{2t}.$$

Solution: Notice: $L(y) = y'' - 3y' - 4y$ and $f(t) = 3e^{2t}$.

(1) Find all solutions y_h to the homogeneous equation $L(y_h) = 0$.

The characteristic equation is

$$r^2 - 3r - 4 = 0 \quad \Rightarrow \quad \begin{cases} r_1 = 4, \\ r_2 = -1. \end{cases}$$

$$y_h(t) = c_1 e^{4t} + c_2 e^{-t}.$$

(2) Trivial in our case. The source function $f(t) = 3e^{2t}$ cannot be simplified into a sum of simpler functions.

(3) Table says: For $f(t) = 3e^{2t}$ guess $y_p(t) = k e^{2t}$

Using the method in few examples.

Example

Find all solutions to the non-homogeneous equation

$$y'' - 3y' - 4y = 3e^{2t}.$$

Solution: Recall: $y_p(t) = k e^{2t}$. We need to find k .

(4) Trivial here, since $L(y_p) \neq 0$, we do not modify our guess.

(Recall: $L(y_h) = 0$ iff $y_h(t) = c_1 e^{4t} + c_2 e^{-t}$.)

(5) Introduce y_p into $L(y_p) = f$ and find k .

$$(2^2 - 6 - 4)ke^{2t} = 3e^{2t} \quad \Rightarrow \quad -6k = 3 \quad \Rightarrow \quad k = -\frac{1}{2}.$$

We have obtained that $y_p(t) = -\frac{1}{2} e^{2t}$.

(6) The general solution to the inhomogeneous equation is

$$y(t) = c_1 e^{4t} + c_2 e^{-t} - \frac{1}{2} e^{2t}.$$

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Using the method in few examples.

Example

Find all solutions to the non-homogeneous equation

$$y'' - 3y' - 4y = 3e^{4t}.$$

Solution: We know that the general solution to homogeneous equation is $y_h(t) = c_1 e^{4t} + c_2 e^{-t}$.

Following the table we guess y_p as $y_p = k e^{4t}$.

However, this guess satisfies $L(y_p) = 0$.

So we modify the guess to $y_p = kt e^{4t}$.

Introduce the guess into $L(y_p) = f$. We need to compute

$$y'_p = k e^{4t} + 4kt e^{4t}, \quad y''_p = 8k e^{4t} + 16kt e^{4t}.$$

Using the method in few examples.

Example

Find all solutions to the non-homogeneous equation

$$y'' - 3y' - 4y = 3e^{4t}.$$

Solution: Recall:

$$y_p = kt e^{4t}, \quad y'_p = k e^{4t} + 4kt e^{4t}, \quad y''_p = 8k e^{4t} + 16kt e^{4t}.$$

$$[(8k + 16kt) - 3(k + 4kt) - 4kt] e^{4t} = 3e^{4t}.$$

$$[(8 + 16t) - 3(1 + 4t) - 4t] k = 3 \quad \Rightarrow \quad [5 + (16 - 12 - 4)t] k = 3$$

We obtain that $k = \frac{3}{5}$. Therefore, $y_p(t) = \frac{3}{5} t e^{4t}$, and

$$y(t) = c_1 e^{4t} + c_2 e^{-t} + \frac{3}{5} t e^{4t}.$$

◁

Using the method in few examples.

Example

Find all the solutions to the inhomogeneous equation

$$y'' - 3y' - 4y = 2 \sin(t).$$

Solution: We know that the general solution to homogeneous equation is $y(t) = c_1 e^{4t} + c_2 e^{-t}$.

Following the table: Since $f = 2 \sin(t)$, then we guess

$$y_p = k_1 \sin(t) + k_2 \cos(t).$$

This guess satisfies $L(y_p) \neq 0$.

Compute: $y'_p = k_1 \cos(t) - k_2 \sin(t)$, $y''_p = -k_1 \sin(t) - k_2 \cos(t)$.

$$\begin{aligned} L(y_p) &= [-k_1 \sin(t) - k_2 \cos(t)] - 3[k_1 \cos(t) - k_2 \sin(t)] \\ &\quad - 4[k_1 \sin(t) + k_2 \cos(t)] = 2 \sin(t), \end{aligned}$$

Using the method in few examples.

Example

Find all the solutions to the inhomogeneous equation

$$y'' - 3y' - 4y = 2 \sin(t).$$

Solution: Recall:

$$\begin{aligned} L(y_p) &= [-k_1 \sin(t) - k_2 \cos(t)] - 3[k_1 \cos(t) - k_2 \sin(t)] \\ &\quad - 4[k_1 \sin(t) + k_2 \cos(t)] = 2 \sin(t), \end{aligned}$$

$$(-5k_1 + 3k_2) \sin(t) + (-3k_1 - 5k_2) \cos(t) = 2 \sin(t).$$

This equation holds for all $t \in \mathbb{R}$. In particular, at $t = \frac{\pi}{2}$, $t = 0$.

$$\left. \begin{aligned} -5k_1 + 3k_2 &= 2, \\ -3k_1 - 5k_2 &= 0, \end{aligned} \right\} \Rightarrow \begin{cases} k_1 = -\frac{5}{17}, \\ k_2 = \frac{3}{17}. \end{cases}$$

Using the method in few examples.

Example

Find all the solutions to the inhomogeneous equation

$$y'' - 3y' - 4y = 2 \sin(t).$$

Solution: Recall: $k_1 = -\frac{5}{17}$ and $k_2 = \frac{3}{17}$.

So the particular solution to the inhomogeneous equation is

$$y_p(t) = \frac{1}{17} [-5 \sin(t) + 3 \cos(t)].$$

The general solution is

$$y(t) = c_1 e^{4t} + c_2 e^{-t} + \frac{1}{17} [-5 \sin(t) + 3 \cos(t)]. \quad \triangleleft$$

Using the method in few examples.

Example

Find all the solutions to the inhomogeneous equation

$$y'' - 3y' - 4y = 3e^{2t} + 2 \sin(t).$$

Solution: We know that the general solution y is given by

$$y(t) = y_h(t) + y_{p_1}(t) + y_{p_2}(t),$$

where $y_h(t) = c_1 e^{4t} + c_2 e^{2t}$, $L(y_{p_1}) = 3e^{2t}$, and $L(y_{p_2}) = 2 \sin(t)$.

We have just found out that

$$y_p(t) = -\frac{1}{2} e^{2t}, \quad y_{p_2}(t) = \frac{1}{17} [-5 \sin(t) + 3 \cos(t)].$$

We conclude that

$$y(t) = c_1 e^{4t} + c_2 e^{2t} - \frac{1}{2} e^{2t} + \frac{1}{17} [-5 \sin(t) + 3 \cos(t)]. \quad \triangleleft$$

Using the method in few examples.

Example

- ▶ For $y'' - 3y' - 4y = 3e^{2t} \sin(t)$, guess

$$y_p(t) = [k_1 \sin(t) + k_2 \cos(t)] e^{2t}.$$

- ▶ For $y'' - 3y' - 4y = 2t^2 e^{3t}$, guess

$$y_p(t) = (k_0 + k_1 t + k_2 t^2) e^{3t}.$$

- ▶ For $y'' - 3y' - 4y = 3t \sin(t)$, guess

$$y_p(t) = (1 + k_1 t) [k_2 \sin(t) + k_3 \cos(t)].$$

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The guessing solution table.

Guessing Solution Table.

$f_i(t)$ (K, m, a, b , given.)	$y_{p_i}(t)$ (Guess) (k not given.)
Ke^{at}	ke^{at}
Kt^m	$k_m t^m + k_{m-1} t^{m-1} + \dots + k_0$
$K \cos(bt)$	$k_1 \cos(bt) + k_2 \sin(bt)$
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