# Sine and Cosine Series (Sect. 10.4).

- Even, odd functions.
- ▶ Main properties of even, odd functions.
- Sine and cosine series.
- Even-periodic, odd-periodic extensions of functions.

#### Definition

A function  $f:[-L,L]\to\mathbb{R}$  is even iff for all  $x\in[-L,L]$  holds

$$f(-x)=f(x).$$

A function  $f:[-L,L] \to \mathbb{R}$  is *odd* iff for all  $x \in [-L,L]$  holds

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#### Remarks:

- ▶ The only function that is both odd and even is f = 0.
- Most functions are neither odd nor even.

Example

Show that the function  $f(x) = x^2$  is even on [-L, L].

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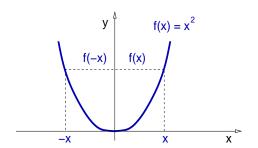
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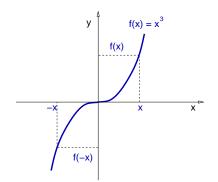
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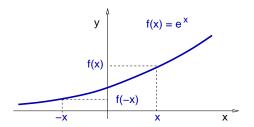
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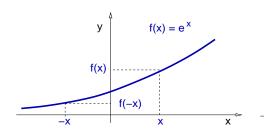
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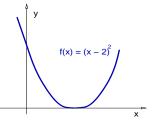
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#### Theorem

- (1) A linear combination of even (odd) functions is even (odd).
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Case "odd" is similar.

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Cases (3), (4) are similar.



### **Theorem**

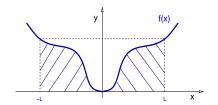
If 
$$f: [-L, L] \to \mathbb{R}$$
 is even, then  $\int_{-L}^{L} f(x) dx = 2 \int_{0}^{L} f(x) dx$ .

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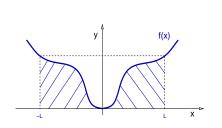
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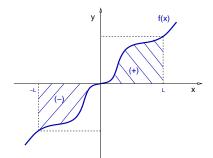


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## Theorem (Cosine and Sine Series)

Consider the function  $f:[-L,L] \to \mathbb{R}$  with Fourier expansion

$$f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} \left[ a_n \cos\left(\frac{n\pi x}{L}\right) + b_n \sin\left(\frac{n\pi x}{L}\right) \right].$$

(1) If f is even, then  $b_n = 0$  for  $n = 1, 2, \dots$ , and the Fourier series

$$f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos\left(\frac{n\pi x}{L}\right)$$

is called a Cosine Series.

(2) If f is odd, then  $a_n = 0$  for  $n = 0, 1, \dots$ , and the Fourier series

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A function  $f:[0,L]\to\mathbb{R}$  can be extended as an even function  $f:[-L,L]\to\mathbb{R}$  requiring for  $x\in[0,L]$  that

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This function  $f:[-L,L]\to\mathbb{R}$  can be further extended as a periodic function  $f:\mathbb{R}\to\mathbb{R}$  requiring for  $x\in[-L,L]$  that

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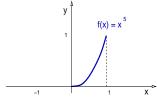
Example

Sketch the graph of the even-periodic extension of  $f(x) = x^5$ , with  $x \in [0,1]$ .

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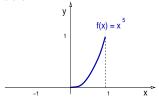
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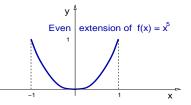


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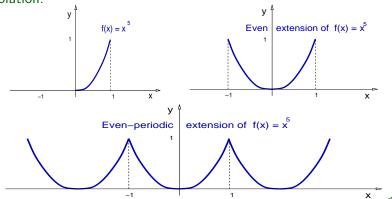




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## (2) Odd-periodic case:

A function  $f:(0,L)\to\mathbb{R}$  can be extended as an odd function  $f:(-L,L)\to\mathbb{R}$  requiring for  $x\in(0,L)$  that

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This function  $f:(-L,L)\to\mathbb{R}$  can be further extended as a periodic function  $f:\mathbb{R}\to\mathbb{R}$  requiring for  $x\in(-L,L)$  and n integer that

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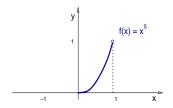
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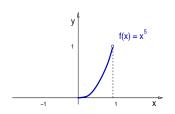
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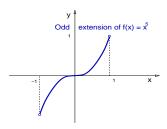
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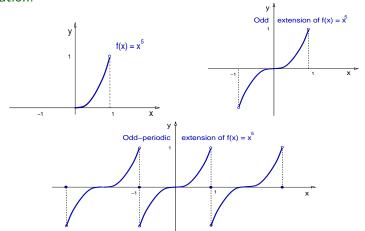
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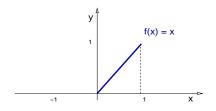
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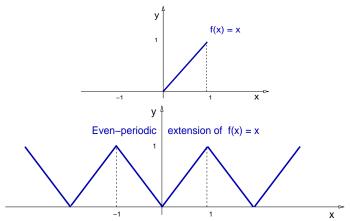
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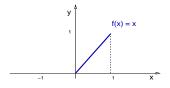
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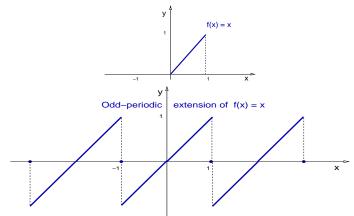
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# Solving the Heat Equation (Sect. 10.5).

- ▶ Review: The Stationary Heat Equation.
- ► The Heat Equation.
- ► The Initial-Boundary Value Problem.
- ▶ The separation of variables method.
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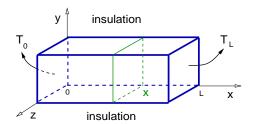
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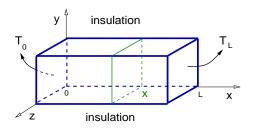
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Remark: The heat transfer occurs only along the x-axis.



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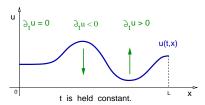
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The IBVP for the one-dimensional Heat Equation is the following: Given a constant k>0 and a function  $f:[0,L]\to\mathbb{R}$  with f(0)=f(L)=0, find  $u:[0,\infty)\times[0,L]\to\mathbb{R}$  solution of

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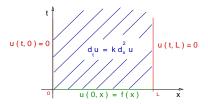
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▶ We have transformed the original PDE into infinitely many ODEs parametrized by *n*, positive integer.

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The real-valued general solution is

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We conclude that: 
$$u_n(t,x) = e^{-k(\frac{n\pi}{L})^2 t} \sin(\frac{n\pi x}{L}), n = 1, 2, \cdots$$

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$$\int_0^L \sin\left(\frac{n\pi x}{L}\right) \sin\left(\frac{m\pi x}{L}\right) dx = \begin{cases} 0, & m \neq n, \\ \frac{L}{2}, & m = n. \end{cases}$$

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Summary: IBVP for the Heat Equation.

Propose:

$$u(t,x) = \sum_{n=1}^{\infty} c_n v_n(t) w_n(x).$$

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#### Remark:

The separation of variables method does not work for every PDE.

# Solving the Heat Equation (Sect. 10.5).

- Review: The Stationary Heat Equation.
- ► The Heat Equation.
- ► The Initial-Boundary Value Problem.
- ▶ The separation of variables method.
- ► An example of separation of variables.

Example

Find the solution to the IBVP 
$$4\partial_t u=\partial_x^2 u,\quad t>0,\quad x\in[0,2],$$
 
$$u(0,x)=3\sin(\pi x/2),\quad u(t,0)=0,\quad u(t,2)=0.$$

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$$4\partial_t u = \partial_x^2 u$$
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Solution: We conclude that

$$u(t,x) = 3 e^{-(\frac{\pi}{4})^2 t} \sin(\frac{\pi x}{2}).$$

#### Review Exam 4.

- Sections 7.1-7.6, 7.8, 10.1-10.5.
- ▶ 5 or 6 problems.
- 50 minutes.
  - Overview of linear differential systems (7.1).
  - Review of Linear Algebra (7.2,7.3).
  - ▶ Basic Theorey of first order systems (7.4).
  - ► Homogeneous constant coefficients systems:
    - ▶ Real and different eigenvalues (7.5).
    - Complex eigenvalues (7.6).
    - Real and repeated eigenvalues (7.8).

Example

$$\mathbf{x}'(t) = A\mathbf{x}(t), \qquad A = \begin{bmatrix} 1 & 2 \\ -2 & 1 \end{bmatrix}.$$

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Find the real-valued general solution of

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Eigenvector for  $\lambda_+$ .

$$(A - \lambda_{+}I) = \begin{bmatrix} 1 - (1+2i) & 2 \\ -2 & 1 - (1+2i) \end{bmatrix}$$

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Find the real-valued general sol.  $\mathbf{x}'(t) = A\mathbf{x}(t), A = \begin{bmatrix} 1 & 2 \\ -2 & 1 \end{bmatrix}$ .

Solution: Recall: 
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 Hence  $\lambda_+ = -1$ ,

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General solution: 
$$\mathbf{x} = c_1 \begin{bmatrix} \sqrt{2} \\ 2 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} -\sqrt{2} \\ 1 \end{bmatrix} e^{-4t}$$
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#### Example

Plot the phase portrait of several linear combinations of the fundamental solutions found above,

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#### Solution:

We start plotting the vectors

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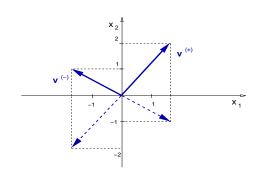
$$\mathbf{x}^{(+)} = egin{bmatrix} \sqrt{2} \\ 2 \end{bmatrix} \, e^{-t}, \quad \mathbf{x}^{(-)} = egin{bmatrix} -\sqrt{2} \\ 1 \end{bmatrix} \, e^{-4t}.$$

#### Solution:

We start plotting the vectors

$$\mathbf{v}^{(+)} = \begin{bmatrix} \sqrt{2} \\ 2 \end{bmatrix},$$

$$\mathbf{v}^{(-)} = \begin{bmatrix} -\sqrt{2} \\ 1 \end{bmatrix}$$
 .



#### Example

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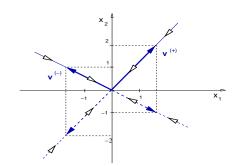
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#### Solution:

Recall:  $\lambda_- < \lambda_+ < 0$ . We plot the solutions

$$\mathbf{x} = \mathbf{x}^{(+)} + \mathbf{x}^{(-)},$$

that is,

$$\mathbf{x} = \mathbf{v}^{(+)} e^{-t} + \mathbf{v}^{(-)} e^{-4t}$$
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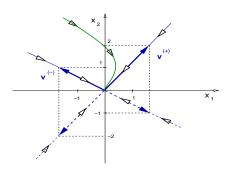
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$$\mathbf{x} = c_1 \, \mathbf{x}^{(+)} + c_2 \, \mathbf{x}^{(-)},$$

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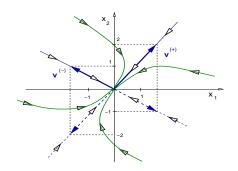
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## Example

Let 
$$\lambda_+ = 4$$
,  $\lambda_- = 1$ ,  $\mathbf{v}^{(+)} = \begin{bmatrix} \sqrt{2} \\ 2 \end{bmatrix}$ , and  $\mathbf{v}^{(-)} = \begin{bmatrix} -\sqrt{2} \\ 1 \end{bmatrix}$ .

Plot the phase portrait of several linear combinations of the fundamental solutions  $\mathbf{x}^{(+)} = v^{(+)} e^{\lambda_+ t}$ ,  $\mathbf{x}^{(-)} = v^{(-)} e^{\lambda_- t}$ ,

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Solution:

Here  $\lambda_+ > \lambda_- > 0$ . We plot the solutions

$$x^{(+)}, -x^{(+)},$$
 $x^{(-)}, -x^{(-)}.$ 

Example

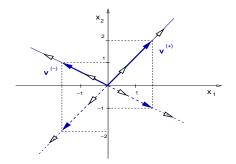
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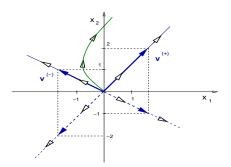
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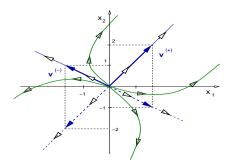
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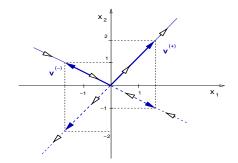
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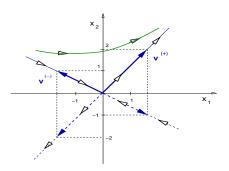
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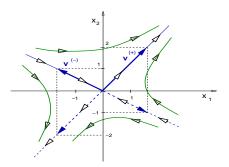
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Example

Find x solution of the IVP

$$\mathbf{x}' = A\mathbf{x}, \qquad \mathbf{x}(0) = \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \qquad A = \begin{bmatrix} -3 & 4 \\ -1 & 1 \end{bmatrix}.$$

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Solution: Eigenvalues of A:

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$$v_1 = 2 v_2$$
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$$v_1=2\,v_2$$
. Choosing  $v_1=2$  and  $v_2=1$ , we get  $\mathbf{v}^{(+)}=\begin{bmatrix}2\\1\end{bmatrix}$ .

### Example

$$\mathbf{x}' = A\mathbf{x}, \qquad \mathbf{x}(0) = \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \qquad A = \begin{bmatrix} -3 & 4 \\ -1 & 1 \end{bmatrix}.$$

Solution: Recall: 
$$\lambda_{\pm}=-1$$
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$$\begin{bmatrix} -2 & 4 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix} \implies \begin{bmatrix} -2 & 4 & 2 \\ -1 & 2 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

### Example

Find x solution of the IVP

$$\mathbf{x}' = A\mathbf{x}, \qquad \mathbf{x}(0) = \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \qquad A = \begin{bmatrix} -3 & 4 \\ -1 & 1 \end{bmatrix}.$$

Solution: Recall:  $\lambda_{\pm} = -1$ , and  $\mathbf{v}^{(+)} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ .

Find **w** solution of (A + I)**w** = **v**.

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$$w_1 = 2w_2 - 1$$
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Choose 
$$w_2 = 0$$
, so  $\mathbf{w} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$ .

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General sol: 
$$\mathbf{x} = c_1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{-t} + c_2 \left( \begin{bmatrix} 2 \\ 1 \end{bmatrix} t + \begin{bmatrix} -1 \\ 0 \end{bmatrix} \right) e^{-t}$$
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#### Example

$$\mathbf{x}' = A \mathbf{x}, \qquad \mathbf{x}(0) = \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \qquad A = \begin{bmatrix} -3 & 4 \\ -1 & 1 \end{bmatrix}.$$

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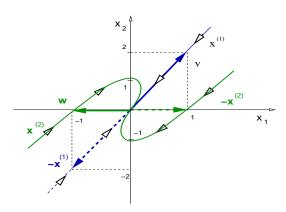
The solution is 
$$\mathbf{x} = 3 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{-t} + 5 \left( \begin{bmatrix} 2 \\ 1 \end{bmatrix} t + \begin{bmatrix} -1 \\ 0 \end{bmatrix} \right) e^{-t}$$
.

Example

Let 
$$\lambda = -1$$
 with  $\mathbf{v} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$  and  $\mathbf{w} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$ .  
Plot  $\pm \mathbf{x}^{(1)} = \pm \mathbf{v} \, e^{-t}$  and  $\pm \mathbf{x}^{(2)} = \pm (\mathbf{v} \, t + \mathbf{w}) \, e^{-t}$ .

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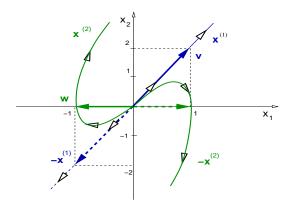
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#### Example

Given any vectors  ${\boldsymbol a}$  and  ${\boldsymbol b}$ , sketch qualitative phase portraits of

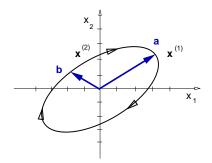
$$\mathbf{x}^{(1)} = \left[\mathbf{a} \, \cos(\beta t) - \mathbf{b} \, \sin(\beta t)\right] e^{\alpha t}, \, \mathbf{x}^{(2)} = \left[\mathbf{a} \, \sin(\beta t) + \mathbf{b} \, \cos(\beta t)\right] e^{\alpha t}.$$

for the cases  $\alpha=$  0, and  $\alpha>$  0, where  $\beta>$  0.

#### Example

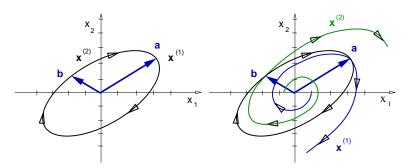
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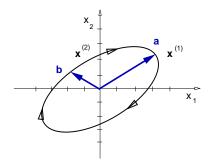
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