# Non-homogeneous equations (Sect. 3.5).

- ► We study:  $y'' + a_1 y' + a_0 y = b(t)$ .
- ▶ Operator notation and preliminary results.
- ▶ Summary of the undetermined coefficients method.
- Using the method in few examples.
- ► The guessing solution table.

# Operator notation and preliminary results.

Notation: Given functions p, q, denote

$$L(y) = y'' + p(t)y' + q(t)y.$$

Therefore, the differential equation

$$y'' + p(t)y' + q(t)y = f(t)$$

can be written as

$$L(y) = f$$
.

The homogeneous equation can be written as

$$L(y)=0.$$

The function L acting on a function y is called an operator.

### Operator notation and preliminary results.

Remark: The operator L is a linear function of y.

#### **Theorem**

For every continuously differentiable functions  $y_1$ ,  $y_2$ :  $(t_1, t_2) \to \mathbb{R}$  and every  $c_1$ ,  $c_2 \in \mathbb{R}$  holds that

$$L(c_1y_1+c_2y_2)=c_1L(y_1)+c_2L(y_2).$$

Proof:

$$L(c_1y_1 + c_2y_2) = (c_1y_1 + c_2y_2)'' + p(t)(c_1y_1 + c_2y_2)' + q(t)(c_1y_1 + c_2y_2)$$

$$L(c_1y_1 + c_2y_2) = (c_1y_1'' + p(t)c_1y_1' + q(t)c_1y_1)$$

$$+ (c_2y_2'' + p(t)c_2y_2' + q(t)c_2y_2)$$

$$L(c_1y_1 + c_2y_2) = c_1L(y_1) + c_2L(y_2).$$

### Operator notation and preliminary results.

#### **Theorem**

Given functions p, q, f, let L(y) = y'' + p(t)y' + q(t)y. If the functions  $y_1$  and  $y_2$  are fundamental solutions of the homogeneous equation

$$L(y)=0,$$

and  $y_p$  is any solution of the non-homogeneous equation

$$L(y_p) = f, (1)$$

then any other solution y of the non-homogeneous equation above is given by

$$y(t) = c_1 y_1(t) + c_2 y_2(t) + y_p(t),$$
 (2)

where  $c_1$ ,  $c_2 \in \mathbb{R}$ .

Notation: The expression for y in Eq. (2) is called the general solution of the non-homogeneous Eq. (1).

# Operator notation and preliminary results.

#### Theorem

Given functions p, q, let L(y) = y'' + p(t)y' + q(t)y. If the function f can be written as  $f(t) = f_1(t) + \cdots + f_n(t)$ , with  $n \ge 1$ , and if there exist functions  $y_{p_1}, \cdots, y_{p_n}$  such that

$$L(y_{p_i}) = f_i, \qquad i = 1, \cdots, n,$$

then the function  $y_p = y_{p_1} + \cdots + y_{p_n}$  satisfies the non-homogeneous equation

$$L(y_p)=f$$
.

# Non-homogeneous equations (Sect. 3.5).

- We study:  $y'' + a_1 y' + a_0 y = b(t)$ .
- ▶ Operator notation and preliminary results.
- **▶** Summary of the undetermined coefficients method.
- Using the method in few examples.
- ► The guessing solution table.

# Summary of the undetermined coefficients method.

Problem: Given a constant coefficients linear operator  $L(y)=y''+a_1y'+a_0y$ , with  $a_1,\ a_2\in\mathbb{R}$ , find every solution of the non-homogeneous differential equation

$$L(y) = f$$
.

#### Remarks:

- ► The undetermined coefficients is a method to find solutions to linear, non-homogeneous, constant coefficients, differential equations.
- ▶ It consists in guessing the solution  $y_p$  of the non-homogeneous equation

$$L(y_p) = f$$
,

for particularly simple source functions f.

# Summary of the undetermined coefficients method.

#### Summary:

- (1) Find the general solution of the homogeneous equation  $L(y_h) = 0$ .
- (2) If f has the form  $f = f_1 + \cdots + f_n$ , with  $n \ge 1$ , then look for solutions  $y_{p_i}$ , with  $i = 1, \dots, n$  to the equations

$$L(y_{p_i}) = f_i$$
.

Once the functions  $y_{p_i}$  are found, then construct

$$y_p=y_{p_1}+\cdots+y_{p_n}.$$

(3) Given the source functions  $f_i$ , guess the solutions functions  $y_{p_i}$  following the Table below.

# Summary of the undetermined coefficients method.

#### Summary (cont.):

$f_i(t)$ (K, m, a, b, given.)	$y_{p_i}(t)$ (Guess) (k not given.)
Ke <sup>at</sup>	ke <sup>at</sup>
Kt <sup>m</sup>	$k_m t^m + k_{m-1} t^{m-1} + \cdots + k_0$
$K\cos(bt)$	$k_1\cos(bt)+k_2\sin(bt)$
K sin(bt)	$k_1\cos(bt)+k_2\sin(bt)$
Kt <sup>m</sup> e <sup>at</sup>	$e^{at}(k_mt^m+\cdots+k_0)$
$Ke^{at}\cos(bt)$	$e^{at}\big[k_1\cos(bt)+k_2\sin(bt)\big]$
$KKe^{at}\sin(bt)$	$e^{at}\big[k_1\cos(bt)+k_2\sin(bt)\big]$
$Kt^m \cos(bt)$	$(k_m t^m + \cdots + k_0) [a_1 \cos(bt) + a_2 \sin(bt)]$
$Kt^m \sin(bt)$	$(k_m t^m + \cdots + k_0) [a_1 \cos(bt) + a_2 \sin(bt)]$

# Summary of the undetermined coefficients method.

### Summary (cont.):

(4) If any guessed function  $y_{p_i}$  satisfies the homogeneous equation  $L(y_{p_i}) = 0$ , then change the guess to the function

$$t^s y_{p_i}$$
, with  $s \geqslant 1$ ,

and s sufficiently large such that  $L(t^s y_{p_i}) \neq 0$ .

- (5) Impose the equation  $L(y_{p_i}) = f_i$  to find the undetermined constants  $k_1, \dots, k_m$ , for the appropriate m, given in the table above.
- (6) The general solution to the original differential equation L(y) = f is then given by

$$y(t) = y_h(t) + y_{p_1} + \cdots + y_{p_n}.$$

# Non-homogeneous equations (Sect. 3.5).

- ▶ We study:  $y'' + a_1 y' + a_0 y = b(t)$ .
- ▶ Operator notation and preliminary results.
- ▶ Summary of the undetermined coefficients method.
- **▶** Using the method in few examples.
- ▶ The guessing solution table.

# Using the method in few examples.

Example

Find all solutions to the non-homogeneous equation

$$y'' - 3y' - 4y = 3e^{2t}.$$

Solution: Notice: L(y) = y'' - 3y' - 4y and  $f(t) = 3e^{2t}$ .

(1) Find all solutions  $y_h$  to the homogeneous equation  $L(y_h) = 0$ . The characteristic equation is

$$r^2 - 3r - 4 = 0 \quad \Rightarrow \quad \begin{cases} r_1 = 4, \\ r_2 = -1. \end{cases}$$

$$y_h(t) = c_1 e^{4t} + c_2 e^{-t}$$
.

- (2) Trivial in our case. The source function  $f(t) = 3e^{2t}$  cannot be simplified into a sum of simpler functions.
- (3) Table says: For  $f(t) = 3e^{2t}$  guess  $y_p(t) = k e^{2t}$

#### Example

Find all solutions to the non-homogeneous equation

$$y'' - 3y' - 4y = 3e^{2t}.$$

Solution: Recall:  $y_p(t) = k e^{2t}$ . We need to find k.

(4) Trivial here, since  $L(y_p) \neq 0$ , we do not modify our guess.

(Recall:  $L(y_h) = 0$  iff  $y_h(t) = c_1 e^{4t} + c_2 e^{-t}$ .)

(5) Introduce  $y_p$  into  $L(y_p) = f$  and find k.

$$(2^2 - 6 - 4)ke^{2t} = 3e^{2t} \Rightarrow -6k = 3 \Rightarrow k = -\frac{1}{2}.$$

We have obtained that  $y_p(t) = -\frac{1}{2} e^{2t}$ .

(6) The general solution to the inhomogeneous equation is

$$y(t) = c_1 e^{4t} + c_2 e^{-t} - \frac{1}{2} e^{2t}.$$

# Using the method in few examples.

#### Example

Find all solutions to the non-homogeneous equation

$$y'' - 3y' - 4y = 3e^{4t}.$$

Solution: We know that the general solution to homogeneous equation is  $y_h(t) = c_1 e^{4t} + c_2 e^{-t}$ .

Following the table we guess  $y_p$  as  $y_p = k e^{4t}$ .

However, this guess satisfies  $L(y_p) = 0$ .

So we modify the guess to  $y_p = kt e^{4t}$ .

Introduce the guess into  $L(y_p) = f$ . We need to compute

$$y_p' = k e^{4t} + 4kt e^{4t}, \qquad y_p'' = 8k e^{4t} + 16kt e^{4t}.$$

Example

Find all solutions to the non-homogeneous equation

$$y'' - 3y' - 4y = 3e^{4t}.$$

Solution: Recall:

$$y_p = kt e^{4t}, \quad y_p' = k e^{4t} + 4kt e^{4t}, \quad y_p'' = 8k e^{4t} + 16kt e^{4t}.$$

$$\left[ (8k + 16kt) - 3(k + 4kt) - 4kt \right] e^{4t} = 3e^{4t}.$$

$$\left[ (8 + 16t) - 3(1 + 4t) - 4t \right] k = 3 \quad \Rightarrow \quad \left[ 5 + (16 - 12 - 4) t \right] k = 3$$

We obtain that  $k=\frac{3}{5}$ . Therefore,  $y_p(t)=\frac{3}{5}\,t\,e^{4t}$ , and

$$y(t) = c_1 e^{4t} + c_2 e^{-t} + \frac{3}{5} t e^{4t}.$$

### Using the method in few examples.

Example

Find all the solutions to the inhomogeneous equation

$$y'' - 3y' - 4y = 2\sin(t).$$

Solution: We know that the general solution to homogeneous equation is  $y(t) = c_1 e^{4t} + c_2 e^{-t}$ .

Following the table: Since  $f = 2\sin(t)$ , then we guess

$$y_p = k_1 \sin(t) + k_2 \cos(t).$$

This guess satisfies  $L(y_p) \neq 0$ .

Compute:  $y_p' = k_1 \cos(t) - k_2 \sin(t)$ ,  $y_p'' = -k_1 \sin(t) - k_2 \cos(t)$ .

$$L(y_p) = [-k_1 \sin(t) - k_2 \cos(t)] - 3[k_1 \cos(t) - k_2 \sin(t)]$$
$$-4[k_1 \sin(t) + k_2 \cos(t)] = 2\sin(t),$$

Example

Find all the solutions to the inhomogeneous equation

$$y'' - 3y' - 4y = 2\sin(t).$$

Solution: Recall:

$$L(y_p) = [-k_1 \sin(t) - k_2 \cos(t)] - 3[k_1 \cos(t) - k_2 \sin(t)]$$
$$-4[k_1 \sin(t) + k_2 \cos(t)] = 2\sin(t),$$

$$(-5k_1+3k_2)\sin(t)+(-3k_1-5k_2)\cos(t)=2\sin(t).$$

This equation holds for all  $t \in \mathbb{R}$ . In particular, at  $t = \frac{\pi}{2}$ , t = 0.

$$\begin{cases}
-5k_1 + 3k_2 = 2, \\
-3k_1 - 5k_2 = 0,
\end{cases} \Rightarrow \begin{cases}
k_1 = -\frac{5}{17}, \\
k_2 = \frac{3}{17}.
\end{cases}$$

# Using the method in few examples.

Example

Find all the solutions to the inhomogeneous equation

$$y'' - 3y' - 4y = 2\sin(t).$$

Solution: Recall:  $k_1 = -\frac{5}{17}$  and  $k_2 = \frac{3}{17}$ .

So the particular solution to the inhomogeneous equation is

$$y_p(t) = \frac{1}{17} \left[ -5\sin(t) + 3\cos(t) \right].$$

The general solution is

$$y(t) = c_1 e^{4t} + c_2 e^{-t} + \frac{1}{17} \left[ -5\sin(t) + 3\cos(t) \right].$$

Example

Find all the solutions to the inhomogeneous equation

$$y'' - 3y' - 4y = 3e^{2t} + 2\sin(t).$$

Solution: We know that the general solution y is given by

$$y(t) = y_h(t) + y_{p_1}(t) + y_{p_2}(t),$$

where  $y_h(t)=c_1e^{4t}+c_2e^{2t}$ ,  $L(y_{p_1})=3e^{2t}$ , and  $L(y_{p_2})=2\sin(t)$ . We have just found out that

$$y_p(t) = -\frac{1}{2}e^{2t}, \qquad y_{p_2}(t) = \frac{1}{17}\left[-5\sin(t) + 3\cos(t)\right].$$

We conclude that

$$y(t) = c_1 e^{4t} + c_2 e^{2t} - \frac{1}{2} e^{2t} + \frac{1}{17} \left[ -5\sin(t) + 3\cos(t) \right].$$

# Using the method in few examples.

Example

► For 
$$y'' - 3y' - 4y = 3e^{2t}\sin(t)$$
, guess  $y_p(t) = [k_1\sin(t) + k_2\cos(t)]e^{2t}$ .

For 
$$y'' - 3y' - 4y = 2t^2 e^{3t}$$
, guess 
$$y_p(t) = (k_0 + k_1 t + k_2 t^2) e^{3t}.$$

► For 
$$y'' - 3y' - 4y = 3t \sin(t)$$
, guess  
$$y_p(t) = (1 + k_1 t) [k_2 \sin(t) + k_3 \cos(t)].$$

# Non-homogeneous equations (Sect. 3.5).

- We study:  $y'' + a_1 y' + a_0 y = b(t)$ .
- ▶ Operator notation and preliminary results.
- ▶ Summary of the undetermined coefficients method.
- ▶ Using the method in few examples.
- ► The guessing solution table.

# The guessing solution table.

### Guessing Solution Table.

$f_i(t)$ (K, m, a, b, given.)	$y_{p_i}(t)$ (Guess) (k not given.)
Ke <sup>at</sup>	ke <sup>at</sup>
Kt <sup>m</sup>	$k_m t^m + k_{m-1} t^{m-1} + \cdots + k_0$
$K\cos(bt)$	$k_1\cos(bt)+k_2\sin(bt)$
$K\sin(bt)$	$k_1\cos(bt)+k_2\sin(bt)$
Kt <sup>m</sup> e <sup>at</sup>	$e^{at}(k_mt^m+\cdots+k_0)$
$Ke^{at}\cos(bt)$	$e^{at}\big[k_1\cos(bt)+k_2\sin(bt)\big]$
$KKe^{at}\sin(bt)$	$e^{at}\big[k_1\cos(bt)+k_2\sin(bt)\big]$
$Kt^m \cos(bt)$	$(k_m t^m + \cdots + k_0) [a_1 \cos(bt) + a_2 \sin(bt)]$
$Kt^m \sin(bt)$	$(k_m t^m + \cdots + k_0) [a_1 \cos(bt) + a_2 \sin(bt)]$