## On linear and non-linear equations.(Sect. 2.4).

- Review: Linear differential equations.
- Non-linear differential equations.
- Properties of solutions to non-linear ODE.
- The Bernoulli equation.


## Review: Linear differential equations.

Theorem (Variable coefficients)
Given continuous functions $a, b:\left(t_{1}, t_{2}\right) \rightarrow \mathbb{R}$, with $t_{2}>t_{1}$, and given constants $t_{0} \in\left(t_{1}, t_{2}\right), y_{0} \in \mathbb{R}$, the $I V P$

$$
y^{\prime}=-a(t) y+b(t), \quad y\left(t_{0}\right)=y_{0}
$$

has the unique solution $y:\left(t_{1}, t_{2}\right) \rightarrow \mathbb{R}$ given by

$$
\begin{equation*}
y(t)=\frac{1}{\mu(t)}\left[y_{0}+\int_{t_{0}}^{t} \mu(s) b(s) d s\right], \tag{1}
\end{equation*}
$$

where the integrating factor function is given by

$$
\mu(t)=e^{A(t)}, \quad A(t)=\int_{t_{0}}^{t} a(s) d s
$$

Proof: Based on the integration factor method.

## Review: Linear differential equations.

## Remarks:

- The Theorem above assumes that the coefficients $a, b$, are continuous in $\left(t_{1}, t_{2}\right) \subset \mathbb{R}$.
- The Theorem above implies:
(a) There is an explicit expression for the solutions of a linear IVP, given in Eq. (1).
(b) For every initial condition $y_{0} \in \mathbb{R}$ there exists a unique solution to a linear IVP.
(c) For every initial condition $y_{0} \in \mathbb{R}$ the corresponding solution $y(t)$ of a linear IVP is defined for all $t \in\left(t_{1}, t_{2}\right)$.
- None of these properties holds for solutions to non-linear differential equations.


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## Non-linear differential equations.

## Definition

An ordinary differential equation $y^{\prime}(t)=f(t, y(t))$ is called non-linear iff the function $(t, u) \mapsto f(t, u)$ is non-linear in the second argument.

## Example

(a) The differential equation $y^{\prime}(t)=\frac{t^{2}}{y^{3}(t)}$ is non-linear, since the function $f(t, u)=t^{2} / u^{3}$ is non-linear in the second argument.
(b) The differential equation $y^{\prime}(t)=2 \operatorname{ty}(t)+\ln (y(t))$ is non-linear, since the function $f(t, u)=2 t u+\ln (u)$ is non-linear in the second argument, due to the term $\ln (u)$.
(c) The differential equation $\frac{y^{\prime}(t)}{y(t)}=2 t^{2}$ is linear, since the function $f(t, u)=2 t^{2} u$ is linear in the second argument.

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## Properties of solutions to non-linear ODE.

## Theorem (Non-linear ODE)

Fix a non-empty rectangle $R=\left(t_{1}, t_{2}\right) \times\left(u_{1}, u_{2}\right) \subset \mathbb{R}^{2}$ and fix a function $f: R \rightarrow \mathbb{R}$ denoted as $(t, u) \mapsto f(t, u)$. If the functions $f$ and $\partial_{u} f$ are continuous on $R$, and $\left(t_{0}, y_{0}\right) \in R$, then there exists a smaller open rectangle $\hat{R} \subset R$ with $\left(t_{0}, y_{0}\right) \in \hat{R}$ such that the IVP

$$
y^{\prime}(t)=f(t, y(t)), \quad y\left(t_{0}\right)=y_{0}
$$

has a unique solution $y$ on the set $\hat{R} \subset \mathbb{R}^{2}$.
Remarks:
(i) There is no general explicit expression for the solution $y(t)$ to a non-linear ODE.
(ii) Non-uniqueness of solution to the IVP above may happen at points $(t, u) \in \mathbb{R}^{2}$ where $\partial_{u} f$ is not continuous.
(iii) Changing the initial data $y_{0}$ may change the domain on the variable $t$ where the solution $y(t)$ is defined.

## Properties of solutions to non-linear ODE.

## Example

Given non-zero constants $a_{1}, a_{2}, a_{3}, a_{4}$, find every solution $y$ of

$$
y^{\prime}=\frac{t^{2}}{\left(y^{4}+a_{4} y^{3}+a_{3} y^{2}+a_{2} y+a_{1}\right)} .
$$

Solution: The ODE is separable. So first, rewrite the equation as

$$
\left(y^{4}+a_{4} y^{3}+a_{3} y^{2}+a_{2} y+a_{1}\right) y^{\prime}=t^{2}
$$

then we integrate in $t$ on both sides of the equation,

$$
\int\left(y^{4}+a_{4} y^{3}+a_{3} y^{2}+a_{2} y+a_{1}\right) y^{\prime} d t=\int t^{2} d t+c
$$

Introduce the substitution $u=y(t)$, so $d u=y^{\prime}(t) d t$,

$$
\int\left(u^{4}+a_{4} u^{3}+a_{3} u^{2}+a_{2} u+a_{1}\right) d u=\int t^{2} d t+c
$$

## Properties of solutions to non-linear ODE.

## Example

Given non-zero constants $a_{1}, a_{2}, a_{3}, a_{4}$, find every solution $y$ of

$$
y^{\prime}=\frac{t^{2}}{\left(y^{4}+a_{4} y^{3}+a_{3} y^{2}+a_{2} y+a_{1}\right)} .
$$

Solution:
Recall: $\int\left(u^{4}+a_{4} u^{3}+a_{3} u^{2}+a_{2} u+a_{1}\right) d u=\int t^{2} d t+c$.
Integrate, and in the result substitute back the function $y$ :

$$
\frac{1}{5} y^{5}(t)+\frac{a_{4}}{4} y^{4}(t)+\frac{a_{3}}{3} y^{3}(t)+\frac{a_{2}}{2} y^{2}(t)+a_{1} y(t)=\frac{t^{3}}{3}+c
$$

The solution is in implicit form. It is the root of a polynomial degree five. There is no formula for the roots of a general polynomial degree five or bigger.
There is no explicit expression for solutions $y$ of the ODE.

## Properties of solutions to non-linear ODE.

## Example

Find every solution $y$ of the initial value problem

$$
y^{\prime}(t)=y^{1 / 3}(t), \quad y(0)=0
$$

Remark: The equation above is non-linear, separable, and the function $f(t, u)=u^{1 / 3}$ has derivative

$$
\partial_{u} f=\frac{1}{3} \frac{1}{u^{2 / 3}},
$$

so $\partial_{u} f$ is not continuous at $u=0$.
The initial condition above is precisely where $f$ is not continuous.
Solution: There are two solutions to the IVP above:
The first solution is

$$
y_{1}(t)=0 .
$$

## Properties of solutions to non-linear ODE.

## Example

Find every solution $y$ of the initial value problem

$$
y^{\prime}(t)=y^{1 / 3}(t), \quad y(0)=0
$$

Solution: The second solution is obtained as follows:

$$
\int[y(t)]^{-1 / 3} y^{\prime}(t) d t=\int d t+c
$$

Then, the substitution $u=y(t)$, with $d u=y^{\prime}(t) d t$, implies that

$$
\begin{gathered}
\int u^{-1 / 3} d u=\int d t+c \Rightarrow \frac{3}{2}[y(t)]^{2 / 3}=t+c \\
y(t)=\left[\frac{2}{3}(t+c)\right]^{3 / 2} \Rightarrow 0=y(0)=\left(\frac{2}{3} c\right)^{3 / 2} \Rightarrow c=0 .
\end{gathered}
$$

So, the second solution is: $y_{2}(t)=\left(\frac{2}{3} t\right)^{3 / 2}$. Recall $y_{1}(t)=0 . \quad \triangleleft$

## Properties of solutions to non-linear ODE.

## Example

Find the solution $y$ to the initial value problem

$$
y^{\prime}(t)=y^{2}(t), \quad y(0)=y_{0}
$$

Solution: This is a separable equation. So,

$$
\int \frac{y^{\prime} d t}{y^{2}}=\int d t+c \quad \Rightarrow \quad-\frac{1}{y}=t+c \quad \Rightarrow \quad y(t)=-\frac{1}{t+c}
$$

Using the initial condition in the expression above,

$$
y_{0}=y(0)=-\frac{1}{c} \Rightarrow c=-\frac{1}{y_{0}} \Rightarrow y(t)=\frac{1}{\left(\frac{1}{y_{0}}-t\right)} .
$$

This solution diverges at $t=1 / y_{0}$, so its domain is $\mathbb{R}-\left\{y_{0}\right\}$.
The solution domain depends on the values of the initial data $y_{0} . \triangleleft$

## Properties of solutions to non-linear ODE.

## Summary:

- Linear ODE:
(a) There is an explicit expression for the solution of a linear IVP.
(b) For every initial condition $y_{0} \in \mathbb{R}$ there exists a unique solution to a linear IVP.
(c) The domain of the solution of a linear IVP is defined for every initial condition $y_{0} \in \mathbb{R}$.
- Non-linear ODE:
(i) There is no general explicit expression for the solution $y(t)$ to a non-linear ODE.
(ii) Non-uniqueness of solution to a non-linear IVP may happen at points $(t, u) \in \mathbb{R}^{2}$ where $\partial_{u} f$ is not continuous.
(iii) Changing the initial data $y_{0}$ may change the domain on the variable $t$ where the solution $y(t)$ is defined.


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## The Bernoulli equation.

Remark: The Bernoulli equation is a non-linear differential equation that can be transformed into a linear differential equation.

## Definition

Given functions $p, q: \mathbb{R} \rightarrow \mathbb{R}$ and a real number $n$, the differential equation in the unknown function $y: \mathbb{R} \rightarrow \mathbb{R}$ given by

$$
y^{\prime}+p(t) y=q(t) y^{n}
$$

is called the Bernoulli equation.

## Theorem

The function $y: \mathbb{R} \rightarrow \mathbb{R}$ is a solution of the Bernoulli equation for

$$
y^{\prime}+p(t) y=q(t) y^{n}, \quad n \neq 1
$$

iff the function $v=1 / y^{(n-1)}$ is solution of the linear differential equation

$$
v^{\prime}-(n-1) p(t) v=-(n-1) q(t) .
$$

## The Bernoulli equation.

## Example

Given arbitrary constants $a_{0}$ and $b_{0}$, find every solution of the differential equation

$$
y^{\prime}=a_{0} y+b_{0} y^{3}
$$

Solution: This is a Bernoulli equation. Divide the equation by $y^{3}$,

$$
\frac{y^{\prime}}{y^{3}}=\frac{a_{0}}{y^{2}}+b_{0}
$$

Introduce the function $v=1 / y^{2}$, with derivative $v^{\prime}=-2\left(y^{\prime} / y^{3}\right)$, into the differential equation above,

$$
-\frac{v^{\prime}}{2}=a_{0} v+b_{0} \quad \Rightarrow \quad v^{\prime}=-2 a_{0} v-2 b_{0} \quad \Rightarrow \quad v^{\prime}+2 a_{0} v=-2 b_{0}
$$

## The Bernoulli equation.

## Example

Given arbitrary constants $a_{0}$ and $b_{0}$, find every solution of the differential equation

$$
y^{\prime}=a_{0} y+b_{0} y^{3}
$$

Solution: Recall: $v^{\prime}+2 a_{0} v=-2 b_{0}$.
The last equation is a linear differential equation for $v$. This equation can be solved using the integrating factor method. Multiply the equation by $\mu(t)=e^{2 a_{0} t}$,

$$
\left(e^{2 a_{0} t} v\right)^{\prime}=-2 b_{0} e^{2 a_{0} t} \quad \Rightarrow \quad e^{2 a_{0} t} v=-\frac{b_{0}}{a_{0}} e^{2 a_{0} t}+c
$$

We obtain that $v=c e^{-2 a_{0} t}-\frac{b_{0}}{a_{0}}$. Since $v=1 / y^{2}$,

$$
\frac{1}{y^{2}}=c e^{-2 a_{0} t}-\frac{b_{0}}{a_{0}} \Rightarrow y= \pm \frac{1}{\left(c e^{-2 a_{0} t}-\frac{b_{0}}{a_{0}}\right)^{1 / 2}}
$$

