Equations with regular-singular points (Sect. 5.5).

- Equations with regular-singular points.
- Examples: Equations with regular-singular points.

- Method to find solutions.
- Example: Method to find solutions.

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Recall:

The point $x_0 \in \mathbb{R}$ is a singular point of the equation

$$P(x) y'' + Q(x) y' + R(x) y = 0$$

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iff holds that $P(x_0) = 0$.

Definition A singular point $x_0 \in \mathbb{R}$ of the equation

$$P(x) y'' + Q(x) y' + R(x) y = 0$$

is called a regular-singular point iff the following limits are finite,

$$\lim_{x \to x_0} \frac{(x - x_0) Q(x)}{P(x)}, \qquad \lim_{x \to x_0} \frac{(x - x_0)^2 R(x)}{P(x)},$$

and both functions

$$\frac{(x-x_0) Q(x)}{P(x)}, \qquad \frac{(x-x_0)^2 R(x)}{P(x)},$$

admit convergent Taylor series expansions around x_0 .

Remark:

• If x_0 is a regular-singular point of

P(x) y'' + Q(x) y' + R(x) y = 0

and $P(x) \simeq (x - x_0)^n$ near x_0 , then near x_0 holds

 $Q(x) \simeq (x - x_0)^{n-1}, \quad R(x) \simeq (x - x_0)^{n-2}.$

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• The main example is an Euler equation, case n = 2,

$$(x-x_0)^2 y'' + p_0(x-x_0) y' + q_0 y = 0.$$

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Example

Show that the singular point of every Euler equation is a regular-singular point.

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Solution: Consider the general Euler equation

$$(x - x_0)^2 y'' + p_0(x - x_0) y' + q_0 y = 0,$$

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where p_0 , q_0 , x_0 , are real constants.

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$$P(x) = (x - x_0)^2,$$
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We conclude that x_0 is a regular-singular point.

Remark: Every equation Py'' + Qy' + Ry = 0 with a regular-singular point at x_0 is close to an Euler equation.

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and multiply it by $(x - x_0)^2$,

$$(x-x_0)^2 y'' + (x-x_0) \Big[\frac{(x-x_0)Q(x)}{P(x)} \Big] y' + \Big[\frac{(x-x_0)^2 R(x)}{P(x)} \Big] y = 0.$$

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The factors between [] approach constants, say p_0 , q_0 , as $x \to x_0$,

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Equations with regular-singular points (Sect. 5.5).

- Equations with regular-singular points.
- **•** Examples: Equations with regular-singular points.

- Method to find solutions.
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Example

Find the regular-singular points of the differential equation

$$(1 - x^2) y'' - 2x y' + \alpha(\alpha + 1) y = 0,$$

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where α is a real constant.

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$$0=P(x)=(1-x^2)$$

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Solution: Find the singular points of this equation,

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$$0 = P(x) = (1 - x^{2}) = (1 - x)(1 + x) \quad \Rightarrow \quad \begin{cases} x_{0} = 1, \\ x_{1} = -1. \end{cases}$$

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both functions above have Taylor series around $x_0 = 1$.

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$$(1 - x^2) y'' - 2x y' + \alpha(\alpha + 1) y = 0,$$

where α is a real constant.

Solution: Recall:

$$\frac{(x-1) Q(x)}{P(x)} = \frac{2x}{1+x}, \quad \frac{(x-1)^2 R(x)}{P(x)} = \frac{(x-1) [\alpha(\alpha+1)]}{1+x}.$$

Furthermore, the following limits are finite,

$$\lim_{x \to 1} \frac{(x-1) Q(x)}{P(x)} = 1, \qquad \lim_{x \to 1} \frac{(x-1)^2 R(x)}{P(x)}$$

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We conclude that $x_0 = 1$ is a regular-singular point.

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where α is a real constant.

Solution:

Case $x_1 = -1$:

$$\frac{(x+1) Q(x)}{P(x)} = \frac{(x+1)(-2x)}{(1-x)(1+x)}$$

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Both functions above have Taylor series $x_1 = -1$.

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Therefore, the point $x_1 = -1$ is a regular-singular point.

Find the regular-singular points of the differential equation

$$(x+2)^2(x-1)y''+3(x-1)y'+2y=0.$$

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Solution: Find the singular points:

Find the regular-singular points of the differential equation

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Solution: Find the singular points: $x_0 = -2$ and $x_1 = 1$.

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So $x_0 = -2$ is not a regular-singular point.

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Solution: Find the singular points: $x_0 = -2$ and $x_1 = 1$. Case $x_0 = -2$:

$$\lim_{x \to -2} \frac{(x+2)Q(x)}{P(x)} = \lim_{x \to -2} \frac{(x+2)3(x-1)}{(x+2)^2(x-1)} = \lim_{x \to -2} \frac{3}{(x+2)} = \pm \infty.$$

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So $x_0 = -2$ is not a regular-singular point. Case $x_1 = 1$:

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Find the regular-singular points of the differential equation

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Both functions have Taylor series around $x_1 = 1$.

Example

Find the regular-singular points of the differential equation

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Therefore, the point $x_1 = -1$ is a regular-singular point.

Example

Find the regular-singular points of the differential equation

$$x y'' - x \ln(|x|) y' + 3x y = 0.$$

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Solution: The singular point is $x_0 = 0$.

Example

Find the regular-singular points of the differential equation

$$x y'' - x \ln(|x|) y' + 3x y = 0.$$

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Solution: The singular point is $x_0 = 0$. We compute the limit

$$\lim_{x \to 0} \frac{xQ(x)}{P(x)}$$

Example

Find the regular-singular points of the differential equation

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Solution: The singular point is $x_0 = 0$. We compute the limit

$$\lim_{x \to 0} \frac{xQ(x)}{P(x)} = \lim_{x \to 0} \frac{x\left[-x\ln(|x|)\right]}{x}$$

Example

Find the regular-singular points of the differential equation

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Solution: The singular point is $x_0 = 0$. We compute the limit

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Use L'Hôpital's rule: $\lim_{x\to 0} \frac{xQ(x)}{P(x)}$

Example

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Find the regular-singular points of the differential equation

$$x y'' - x \ln(|x|) y' + 3x y = 0.$$

Solution: The singular point is $x_0 = 0$. We compute the limit

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L'Hôpital's rule:
$$\lim_{x \to 0} \frac{xQ(x)}{P(x)} = \lim_{x \to 0} -\frac{\frac{1}{x}}{-\frac{1}{x^2}}$$

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Use L'Hôpital's rule: $\lim_{x \to 0} \frac{xQ(x)}{P(x)} = \lim_{x \to 0} \frac{-\frac{1}{x}}{-\frac{1}{x^2}} = \lim_{x \to 0} x$

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Find the regular-singular points of the differential equation

$$x y'' - x \ln(|x|) y' + 3x y = 0.$$

Solution: The singular point is $x_0 = 0$. We compute the limit

$$\lim_{x \to 0} \frac{xQ(x)}{P(x)} = \lim_{x \to 0} \frac{x[-x\ln(|x|)]}{x} = \lim_{x \to 0} -\frac{\ln(|x|)}{\frac{1}{x}}.$$

Use L'Hôpital's rule: $\lim_{x \to 0} \frac{xQ(x)}{P(x)} = \lim_{x \to 0} \frac{-\frac{1}{x}}{-\frac{1}{x^2}} = \lim_{x \to 0} x = 0.$

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Example

Find the regular-singular points of the differential equation

$$x y'' - x \ln(|x|) y' + 3x y = 0.$$

Solution: Recall: $\lim_{x \to 0} \frac{xQ(x)}{P(x)} = 0$ and $\lim_{x \to 0} \frac{x^2R(x)}{P(x)} = 0.$

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Example

Find the regular-singular points of the differential equation

$$x y'' - x \ln(|x|) y' + 3x y = 0.$$

Solution: Recall: $\lim_{x\to 0} \frac{xQ(x)}{P(x)} = 0$ and $\lim_{x\to 0} \frac{x^2R(x)}{P(x)} = 0$.

However, at the point $x_0 = 0$ the function xQ/P does not have a power series expansion around zero,

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Find the regular-singular points of the differential equation

$$x y'' - x \ln(|x|) y' + 3x y = 0.$$

Solution: Recall: $\lim_{x\to 0} \frac{xQ(x)}{P(x)} = 0$ and $\lim_{x\to 0} \frac{x^2R(x)}{P(x)} = 0$.

However, at the point $x_0 = 0$ the function xQ/P does not have a power series expansion around zero, since

$$\frac{xQ(x)}{P(x)} = -x\ln(|x|),$$

and the log function does not have a Taylor series at $x_0 = 0$.

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and the log function does not have a Taylor series at $x_0 = 0$. We conclude that $x_0 = 0$ is not a regular-singular point.

Equations with regular-singular points (Sect. 5.5).

- Equations with regular-singular points.
- Examples: Equations with regular-singular points.

- Method to find solutions.
- Example: Method to find solutions.

Recall: If x_0 is a regular-singular point of

P(x) y'' + Q(x) y' + R(x) y = 0,

with limits
$$\lim_{x \to x_0} rac{(x-x_0)Q(x)}{P(x)} = p_0$$
 and $\lim_{x \to x_0} rac{(x-x_0)^2 R(x)}{P(x)} = q_0$,

then the coefficients of the differential equation above near x_0 are close to the coefficients of the Euler equation

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Recall: If x_0 is a regular-singular point of

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Idea: If the differential equation is close to an Euler equation, then the solutions of the differential equation might be close to the solutions of an Euler equation.

Recall: One solution of an Euler equation is $y(x) = (x - x_0)^r$.

Summary: Solutions for equations with regular-singular points:

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$$y(x) = \sum_{n=0}^{\infty} a_n (x - x_0)^{(n+r)};$$

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- (3) First find the solutions for the constant *r*. Then, introduce this result for *r* into the recurrence relation for the coefficients *a_n*. Only then, solve this latter recurrence relation for the coefficients *a_n*.

Equations with regular-singular points (Sect. 5.5).

- Equations with regular-singular points.
- Examples: Equations with regular-singular points.

- Method to find solutions.
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Example

Find the solution y near the regular-singular point $x_0 = 0$ of

$$x^{2}y'' - x(x+3)y' + (x+3)y = 0.$$

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but for $r \neq 0$ this relation is not true.

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$$x^{2} y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1)a_{n} x^{(n+r)}.$$

The guiding principle to rewrite each term is to have the power function $x^{(n+r)}$ labeled in the same way on every term.

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Find the solution y near the regular-singular point $x_0 = 0$ of

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We split the sums into the term n = 0 and a sum containing the terms with $n \ge 1$,

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We split the sums into the term n = 0 and a sum containing the terms with $n \ge 1$, that is,

$$0 = [r(r-1) - 3r + 3]a_0x^r + \sum_{n=1}^{\infty} [(n+r)(n+r-1)a_n - (n+r-1)a_{(n-1)} - 3(n+r)a_n + a_{(n-1)} + 3a_n]x^{(n+r)}$$

Example

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Solution: Therefore, [r(r-1) - 3r + 3] = 0 and $[(n+r)(n+r-1)a_n - (n+r-1)a_{(n-1)} - 3(n+r)a_n + a_{(n-1)} + 3a_n] = 0.$

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The last expression can be rewritten as follows,

$$\left[\left[(n+r)(n+r-1)-3(n+r)+3\right]a_n-(n+r-1-1)a_{(n-1)}\right]=0,$$

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Example

Find the solution y near the regular-singular point $x_0 = 0$ of

$$x^{2} y'' - x(x+3) y' + (x+3) y = 0.$$

Solution: Hence, the recurrence relation is given by the equations

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First: solve the first equation for r_{\pm} .

Example

Find the solution y near the regular-singular point $x_0 = 0$ of

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Solution: Hence, the recurrence relation is given by the equations

$$r(r-1) - 3r + 3 = 0,$$

(n+r-1)(n+r-3)a_n - (n+r-2)a_(n-1) = 0.

First: solve the first equation for r_{\pm} .

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First: solve the first equation for r_{\pm} .

Second: Introduce the first solution r_+ into the second equation above and solve for the a_n ; the result is a solution y_+ of the original differential equation;

Third: Introduce the second solution r_{-} into into the second equation above and solve for the a_n ;

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Solution: We first solve r(r-1) - 3r + 3 = 0.

$$r^{2} - 4r + 3 = 0 \quad \Rightarrow \quad r_{\pm} = \frac{1}{2} \left[4 \pm \sqrt{16 - 12} \right]$$

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Introduce $r_+ = 3$ into the equation for a_n :

$$(n+2)na_n - (n+1)a_{n-1} = 0.$$

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Introduce $r_+ = 3$ into the equation for a_n :

$$(n+2)na_n - (n+1)a_{n-1} = 0.$$

One can check that the solution y_+ is

$$y_{+} = a_0 x^3 \Big[1 + \frac{2}{3} x + \frac{1}{4} x^2 + \frac{1}{15} x^3 + \cdots \Big].$$

Example

Find the solution y near the regular-singular point $x_0 = 0$ of

$$x^{2}y'' - x(x+3)y' + (x+3)y = 0.$$

Solution: Introduce $r_{-} = 1$ into the equation for a_n :

$$n(n-2)a_n - (n-1)a_{n-1} = 0.$$

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One can also check that the solution y_{-} is

$$y_{-} = a_2 x \Big[x^2 + \frac{2}{3} x^3 + \frac{1}{4} x^4 + \frac{1}{15} x^5 + \cdots \Big].$$

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Notice:

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Notice:

$$y_{-} = a_2 x^3 \left[1 + \frac{2}{3} x + \frac{1}{4} x^2 + \frac{1}{15} x^3 + \cdots \right] \Rightarrow y_{-} = \frac{a_2}{a_1} y_{+}.$$

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Remark: It can be shown the following result: If the roots of the Euler characteristic polynomial r_+ , r_- differ by an integer, then the second solution y_- , the solution corresponding to the smaller root, is not given by the method above.

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The Laplace Transform (Sect. 6.1).

- ► The definition of the Laplace Transform.
- Review: Improper integrals.
- Examples of Laplace Transforms.
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Definition

The function $F : D_F \to \mathbb{R}$ is the Laplace transform of a function $f : [0, \infty) \to \mathbb{R}$ iff for all $s \in D_F$ holds,

$$F(s)=\int_0^\infty e^{-st}f(t)\,dt,$$

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where $D_F \subset \mathbb{R}$ is the set where the integral converges.

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- This notation L[] emphasizes that the Laplace transform defines a map from a set of functions into a set of functions.
- Functions are denoted as $t \mapsto f(t)$.
- The Laplace transform is also a function: $f \mapsto \mathcal{L}[f]$.

The Laplace Transform (Sect. 6.1).

- ► The definition of the Laplace Transform.
- Review: Improper integrals.
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- A table of Laplace Transforms.
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- ► Laplace Transform and differential equations.

Recall: Improper integral are defined as a limit.

$$\int_{t_0}^{\infty} g(t) dt = \lim_{N \to \infty} \int_{t_0}^{N} g(t) dt.$$

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Compute the improper integral $\int_0^\infty e^{-at} dt$, with a > 0.

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Example Compute $\mathcal{L}[1]$.

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Solution: We have to find the Laplace Transform of f(t) = 1.

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$$\mathcal{L}[1] = \int_0^\infty e^{-st} \, 1 \, dt = \int_0^\infty e^{-st} \, dt$$
$$\int_0^\infty e^{-at} \, dt = \frac{1}{a} \text{ for } a > 0, \text{ and diverges for } a \leqslant 0.$$

Therefore $\mathcal{L}[1] = \frac{1}{s}$, for s > 0, and $\mathcal{L}[1]$ does not exists for $s \leq 0$.

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 for $a > 0$, and diverges for $a \leq 0$.

Therefore $\mathcal{L}[1] = \frac{1}{s}$, for s > 0, and $\mathcal{L}[1]$ does not exists for $s \leq 0$. In other words, $F(s) = \mathcal{L}[1]$ is the function $F : D_F \to \mathbb{R}$ given by

$$f(t) = 1,$$
 $F(s) = \frac{1}{s},$ $D_F = (0,\infty).$

Example

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We conclude that $\mathcal{L}[e^{at}] = \frac{1}{s-a}$ for s > a. In other words,

$$f(t) = e^{at}, \qquad F(s) = \frac{1}{(s-a)}, \qquad s > a.$$

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Compute $\mathcal{L}[\sin(at)]$, where $a \in \mathbb{R}$.

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This identity implies

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Hence, it is not difficult to see that

$$\left(\frac{s^2+a^2}{s^2}\right)\int_0^\infty e^{-st}\sin(at)\,dt=\frac{a}{s^2},\qquad s>0,$$

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The Laplace Transform (Sect. 6.1).

- ► The definition of the Laplace Transform.
- Review: Improper integrals.
- Examples of Laplace Transforms.
- A table of Laplace Transforms.
- Properties of the Laplace Transform.
- Laplace Transform and differential equations.

A table of Laplace Transforms.

f(t) = 1	$F(s) = rac{1}{s}$	s>0,
$f(t)=e^{at}$	$F(s) = \frac{1}{s-a}$	$s > \max\{a, 0\},$
$f(t) = t^n$	$F(s) = \frac{n!}{s^{(n+1)}}$	s>0,
$f(t) = \sin(at)$	$F(s) = \frac{a}{s^2 + a^2}$	s>0,
$f(t) = \cos(at)$	$F(s) = \frac{s}{s^2 + a^2}$	s > 0,
$f(t) = \sinh(at)$	$F(s) = \frac{a}{s^2 - a^2}$	s > 0,
$f(t) = \cosh(at)$	$F(s) = \frac{s}{s^2 - a^2}$	s>0,
$f(t) = t^n e^{at}$	$F(s) = \frac{n!}{(s-a)^{(n+1)}}$	$s > \max\{a, 0\},$
$f(t) = e^{at}\sin(bt)$	$F(s) = \frac{b}{(s-a)^2 + b^2}$	$s > \max\{a, 0\}.$

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Theorem (Sufficient conditions) If the function $f : [0, \infty) \to \mathbb{R}$ is piecewise continuous and there exist positive constants k and a such that

 $|f(t)| \leq k e^{at},$

then the Laplace Transform of f exists for all s > a.

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Theorem (Linear combination)

If the $\mathcal{L}[f]$ and $\mathcal{L}[g]$ are well-defined and a, b are constants, then

 $\mathcal{L}[af + bg] = a \mathcal{L}[f] + b \mathcal{L}[g].$

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Proof: Integration is a linear operation:

$$\int [af(t) + bg(t)] dt = a \int f(t) dt + b \int g(t) dt.$$

Theorem (Derivatives) If the $\mathcal{L}[f]$ and $\mathcal{L}[f']$ are well-defined, then holds,

$$\mathcal{L}[f'] = s \, \mathcal{L}[f] + f(0). \tag{1}$$

Furthermore, if $\mathcal{L}[f'']$ is well-defined, then it also holds

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$$\lim_{n\to\infty}\int_0^n e^{-st}f'(t)\,dt = \lim_{n\to\infty}\left[\left(e^{-st}f(t)\right)\Big|_0^n - \int_0^n (-s)e^{-st}f(t)\,dt\right]$$

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Properties of the Laplace Transform.

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$$\mathcal{L}[f'] = \lim_{n \to \infty} \left[e^{-sn} f(n) - f(0) \right] + s \int_0^\infty e^{-st} f(t) dt = -f(0) + s \mathcal{L}[f],$$

where we used that $\lim_{n\to\infty} e^{-sn}f(n) = 0$ for s big enough, and we also used that $\mathcal{L}[f]$ is well-defined.

We then conclude that $\mathcal{L}[f'] = s \mathcal{L}[f] - f(0)$.

The Laplace Transform (Sect. 6.1).

- ► The definition of the Laplace Transform.
- Review: Improper integrals.
- Examples of Laplace Transforms.
- A table of Laplace Transforms.
- Properties of the Laplace Transform.
- ► Laplace Transform and differential equations.

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Remark: Laplace Transforms can be used to find solutions to differential equations with constant coefficients.

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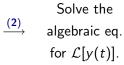
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(1)

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Algebraic eq. (2)
for
$$\mathcal{L}[y(t)]$$
.



Solve the for $\mathcal{L}[y(t)]$.

Transform back $\xrightarrow{(2)} \quad \text{algebraic eq.} \quad \xrightarrow{(3)} \quad \text{to obtain } y(t).$ (Using the table.)

Example

Use the Laplace transform to find the solution y(t) to the IVP

$$y' + 2y = 0,$$
 $y(0) = 3.$

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Find an algebraic equation for $\mathcal{L}[y]$.

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Also recall the property: $\mathcal{L}[y'] = s \mathcal{L}[y] - y(0)$, that is,

$$\left[s\mathcal{L}[y]-y(0)\right]+2\mathcal{L}[y]=0 \quad \Rightarrow \quad (s+2)\mathcal{L}[y]=y(0).$$

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Solution: Recall: $(s+2)\mathcal{L}[y] = y(0)$.

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$$\mathcal{L}[y] = \frac{y(0)}{s+2},$$

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Solution: Recall: $(s+2)\mathcal{L}[y] = y(0)$.

(2): Solve the algebraic equation for $\mathcal{L}[y]$.

$$\mathcal{L}[y] = \frac{y(0)}{s+2}, \quad y(0) = 3, \quad \Rightarrow \quad \mathcal{L}[y] = \frac{3}{s+2}.$$

(3): Transform back to y(t). From the table:

$$\mathcal{L}[e^{at}] = \frac{1}{s-a} \Rightarrow \frac{3}{s+2} = 3\mathcal{L}[e^{-2t}] \Rightarrow \frac{3}{s+2} = \mathcal{L}[3e^{-2t}].$$

Hence, $\mathcal{L}[y] = \mathcal{L}[3e^{-2t}] \quad \Rightarrow \quad y(t) = 3e^{-2t}. \quad \lhd$

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The Laplace Transform and the IVP (Sect. 6.2).

- Solving differential equations using L[].
 - Homogeneous IVP.
 - First, second, higher order equations.
 - Non-homogeneous IVP.
 - ► Recall: Partial fraction decompositions.

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First, second, higher order equations.

Idea of the method:

Remark: The method works with:

- Constant coefficient equations.
- Homogeneous and non-homogeneous equations.

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First, second, higher order equations.

Idea of the method:

$$\mathcal{L}\begin{bmatrix} \text{differential eq.} \\ \text{for } y(t). \end{bmatrix}$$

Remark: The method works with:

- Constant coefficient equations.
- Homogeneous and non-homogeneous equations.
- First, second, higher order equations.

Idea of the method:

$$\mathcal{L}\begin{bmatrix} \text{differential eq.} \\ \text{for } y(t). \end{bmatrix} \xrightarrow{(1)} \begin{array}{c} \text{Algebraic eq.} \\ \text{for } \mathcal{L}[y(t)]. \end{array}$$

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 $\begin{array}{c} \text{Solve the} \\ \xrightarrow{(2)} & \text{algebraic eq.} \\ & \text{for } \mathcal{L}[y(t)]. \end{array}$

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Algebraic eq. (2) for $\mathcal{L}[y(t)]$. Transform back to obtain y(t). (Using the table.)

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Recall:

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(a) $\mathcal{L}[af(t) + bg(t)] = a\mathcal{L}[f(t)] + b\mathcal{L}[g(t)];$

(b) $\mathcal{L}[y^{(n)}] = s^n \mathcal{L}[y] - s^{(n-1)} y(0) - s^{(n-2)} y'(0) - \dots - y^{(n-1)}(0).$

The Laplace Transform and the IVP (Sect. 6.2).

- ▶ Solving differential equations using *L*[].
 - Homogeneous IVP.
 - First, second, higher order equations.
 - Non-homogeneous IVP.
 - ► Recall: Partial fraction decompositions.

Example

Use the Laplace transform to find the solution y(t) to the IVP

$$y'' - y' - 2y = 0,$$
 $y(0) = 1,$ $y'(0) = 0.$

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Derivatives are transformed into power functions,

$$\left[s^{2}\mathcal{L}[y] - s\,y(0) - y'(0)\right] - \left[s\,\mathcal{L}[y] - y(0)\right] - 2\,\mathcal{L}[y] = 0,$$

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We the obtain $(s^2 - s - 2)\mathcal{L}[y] = (s - 1)y(0) + y'(0)$.

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$$\mathcal{L}[y] = \frac{(s-1)}{(s^2-s-2)}$$

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Therefore, we rewrite: $\mathcal{L}[y] = \frac{(s-1)}{(s-2)(s+1)}.$

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Find constants a and b such that

$$\frac{(s-1)}{(s-2)(s+1)} = \frac{a}{s-2} + \frac{b}{s+1}.$$

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Example

Use the Laplace transform to find the solution y(t) to the IVP

$$y'' - y' - 2y = 0,$$
 $y(0) = 1,$ $y'(0) = 0.$

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Solution: Recall: $\frac{(s-1)}{(s-2)(s+1)} = \frac{a}{s-2} + \frac{b}{s+1}$.

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Hence, $a = \frac{1}{3}$ and $b = \frac{2}{3}$.

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Hence,
$$a = \frac{1}{3}$$
 and $b = \frac{2}{3}$. Then, $\mathcal{L}[y] = \frac{1}{3} \frac{1}{(s-2)} + \frac{2}{3} \frac{1}{(s+1)}$

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So we arrive at the equation

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We conclude that: $y(t) = \frac{1}{3}(e^{2t} + 2e^{-t}).$

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Solution: Compute the $\mathcal{L}[$] of the differential equation,

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Solution: Compute the $\mathcal{L}[\]$ of the differential equation,

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Solution: Compute the $\mathcal{L}[\]$ of the differential equation,

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The $\mathcal{L}[$] is a linear function,

$$\mathcal{L}[y''] - 4 \, \mathcal{L}[y'] + 4 \, \mathcal{L}[y] = 0.$$

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Derivatives are transformed into power functions,

$$\left[s^{2}\mathcal{L}[y] - s\,y(0) - y'(0)\right] - 4\left[s\,\mathcal{L}[y] - y(0)\right] + 4\,\mathcal{L}[y] = 0,$$

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Solution: Compute the $\mathcal{L}[$] of the differential equation,

$$\mathcal{L}[y''-4y'+4y]=\mathcal{L}[0]=0.$$

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Derivatives are transformed into power functions,

$$\left[s^{2}\mathcal{L}[y] - s y(0) - y'(0)\right] - 4\left[s\mathcal{L}[y] - y(0)\right] + 4\mathcal{L}[y] = 0,$$

Therefore, $(s^2 - 4s + 4) \mathcal{L}[y] = (s - 4) y(0) + y'(0).$

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Solution: Recall: $(s^2 - 4s + 4) \mathcal{L}[y] = (s - 4) y(0) + y'(0)$.

Introduce the initial conditions,

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Solution: Recall: $(s^2 - 4s + 4) \mathcal{L}[y] = (s - 4) y(0) + y'(0)$. Introduce the initial conditions, $(s^2 - 4s + 4) \mathcal{L}[y] = s - 3$.

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Solve for $\mathcal{L}[y]$ as follows:

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 \Rightarrow $s_{\pm}=rac{1}{2}[4\pm\sqrt{16-16}]$ \Rightarrow $s_{+}=s_{-}=2.$
We obtain: $\mathcal{L}[y]=rac{(s-3)}{(s-2)^2}.$

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$$\mathcal{L}[y] = \frac{(s-2)+2-3}{(s-2)^2}$$

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Example

Use the Laplace transform to find the solution y(t) to the IVP

$$y'' - 4y' + 4y = 0,$$
 $y(0) = 1,$ $y'(0) = 1.$

Solution: Recall: $\mathcal{L}[y] = \frac{(s-3)}{(s-2)^2}$.

This expression is already in the partial fraction decomposition. Idea: Rewrite the right-hand side in terms of function in the table.

$$\mathcal{L}[y] = \frac{(s-2)+2-3}{(s-2)^2} = \frac{(s-2)}{(s-2)^2} - \frac{1}{(s-2)^2} = \frac{1}{s-2} - \frac{1}{(s-2)^2}.$$

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From the Laplace transforms table:

$$\mathcal{L}[e^{at}] = \frac{1}{s-a} \quad \Rightarrow \quad \frac{1}{s-2} = \mathcal{L}[e^{2t}],$$
$$\mathcal{L}[t^n e^{at}] = \frac{n!}{(s-a)^{(n+1)}}$$

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Use the Laplace transform to find the solution y(t) to the IVP

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$$y'' - 4y' + 4y = 0, \qquad y(0) = 1, \qquad y'(0) = 1.$$

Solution: Recall: $\mathcal{L}[y] = \frac{1}{s-2} - \frac{1}{(s-2)^2}$ and
 $\frac{1}{s-2} = \mathcal{L}[e^{2t}], \qquad \frac{1}{(s-2)^2} = \mathcal{L}[te^{2t}].$

Example

Use the Laplace transform to find the solution y(t) to the IVP

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So we arrive at the equation

$$\mathcal{L}[y] = \mathcal{L}[e^{2t}] - \mathcal{L}[te^{2t}]$$

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We conclude that $y(t) = e^{2t} - te^{2t}$.

The Laplace Transform and the IVP (Sect. 6.2).

- Solving differential equations using L[].
 - Homogeneous IVP.
 - First, second, higher order equations.
 - Non-homogeneous IVP.
 - ► Recall: Partial fraction decompositions.

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First, second, higher order equations.

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Use the Laplace Transform to find the solution of $y^{(4)} - 4y = 0$,

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We obtain, $\mathcal{L}[y] = \frac{s^3 - 2s}{(s^4 - 4)}$.

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$$\mathcal{L}[y] = \frac{s(s^2 - 2)}{(s^2 - 2)(s^2 + 2)}$$

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$$\mathcal{L}[y] = rac{s}{\left(s^2 + \left[\sqrt{2}\right]^2\right)} = \mathcal{L}\left[\cos(\sqrt{2}t)\right].$$

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We conclude that $y(t) = \cos(\sqrt{2} t)$.

The Laplace Transform and the IVP (Sect. 6.2).

- Solving differential equations using $\mathcal{L}[$].
 - Homogeneous IVP.
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Example

Use the Laplace transform to find the solution y(t) to the IVP

$$y'' - 4y' + 4y = 3\sin(2t),$$
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Solution: Compute the Laplace transform of the equation,

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The right-hand side above can be expressed as follows,

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Use the Laplace transform to find the solution y(t) to the IVP

$$y'' - 4y' + 4y = 3\sin(2t), \qquad y(0) = 1, \qquad y'(0) = 1.$$

Solution: Compute the Laplace transform of the equation,

$$\mathcal{L}[y''-4y'+4y] = \mathcal{L}[3\sin(2t)].$$

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The right-hand side above can be expressed as follows,

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$$y'' - 4y' + 4y = 3\sin(2t),$$
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Introduce the initial conditions,

$$(s^2 - 4s + 4) \mathcal{L}[y] = s - 3 + \frac{6}{s^2 + 4}$$

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 $y'' - 4y' + 4y = 3\sin(2t),$ y(0) = 1, y'(0) = 1.

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$$y'' - 4y' + 4y = 3\sin(2t),$$
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Solution: Recall: $(s^2 - 4s + 4)\mathcal{L}[y] = s - 3 + \frac{6}{s^2 + 4}$.

Therefore,
$$\mathcal{L}[y] = \frac{(s-3)}{(s^2-4s+4)} + \frac{6}{(s^2-4+4)(s^2+4)}.$$

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From an Example above we know that

$$\mathcal{L}[e^{2t}-te^{2t}]=rac{1}{s-2}-rac{1}{(s-2)^2}.$$

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Find constants a, b, c, d, such that

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$$6 = (as + b)(s - 2)^2 + c(s - 2)(s^2 + 4) + d(s^2 + 4).$$

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We obtain the system

$$a + c = 0,$$
 $-4a + b - 2c + d = 0,$
 $4a - 4b + 4c = 0,$ $4b - 8c + 4d = 6.$

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$$y'' - 4y' + 4y = 3\sin(2t),$$
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Solution: The solution for this linear system is

$$a = \frac{3}{8}, \qquad b = 0, \qquad c = -\frac{3}{8}, \qquad d = \frac{3}{4}.$$

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$$\frac{6}{(s-2)^2 (s^2+4)} = \frac{3}{8} \mathcal{L}[\cos(2t)] - \frac{3}{8} \mathcal{L}[e^{2t}] + \frac{3}{4} \mathcal{L}[te^{2t}].$$

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 $\mathcal{L}[y(t)] = \mathcal{L}[(1-t)e^{2t} + \frac{3}{8}(-1+2t)e^{2t} + \frac{3}{8}\cos(2t)].$

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$$\mathcal{L}[y(t)] = \mathcal{L}[(1-t)e^{2t} + \frac{3}{8}(-1+2t)e^{2t} + \frac{3}{8}\cos(2t)].$$

We conclude that

$$y(t) = (1-t)e^{2t} + \frac{3}{8}(2t-1)e^{2t} + \frac{3}{8}\cos(2t).$$