

Name: Key PID Number: _____

MTH 415

Final Exam

August 19, 2009

- No calculators or any other devices are allowed on this exam.
- Read each question carefully. If any question is not clear, ask for clarification.
- Write your solutions clearly and legibly; no credit will be given for illegible solutions.
- Answer each question completely, and show all your work.
- If you present different answers, then the worst answer will be graded.

Signature: _____

Problem	Points	Score
1	20	
2	20	
3	20	
4	20	
5	20	
6	20	
7	20	
8	20	
9	20	
10	20	
Σ	200	

1. (20 points) Consider the matrix $A = \begin{bmatrix} -2 & 3 & -1 \\ 1 & 2 & -1 \\ -2 & -1 & 1 \end{bmatrix}$. Find the coefficients $(A^{-1})_{13}$ and $(A^{-1})_{21}$ of the inverse matrix of A . Show your work.

$$(A^{-1})_{13} = \frac{C_{31}}{\det(A)}$$

$$\begin{aligned} \det(A) &= (-2)(2-1) - 3(1-2) - 1(-1+4) \\ &= -2 + 3 - 3 \end{aligned}$$

$$\boxed{\det(A) = -2}$$

$$\boxed{(A^{-1})_{13} = \frac{1}{2}}$$

$$C_{31} = (-1)^{3+1} \det(\check{A}_{31})$$

$$= \begin{vmatrix} 3 & -1 \\ 2 & -1 \end{vmatrix} = -3 + 2 = -1$$

$$(A^{-1})_{21} = \frac{C_{12}}{\det(A)}$$

$$C_{12} = (-1)^{1+2} \begin{vmatrix} 1 & -1 \\ -2 & 1 \end{vmatrix} = -(1-2) = 1$$

$$\boxed{(A^{-1})_{21} = -\frac{1}{2}}$$

2. (20 points) Consider the vector space $\mathbb{P}_3([0, 1])$ with the inner product

$$\langle p, q \rangle = \int_0^1 p(x)q(x) dx.$$

Given the set $\mathcal{U} = \{p_1 = x^2, p_2 = x^3\}$, find an orthogonal basis for the subspace $U = \text{Span}(\mathcal{U})$ using the Gram-Schmidt method on the set \mathcal{U} starting with the vector p_1 .

$$q_1 = x^2$$

$$\|q_1\|^2 = \int_0^1 x^4 dx = \frac{x^5}{5} \Big|_0^1 = \frac{1}{5}$$

$$q_2 = x^3 - \frac{\langle q_1, p_2 \rangle}{\|q_1\|^2} x^2$$

$$\langle q_1, p_2 \rangle = \int_0^1 x^5 dx = \frac{x^6}{6} \Big|_0^1 = \frac{1}{6}$$

$$q_2 = x^3 - \frac{1}{6} \cdot 5 x^2$$

$$p_2 = x^3 - \frac{5}{6} x^2$$

3. Consider the matrix $A = \begin{bmatrix} 1 & 3 & 1 & 1 \\ 2 & 6 & 3 & 0 \\ 3 & 9 & 5 & -1 \end{bmatrix}$.

(a) (10 points) Verify that the vector $v = \begin{bmatrix} 3 \\ 1 \\ -4 \\ -2 \end{bmatrix}$ belongs to the null space of A.

(b) (10 points) Extend the set $\{v\}$ into a basis of the null space of A.

$$(a) \begin{bmatrix} 1 & 3 & 1 & 1 \\ 2 & 6 & 3 & 0 \\ 3 & 9 & 5 & -1 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \\ -4 \\ -2 \end{bmatrix} = \begin{bmatrix} 3 + 3 - 4 - 2 \\ 6 + 6 - 12 + 0 \\ 9 + 9 - 20 + 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$(b) \begin{bmatrix} 1 & 3 & 1 & 1 \\ 0 & 0 & 1 & -2 \\ 0 & 0 & 2 & -4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 3 & 0 & 3 \\ 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{matrix} x_1 = -3x_2 - 3x_4 \\ x_3 = 2x_4 \end{matrix}$$

$$\underline{x} = \begin{bmatrix} -3x_2 - 3x_4 \\ x_2 \\ 2x_4 \\ x_4 \end{bmatrix} = \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix} x_2 + \begin{bmatrix} -3 \\ 0 \\ 2 \\ 1 \end{bmatrix} x_4$$

$$\left\{ \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 2 \\ 1 \end{bmatrix} \right\} \quad \begin{bmatrix} 1 & -1 & -1 \\ 1 & 1 & 0 \\ -4 & 0 & 1 \\ 2 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -1 & -1 \\ 0 & 2 & 1 \\ 0 & -4 & -2 \\ 0 & -2 & 3 \end{bmatrix}$$

Basis $\left\{ \begin{bmatrix} 3 \\ 1 \\ -4 \\ -2 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 2 \\ 1 \end{bmatrix} \right\}$

4. (20 points) Use Cramer's rule to find the solution to the linear system

$$2x_1 + x_2 - x_3 = 0$$

$$x_1 + x_3 = 1$$

$$x_1 + 2x_2 + 3x_3 = 0.$$

$$\begin{bmatrix} 2 & 1 & -1 \\ 1 & 0 & 1 \\ 1 & 2 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\begin{vmatrix} 2 & 1 & -1 \\ 1 & 0 & 1 \\ 1 & 2 & 3 \end{vmatrix} = -(3-1) \\ = -2(2+1) \\ = -2-6$$

$$\det(A) = -8$$

$$x_1 = \frac{\begin{vmatrix} 0 & 1 & -1 \\ 1 & 0 & 1 \\ 0 & 2 & 3 \end{vmatrix}}{(-8)} = \frac{-(3+2)}{(-8)} = 1$$

$$\Rightarrow \boxed{x_1 = \frac{5}{8}}$$

$$x_2 = \frac{\begin{vmatrix} 2 & 0 & -1 \\ 1 & 1 & 1 \\ 1 & 0 & 3 \end{vmatrix}}{(-8)} = \frac{(6+1)}{-8} \Rightarrow$$

$$\boxed{x_2 = -\frac{7}{8}}$$

$$x_3 = \frac{\begin{vmatrix} 2 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 2 & 0 \end{vmatrix}}{(-8)} = \frac{-(4-1)}{(-8)} = \frac{3}{8} \Rightarrow$$

$$\boxed{x_3 = \frac{3}{8}}$$

$$\underline{X} = \frac{1}{8} \begin{bmatrix} 5 \\ -7 \\ 3 \end{bmatrix}$$

5. (20 points) Let \mathcal{S}_3 and \mathcal{S}_2 be standard bases of \mathbb{R}^3 and \mathbb{R}^2 , respectively, and consider the linear transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ given by

$$\left[T \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right) \right]_{\mathcal{S}_2} = \begin{bmatrix} -x_1 + 2x_2 - x_3 \\ x_1 + x_3 \end{bmatrix}_{\mathcal{S}_2},$$

and introduce the bases $\mathcal{U} \subset \mathbb{R}^3$ and $\mathcal{V} \subset \mathbb{R}^2$ given by

$$\mathcal{U} = \left\{ [u_1]_{\mathcal{S}_3} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}_{\mathcal{S}_3}, [u_2]_{\mathcal{S}_3} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}_{\mathcal{S}_3}, [u_3]_{\mathcal{S}_3} = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}_{\mathcal{S}_3} \right\},$$

$$\mathcal{V} = \left\{ [v_1]_{\mathcal{S}_2} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}_{\mathcal{S}_2}, [v_2]_{\mathcal{S}_2} = \begin{bmatrix} -3 \\ 2 \end{bmatrix}_{\mathcal{S}_2} \right\}.$$

Find the matrices $[T]_{\mathcal{S}_3 \mathcal{S}_2}$ and $[T]_{\mathcal{U}\mathcal{V}}$. Show your work.

$$T_{\mathcal{S}\mathcal{S}} = \begin{bmatrix} -1 & 2 & -1 \\ 1 & 0 & 1 \end{bmatrix}$$

$$P = I_{\mathcal{U}\mathcal{S}} = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$T_{\mathcal{U}\mathcal{V}} = Q^{-1} T_{\mathcal{S}\mathcal{S}} P$$

$$Q = I_{\mathcal{V}\mathcal{S}} = \begin{bmatrix} 1 & -3 \\ 2 & 2 \end{bmatrix}$$

$$Q^{-1} = \frac{1}{(2+6)} \begin{bmatrix} 2 & 3 \\ -2 & 1 \end{bmatrix}$$

$$= \frac{1}{8} \begin{bmatrix} 2 & 3 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} -1 & 2 & -1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

$$= \frac{1}{8} \begin{bmatrix} 2 & 3 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & -2 & 1 \\ 1 & 2 & 1 \end{bmatrix}$$

$$T_{\mathcal{U}\mathcal{V}} = \frac{1}{8} \begin{bmatrix} 5 & 2 & 5 \\ -1 & 6 & -1 \end{bmatrix}$$

6. Consider the inner product space $(\mathbb{R}^{2,2}, \langle \cdot, \cdot \rangle_F)$ and the subspace

$$W = \text{Span}\left\{E_1 = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, E_2 = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}\right\} \subset \mathbb{R}^{2,2}.$$

Find a basis for W^\perp , the orthogonal complement of W .

$$X = \begin{bmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{bmatrix} \quad 0 = \langle E_1, X \rangle = \text{tr}\left(\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{bmatrix}\right) = x_{21} + x_{12}$$

$$0 = \langle E_2, X \rangle = \text{tr}\left(\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{bmatrix}\right) = x_{11} - x_{22}$$

$$x_{21} = -x_{12}$$

$$x_{11} = x_{22}$$

$$X = \begin{bmatrix} x_{11} & x_{12} \\ -x_{12} & x_{11} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} x_{11} + \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} x_{12}.$$

$$W^\perp = \text{Span}\left(\left\{ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \right\}\right)$$

basis of W^\perp .

7. (20 points) Consider the matrix $A = \begin{bmatrix} 1 & 2 \\ 1 & -1 \\ -2 & 1 \end{bmatrix}$ and the vector $b = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$.

- (a) Find the least-squares solution \hat{x} to the matrix equation $Ax = b$.
 (b) Verify that the vector $A\hat{x} - b$, where \hat{x} is the least-squares solution found in part (a), belongs to the space $R(A)^\perp$, the orthogonal complement of $R(A)$.

$$(a) \quad A^T A = \begin{bmatrix} 1 & 1 & -2 \\ 2 & -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & -1 \\ -2 & 1 \end{bmatrix} = \begin{bmatrix} 6 & -1 \\ -1 & 6 \end{bmatrix}$$

$$A^T b = \begin{bmatrix} 1 & 1 & -2 \\ 2 & -1 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\hat{x} = \frac{1}{35} \begin{bmatrix} 6 & 1 \\ 1 & 6 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \frac{1}{35} \begin{bmatrix} 5 \\ -5 \end{bmatrix} \Rightarrow \boxed{\hat{x} = \frac{1}{7} \begin{bmatrix} 1 \\ -1 \end{bmatrix}}$$

$$(b) \quad A\hat{x} = \begin{bmatrix} 1 & 2 \\ 1 & -1 \\ -2 & 1 \end{bmatrix} \frac{1}{7} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} -1 \\ 2 \\ -3 \end{bmatrix}$$

$$A\hat{x} - b = \frac{1}{7} \left(\begin{bmatrix} -1 \\ 2 \\ -3 \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right) \Rightarrow \boxed{(A\hat{x} - b) = \frac{1}{7} \begin{bmatrix} -1 \\ 1 \\ -3 \end{bmatrix}}$$

$$\begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 1 \\ -3 \end{bmatrix} = 1 + 1 - 6 = 0 \quad \checkmark$$

$$\begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 1 \\ -3 \end{bmatrix} = 2 - 1 - 3 = 0 \quad \checkmark$$

8. Suppose that a matrix $A \in \mathbb{R}^{3,3}$ has eigenvalues $\lambda_1 = 1$, $\lambda_2 = 2$, and $\lambda_3 = 4$.

(a) (15 points) Find the trace of A , find the trace of A^2 , and find the determinant of A .

(b) (5 points) Is matrix A invertible? If your answer is "yes", then prove it and find $\det(A^{-1})$; if your answer is "no", then prove it.

$$A \in \mathbb{R}^{3,3} \quad \left. \begin{array}{l} \lambda_1 \neq \lambda_2 \\ \neq \lambda_3 \\ \lambda_2 \neq \lambda_3 \end{array} \right\} \Rightarrow \{v_1, v_2, v_3\} \text{ l.i., where.}$$
$$A v_i = \lambda_i v_i \quad i=1, 2, 3.$$

$$\therefore A \text{ diagonalizable} \Rightarrow \exists P, P^{-1}, D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{bmatrix} \text{ s.t.}$$

$$A = P D P^{-1}$$

$$(a) \quad \left[\begin{array}{l} \text{tr}(A) = \text{tr}(P D P^{-1}) = \text{tr}(P^{-1} P D) = \text{tr}(D) = 1+2+4 = 7. \\ \text{tr}(A^2) = \text{tr}(P D^2 P^{-1}) = \text{tr}(D^2) = 1+4+16 = 21 \\ \det(A) = \det(P D P^{-1}) = \det(D) = (1)(2)(4) = 8. \end{array} \right]$$

(b) Set of columns of A is l.i. $\Rightarrow A$ invertible.

$$A^{-1} = (P D P^{-1})^{-1} = (P^{-1})^{-1} D^{-1} P^{-1} = P D^{-1} P^{-1}$$

$$\det(A^{-1}) = \det(D^{-1}) = \frac{1}{8}$$

9. Consider the matrix $A = \begin{bmatrix} 7 & 5 \\ 3 & -7 \end{bmatrix}$.

- (a) (10 points) Find the eigenvalues and eigenvectors of A.
 (b) (10 points) Compute the matrix e^A .

$$(a) \quad \begin{vmatrix} 7-\lambda & 5 \\ 3 & -7-\lambda \end{vmatrix} = (\lambda-7)(\lambda+7) - 15 = \lambda^2 - 49 - 15 = \lambda^2 - 64$$

$$\therefore \lambda^2 - 64 = 0 \Rightarrow \boxed{\lambda_{\pm} = \pm 8}$$

$$\lambda_+ \quad \begin{bmatrix} -1 & 5 \\ 3 & -15 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -5 \\ 0 & 0 \end{bmatrix} \quad x_1 = 5x_2$$

$$\boxed{x_+ = \begin{bmatrix} 5 \\ 1 \end{bmatrix}, \lambda_+ = 8}$$

$$\lambda_- \quad \begin{bmatrix} 15 & 5 \\ 3 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 3 & 1 \\ 0 & 0 \end{bmatrix} \quad 3x_1 = -x_2$$

$$\boxed{x_- = \begin{bmatrix} 1 \\ -3 \end{bmatrix}, \lambda_- = -8}$$

$$(b) \quad e^A = P e^D P^{-1} \quad P = \begin{bmatrix} 5 & 1 \\ 1 & -3 \end{bmatrix} \quad D = \begin{bmatrix} 8 & 0 \\ 0 & -8 \end{bmatrix}$$

$$\boxed{e^A = \begin{bmatrix} 5 & 1 \\ 1 & -3 \end{bmatrix} \begin{bmatrix} e^8 & 0 \\ 0 & e^{-8} \end{bmatrix} \frac{(-1)}{16} \begin{bmatrix} 3 & 1 \\ 1 & -5 \end{bmatrix}} \quad P^{-1} = \frac{(-1)}{16} \begin{bmatrix} -3 & -1 \\ -1 & 5 \end{bmatrix}$$

10. (20 points) Find the function $x: \mathbb{R} \rightarrow \mathbb{R}^2$ solution of the initial value problem

$$\frac{d}{dt}x(t) = Ax(t), \quad x(0) = x_0,$$

where the matrix $A = \begin{bmatrix} -5 & 2 \\ -12 & 5 \end{bmatrix}$ and the vector $x_0 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$.

$$\begin{vmatrix} -5-\lambda & 2 \\ -12 & 5-\lambda \end{vmatrix} = (\lambda-5)(\lambda+5) + 24 = \lambda^2 - 25 + 24 = \lambda^2 - 1$$

$$\lambda_{\pm} = \pm 1$$

$$\lambda_+ = 1 \quad \begin{bmatrix} -6 & 2 \\ -12 & 4 \end{bmatrix} \rightarrow \begin{bmatrix} -3 & 1 \\ 0 & 0 \end{bmatrix} \quad +3x_1 = x_2$$

$$x_+ = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

$$\lambda_- = -1 \quad \begin{bmatrix} -4 & 2 \\ -12 & 6 \end{bmatrix} \rightarrow \begin{bmatrix} -2 & 1 \\ 0 & 0 \end{bmatrix} \quad 2x_1 = x_2$$

$$x_- = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \quad \lambda_- = -1$$

$$x(t) = c_1 \begin{bmatrix} 1 \\ 3 \end{bmatrix} e^t + c_2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^{-t}$$

$$\begin{bmatrix} 1 & 1 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \Rightarrow \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \frac{1}{(2-3)} \begin{bmatrix} 2 & -1 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$= (-1) \begin{bmatrix} 1 \\ -2 \end{bmatrix} \Rightarrow \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

$$x(t) = -e^t \begin{bmatrix} 1 \\ 3 \end{bmatrix} + 2e^{-t} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$