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Math 20D.

Quiz 4

May 9, 2008

*Answer each question completely, and show your work.*

*If you use extra paper, write your name on each extra page,*

*and staple the question page and your own added pages together.*

1. (30 points) Verify that the functions  $y_1(t) = t$  and  $y_2(t) = te^t$  are solutions to the homogeneous differential equation

$$t^2 y'' - t(t+2)y' + (t+2)y = 0 \quad t > 0,$$

and then use the method of variation of parameters to obtain a particular solution to the inhomogeneous differential equation

$$t^2 y'' - t(t+2)y' + (t+2)y = t^3 e^{3t} \quad t > 0.$$

**Solution:** We first verify that the function  $y_1(t) = t$  is solution of the homogeneous equation above:  $y_1'(t) = 1$  and  $y_1''(t) = 0$ , therefore

$$t^2(0) - t(t+2)(1) + (t+2)t = 0.$$

We now verify that the function  $y_2(t) = te^t$  is also solution of the homogeneous equation above:  $y_2'(t) = (t+1)e^t$  and  $y_2''(t) = (t+2)e^t$ , therefore,

$$t^2(t+2)e^t - t(t+2)(t+1)e^t + (t+2)te^t = (t+2)te^t[t - (t+1) + 1] = 0.$$

We now construct a particular solution  $y_p$  using the variation of parameters method. Rewrite the inhomogeneous equation above as:

$$y'' - \left(1 + \frac{2}{t}\right)y' + (t+2)\frac{1}{t^2}y = te^{3t} \quad t > 0.$$

Then, the solution is given by the expression

$$y_p(t) = u_1(t)y_1(t) + u_2(t)y_2(t), \quad \text{where} \quad \begin{cases} u_1(t) = - \int \frac{y_2(t)g(t)}{W(t)} dt \\ u_2(t) = \int \frac{y_1(t)g(t)}{W(t)} dt, \end{cases}$$

where

$$g(t) = te^{3t}, \quad W(t) = y_1(t)y_2'(t) - y_1'(t)y_2(t).$$

We first compute the Wronskian function  $W$ :

$$W(t) = t(t+1)e^t - (1)te^t \Rightarrow W(t) = t^2e^t.$$

Then, the function  $u_1$  is given by

$$u_1(t) = - \int \frac{(te^t)(te^{3t})}{t^2e^t} dt = - \int e^{3t} dt \Rightarrow u_1(t) = -\frac{e^{3t}}{3}.$$

The function  $u_2$  is given by

$$u_2(t) = \int \frac{(t)(te^{3t})}{t^2e^t} dt = \int e^{2t} dt \Rightarrow u_2(t) = \frac{e^{2t}}{2}.$$

The particular solution  $y_p$  is given by

$$y_p(t) = -\frac{e^{3t}}{3}(t) + \frac{e^{2t}}{2}(te^t) \Rightarrow \boxed{y_p(t) = \frac{1}{6}te^{3t}}.$$

2. (35 points) Decide whether the set of vectors shown below is linearly dependent or independent. In the case that the set of vectors is linearly dependent, express one of them as a linear combination of the other two.

$$\left\{ \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 7 \\ 4 \end{bmatrix} \right\}$$

**Solution:** We perform Gauss Elimination Operations to find the solution to the homogeneous equation

$$\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} c_1 + \begin{bmatrix} -1 \\ 2 \\ -1 \end{bmatrix} c_2 + \begin{bmatrix} 1 \\ 7 \\ 4 \end{bmatrix} c_3 = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

We then obtain:

$$\begin{bmatrix} 1 & -1 & 1 \\ 1 & 2 & 7 \\ 2 & -1 & 4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -1 & 1 \\ 0 & 3 & 6 \\ 0 & 1 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix},$$

We therefore have  $c_1 = -3c_3$ ,  $c_2 = -2c_3$ , and  $c_3$  free, which says that the vectors above are **linearly dependent**. Choosing  $c_3 = 1$  we obtain

$$\boxed{\begin{bmatrix} 1 \\ 7 \\ 4 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} + 2 \begin{bmatrix} -1 \\ 2 \\ -1 \end{bmatrix}}.$$

3. (35 points) Find all eigenvalues and eigenvectors of matrix  $A$  below. Also find all eigenvalues and eigenvectors of the matrix  $B$  below,

$$A = \begin{bmatrix} 3 & 0 & 1 \\ 0 & 3 & 2 \\ 0 & 0 & 1 \end{bmatrix} \quad B = \begin{bmatrix} 3 & 1 & 1 \\ 0 & 3 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

**Solution:** The eigenvalues of matrix  $A$  are the solutions to the equation

$$0 = \begin{vmatrix} 3 - \lambda & 0 & 1 \\ 0 & 3 - \lambda & 2 \\ 0 & 0 & 1 - \lambda \end{vmatrix} = (3 - \lambda)^2(1 - \lambda) \Rightarrow \begin{cases} \lambda_1 = 3, \\ \lambda_2 = 1. \end{cases}$$

The eigenvectors for  $\lambda_1 = 3$  are computed as follows:

$$\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 2 \\ 0 & 0 & -2 \end{bmatrix} \rightarrow \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix},$$

which implies that  $v_3 = 0$  while  $v_1$  and  $v_2$  are free. Therefore, there are two linearly independent eigenvectors given by

$$\lambda_1 = 3, \quad \mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}.$$

The eigenvectors for  $\lambda_2 = 1$  are computed as follows:

$$\begin{bmatrix} 2 & 0 & 1 \\ 0 & 2 & 2 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix},$$

which implies that  $v_3$  is free while  $2v_1 = -v_3$  and  $v_2 = -v_3$ . Therefore, choosing  $v_3 = 2$ , the eigenvector is given by

$$\lambda_2 = 1, \quad \mathbf{w} = \begin{bmatrix} -1 \\ -2 \\ 2 \end{bmatrix}.$$

The eigenvalues of matrix  $B$  are the solutions to the equation

$$0 = \begin{vmatrix} 3 - \lambda & 1 & 1 \\ 0 & 3 - \lambda & 2 \\ 0 & 0 & 1 - \lambda \end{vmatrix} = (3 - \lambda)^2(1 - \lambda) \Rightarrow \begin{cases} \lambda_1 = 3, \\ \lambda_2 = 1. \end{cases}$$

The eigenvectors for  $\lambda_1 = 3$  are computed as follows:

$$\begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 2 \\ 0 & 0 & -2 \end{bmatrix} \rightarrow \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix},$$

which implies that  $v_2 = 0$  and  $v_3 = 0$  while  $v_1$  is free. Therefore, the set of linearly independent eigenvectors consists of only one vector, which can be chosen to be:

$$\lambda_1 = 3, \quad \mathbf{v} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}.$$

The eigenvectors for  $\lambda_2 = 1$  are computed as follows:

$$\begin{bmatrix} 2 & 1 & 1 \\ 0 & 2 & 2 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

which implies that  $v_3$  is free while  $v_1 = 0$  and  $v_2 = -v_3$ . Therefore, choosing  $v_3 = 1$ , the eigenvector is given by

$$\lambda_2 = 1, \quad \mathbf{w} = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}.$$