

## Slide 1

**Directional derivative and gradient vector**

- Definition of directional derivative. (Sec. 14.6)
- Directional derivative and partial derivatives.
- Gradient vector.
- Geometrical meaning of the gradient.

## Slide 2

**The directional derivative generalizes the partial derivatives to any direction**

**Definition 1** *The directional derivative of the function  $f(x, y)$  at the point  $(x_0, y_0)$  in the direction of a unit vector  $\mathbf{u} = \langle u_x, u_y \rangle$  if*

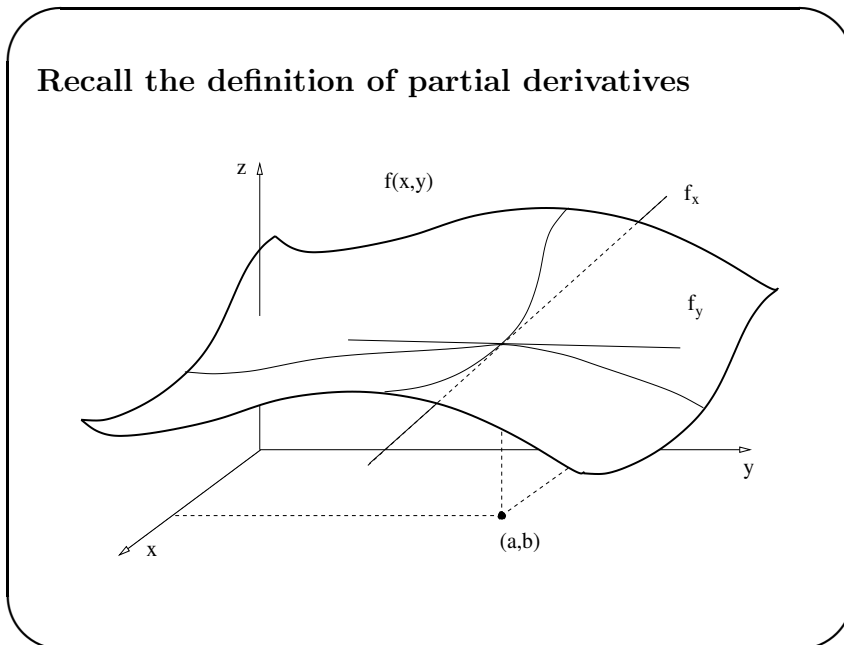
$$D_{\mathbf{u}}f(x_0, y_0) = \lim_{t \rightarrow 0} \frac{1}{t} [f(x_0 + u_x t, y_0 + u_y t) - f(x_0, y_0)],$$

*if the limit exists.*

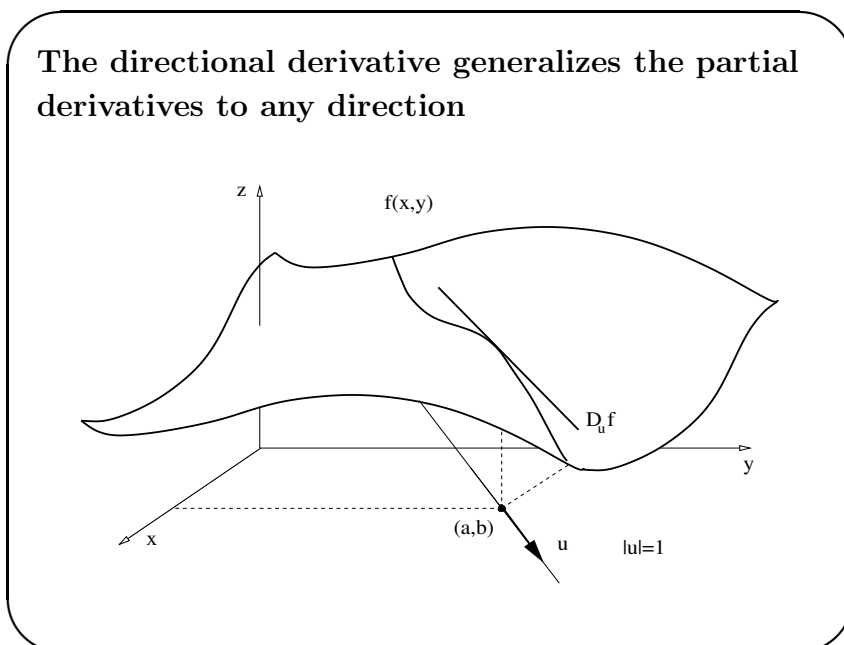
Particular cases:

- $\mathbf{u} = \langle 1, 0 \rangle = \mathbf{i}$ , then  $D_{\mathbf{i}}f(x_0, y_0) = f_x(x_0, y_0)$ .
- $\mathbf{u} = \langle 0, 1 \rangle = \mathbf{j}$ , then  $D_{\mathbf{j}}f(x_0, y_0) = f_y(x_0, y_0)$ .

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$|\mathbf{u}| = 1$  implies that  $t$  is the distance between the points  $(x, y) = (x_0 + u_x t, y_0 + u_y t)$  and  $(x_0, y_0)$

$$\begin{aligned}d &= |\langle x - x_0, y - y_0 \rangle|, \\ &= |\langle u_x t, u_y t \rangle|, \\ &= |t| |\mathbf{u}|, \\ &= |t|.\end{aligned}$$

The directional derivative of  $f(x, y)$  at  $(x_0, y_0)$  along  $\mathbf{u}$  is the pointwise rate of change of  $f$  with respect to the distance along the line parallel to  $\mathbf{u}$  passing through  $(x_0, y_0)$ .

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Here is a useful formula to compute directional derivative

**Theorem 1** *If  $f(x, y)$  is differentiable and  $\mathbf{u} = \langle u_x, u_y \rangle$  is a unit vector, then*

$$D_{\mathbf{u}}f(x_0, y_0) = f_x(x_0, y_0) u_x + f_y(x_0, y_0) u_y.$$

The proof is based in the chain rule, case 1

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**Proof of the theorem**

Chain rule case 1, for  $x(t) = x_0 + u_x t$ ,  $y(t) = y_0 + u_y t$ .  
Then,  $z(t) = f(x(t), y(t))$ .

On the one hand,

$$\begin{aligned}\left. \frac{dz}{dt} \right|_{t=0} &= \lim_{t \rightarrow 0} \frac{1}{t} [z(t) - z(0)], \\ &= \lim_{t \rightarrow 0} \frac{1}{t} [f(x_0 + u_x t, y_0 + u_y t) - f(x_0, y_0)], \\ &= D_{\mathbf{u}} f(x_0, y_0).\end{aligned}$$

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**Proof of the theorem (Cont.)**

On the other hand,

$$\begin{aligned}\frac{dz}{dt}(t) &= f_x(x(t), y(t)) \frac{dx}{dt}(t) + f_y(x(t), y(t)) \frac{dy}{dt}(t), \\ &= f_x(x(t), y(t)) u_x + f_y(x(t), y(t)) u_y,\end{aligned}$$

then,

$$\left. \frac{dz}{dt} \right|_{t=0} = f_x(x_0, y_0) u_x + f_y(x_0, y_0) u_y.$$

Therefore,

$$D_{\mathbf{u}} f(x_0, y_0) = f_x(x_0, y_0) u_x + f_y(x_0, y_0) u_y.$$

□

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**Example about how to compute a directional derivative**

Let  $f(x, y) = \sin(x + 2y)$ . Compute the directional derivative of  $f(x, y)$  at  $(4, -2)$  in the direction  $\theta = \pi/6$ .

$$\mathbf{u} = \langle \cos(\theta), \sin(\theta) \rangle, \quad \mathbf{u} = \langle \sqrt{3}/2, 1/2 \rangle.$$

Also

$$f_x = \cos(x + 2y), \quad f_y = 2 \cos(x + 2y),$$

then

$$\begin{aligned} D_{\mathbf{u}}f(x, y) &= \cos(x + 2y)u_x + 2 \cos(x + 2y)u_y, \\ D_{\mathbf{u}}f(4, -2) &= \frac{\sqrt{3}}{2} + 1. \end{aligned}$$

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**Directional derivatives can be defined on functions of 2, 3 or more variables**

**Definition 2** (functions of 3 variables)

*The directional derivative of the function  $f(x, y, z)$  at the point  $(x_0, y_0, z_0)$  in the direction of a unit vector*

$\mathbf{u} = \langle u_x, u_y, u_z \rangle$  *is*

$$D_{\mathbf{u}}f(x_0, y_0, z_0) = \lim_{t \rightarrow 0} \frac{1}{t} [f(x_0 + u_x t, y_0 + u_y t, z_0 + u_z t) - f(x_0, y_0, z_0)],$$

*if the limit exists.*

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**The same useful theorem we had in 2 variable functions**

**Theorem 2** *If  $f(x, y, z)$  is differentiable and  $\mathbf{u} = \langle u_x, u_y, u_z \rangle$  is a unit vector, then*

$$D_{\mathbf{u}}f(x_0, y_0, z_0) = f_x(x_0, y_0, z_0)u_x + f_y(x_0, y_0, z_0)u_y + f_z(x_0, y_0, z_0)u_z.$$

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**The directional derivative can be written in terms of a dot product**

In the case of 2 variable functions:

$$D_{\mathbf{u}}f = f_x u_x + f_y u_y = (\nabla f) \cdot \mathbf{u},$$

with  $\nabla f = \langle f_x, f_y \rangle$ .

In the case of 3 variable functions:

$$D_{\mathbf{u}}f = f_x u_x + f_y u_y + f_z u_z = (\nabla f) \cdot \mathbf{u},$$

with  $\nabla f = \langle f_x, f_y, f_z \rangle$ .

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We introduce the gradient vector for functions of 2 or 3 variables

**Definition 3** Let  $f(x, y, z)$  be a differentiable function. Then,

$$\nabla f(x, y, z) = \langle f_x(x, y, z), f_y(x, y, z), f_z(x, y, z) \rangle,$$

is called the gradient of  $f(x, y, z)$ .

In 2 variables:  $\nabla f(x, y) = \langle f_x(x, y), f_y(x, y) \rangle$ .

Alternative notation:  $\nabla f = f_x \mathbf{i} + f_y \mathbf{j} + f_z \mathbf{k}$ .

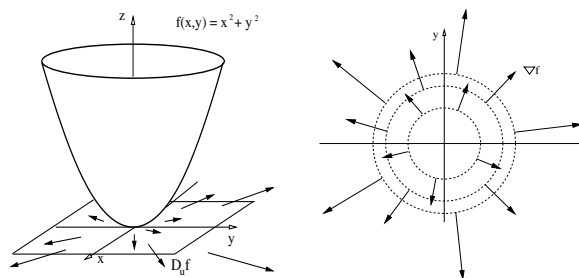
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The useful theorem now has the following form

**Theorem 3** Let  $f(x, y, z)$  be differentiable function. Then,

$$D_{\mathbf{u}}f(\mathbf{x}) = (\nabla f(\mathbf{x})) \cdot \mathbf{u}.$$

with  $|\mathbf{u}| = 1$ .



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**Gradient vector** The gradient vector has two main properties:

- It points in the direction of the maximum increase of  $f$ , and  $|\nabla f|$  is the value of the maximum increase rate.
- $\nabla f$  is normal to the level surfaces.

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**Here is the first property of the gradient vector**

**Theorem 4** *Let  $f$  be a differentiable function of 2 or 3 variables. Fix  $P_0 \in D(f)$ , and let  $\mathbf{u}$  be an arbitrary unit vector.*

*Then, the maximum value of  $D_{\mathbf{u}}f(P_0)$  among all possible directions is  $|\nabla f(P_0)|$ , and it is achieved for  $\mathbf{u}$  parallel to  $\nabla f(P_0)$ .*



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**The proof of the first property**

$$\begin{aligned} D_{\mathbf{u}}f(P_0) &= (\nabla f(P_0)) \cdot \mathbf{u}, \\ &= |\nabla f(P_0)| |\mathbf{u}| \cos(\theta), \\ &= |\nabla f(P_0)| \cos(\theta). \end{aligned}$$

But  $-1 \leq \cos(\theta) \leq 1$  implies

$$-|\nabla f(P_0)| \leq D_{\mathbf{u}}f(P_0) \leq |\nabla f(P_0)|.$$

And  $D_{\mathbf{u}}f(P_0) = |\nabla f(P_0)|$ ,  $\Leftrightarrow \theta = 0 \Leftrightarrow \mathbf{u}$  is parallel  $\nabla f(P_0)$ . □

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**Here is the second property of the gradient vector, in the case of 3 variable functions**

**Theorem 5** *Let  $f(x, y, z)$  be a differentiable at  $P_0$ . Then,  $\nabla f(P_0)$  is orthogonal to the plane tangent to a level surface containing  $P_0$ .*

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**Proof of the second property**

Let  $\mathbf{r}(t)$  be any differentiable curve in the level surface  $f(x, y, z) = k$ . Assume that  $\mathbf{r}(t = 0) = \overrightarrow{OP_0}$ . Then,

$$\begin{aligned} 0 &= \frac{df}{dt}, \\ &= f_x \frac{dx}{dt} + f_y \frac{dy}{dt} + f_z \frac{dz}{dt}, \\ &= \nabla f(\mathbf{r}(t)) \cdot \frac{d\mathbf{r}}{dt}(t). \end{aligned}$$

But  $(d\mathbf{r})/(dt)$  is tangent to the level surface for any choice of  $\mathbf{r}(t)$ . Therefore

$$\nabla f(\mathbf{r}(t = 0)) \cdot \frac{d\mathbf{r}}{dt}(t = 0) = 0$$

implies that  $\nabla f(P_0)$  is orthogonal to the level surface.  $\square$

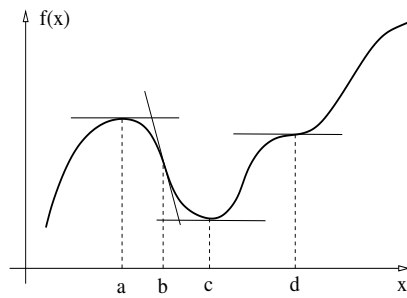
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**Local and absolute maxima, minima, and inflection points**

- Definitions of local extrema. (Sec. 14.7)
- Characterization of local extrema.
- Absolute extrema on closed and bounded sets.
- Typical exercises.

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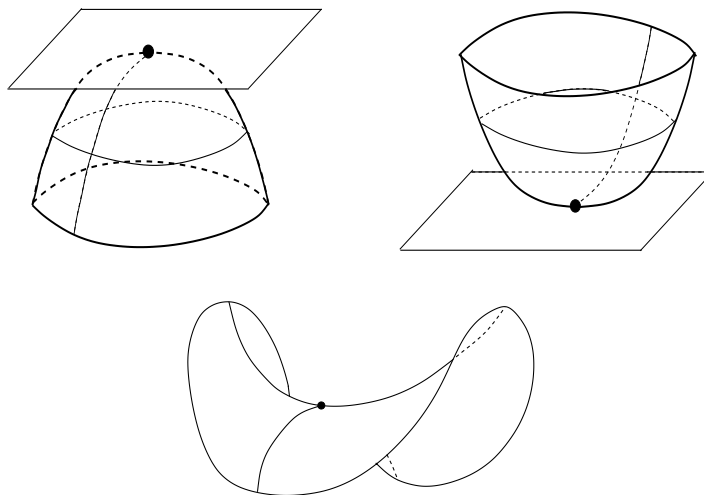
Recall the main results on local extrema for  $f(x)$



at	$f$	$f'$	$f''$
$a$	max.	$0$	$< 0$
$b$	infl.	$\neq 0$	$\pm 0 \mp$
$c$	min.	$0$	$> 0$
$d$	infl.	$= 0$	$\pm 0 \mp$

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The main cases of local extrema for  $f(x, y)$



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The intuitive notions of local extrema can be written precisely as follows

**Definition 4 (Local maximum)** A function  $f(x, y)$  has a local maximum at  $(a, b) \in D(f) \Leftrightarrow f(x, y) \leq f(a, b)$  for all  $(x, y)$  near  $(a, b)$ .

**Definition 5 (Local minimum)** A function  $f(x, y)$  has a local minimum at  $(a, b) \in D(f) \Leftrightarrow f(x, y) \geq f(a, b)$  for all  $(x, y)$  near  $(a, b)$ .

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The tangent plane to the graph of  $f$  at a local max-min is horizontal

**Theorem 6** Let  $f(x, y)$  be differentiable at  $(a, b)$ . If  $f$  has a local maximum or minimum at  $(a, b)$  then  $\nabla f(a, b) = \langle 0, 0 \rangle$ .

Recall:  $\mathbf{n} = \langle f_x, f_y, -1 \rangle = \langle 0, 0, -1 \rangle$ .

The converse is not true: It could be a saddle point

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**Stationary points include local maxima, minima, and saddle points**

**Definition 6 (Stationary point)** *Let  $f(x, y)$  be a differentiable function at  $(a, b)$ . If  $\nabla f(a, b) = \langle 0, 0 \rangle$ , then the point  $(a, b)$  is called a stationary point of  $f$ .*

**Stationary points are located where the gradient vector vanishes**

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**Theorem 7 (Second derivative test)** *Let  $(a, b)$  be a stationary point of  $f(x, y)$ , that is,  $\nabla f(a, b) = \mathbf{0}$ . Assume that  $f(x, y)$  has continuous second derivatives in a disk with center in  $(a, b)$ . Introduce the quantity*

$$D = f_{xx}(a, b)f_{yy}(a, b) - [f_{xy}(a, b)]^2.$$

- *If  $D > 0$  and  $f_{xx}(a, b) > 0$ , then  $f(a, b)$  is a local minimum.*
- *If  $D > 0$  and  $f_{xx}(a, b) < 0$ , then  $f(a, b)$  is a local maximum.*
- *If  $D < 0$ , then  $f(a, b)$  is a saddle point.*
- *If  $D = 0$  the test is inconclusive.*

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Find the local extrema of  $f(x, y) = y^2 - x^2$

$$\nabla f = \langle -2x, 2y \rangle, \quad \Rightarrow \quad \nabla f = \langle 0, 0 \rangle \quad \text{at} \quad (0, 0).$$

$$f_{xx}(0, 0) = -2, \quad f_{yy}(0, 0) = 2, \quad f_{xy}(0, 0) = 0,$$

$$D = (-2)(2) = -4 < 0 \quad \Rightarrow \quad \text{saddle point at } (0, 0).$$

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Is  $(0, 0)$  a local extrema of  $f(x, y) = y^2x^2$ ?

$$\nabla f(x, y) = \langle 2xy^2, 2yx^2 \rangle, \quad \Rightarrow$$

$$\nabla f(0, 0) = \langle 0, 0 \rangle \quad \text{at} \quad (0, 0).$$

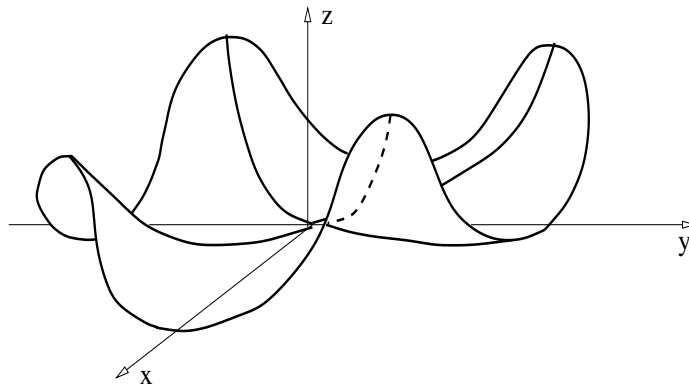
$$f_{xx}(x, y) = 2y^2, \quad f_{yy}(x, y) = 2x^2, \quad f_{xy}(x, y) = 4xy,$$

$$f_{xx}(0, 0) = 0, \quad f_{yy}(0, 0) = 0, \quad f_{xy}(0, 0) = 0,$$

So  $D = 0$  and the test is inconclusive.

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From the graph of  $f = x^2y^2$  is easy to see that  $(0, 0)$  is a global minimum



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Find the maximum volume of a closed rectangular box with a given surface area  $A_0$

$$V(x, y, z) = xyz, \quad A(x, y, z) = 2xy + 2xz + 2yz.$$

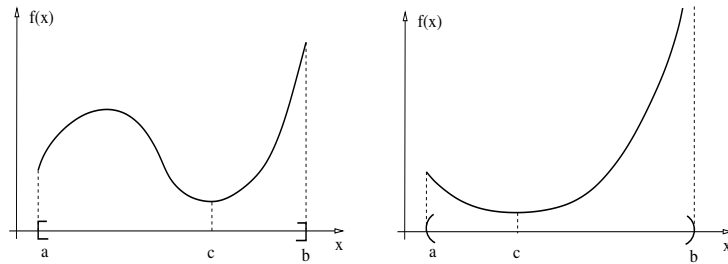
But  $A(x, y, z) = A_0$ , then

$$z = \frac{A_0 - 2xy}{2(x + y)}, \quad \Rightarrow \quad V(x, y) = \frac{A_0xy - 2x^2y^2}{2(x + y)}.$$

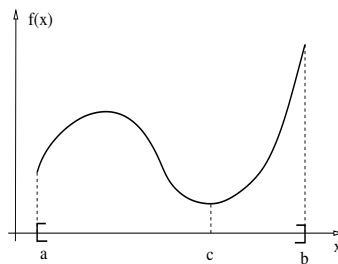
Find  $\nabla V(x_0, y_0) = \langle 0, 0 \rangle$ .

The result is  $x_0 = y_0 = z_0 = \sqrt{A_0/6}$ .

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**Local extrema need not be the absolute extrema****Absolute extrema may not be defined on open intervals**

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**Continuous functions  $f(x)$  on intervals  $[a, b]$  always have absolute extrema****Intervals  $[a, b]$  are bounded and closed sets in  $\mathbb{R}$** 

Because they do not extend to infinity, and the boundary points belong to the set.



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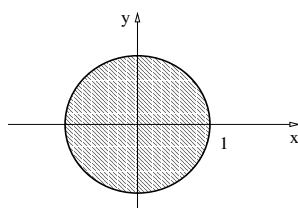
Here is the generalization of closed and bounded intervals to  $\mathbb{R}^2$

**Definition 7** A set  $D \subset \mathbb{R}^2$  is bounded if it can be contained in a disk. A set  $D \subset \mathbb{R}^2$  is closed if it contains all its boundary points.

A point  $P \in \mathbb{R}^2$  is a boundary point of a set  $D$  if every disk with center in  $P$  always contains both points in  $D$  and points not in  $D$ .

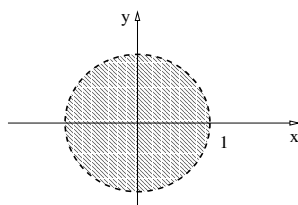
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Here are examples of bounded sets



$$\{x^2 + y^2 \leq 1\},$$

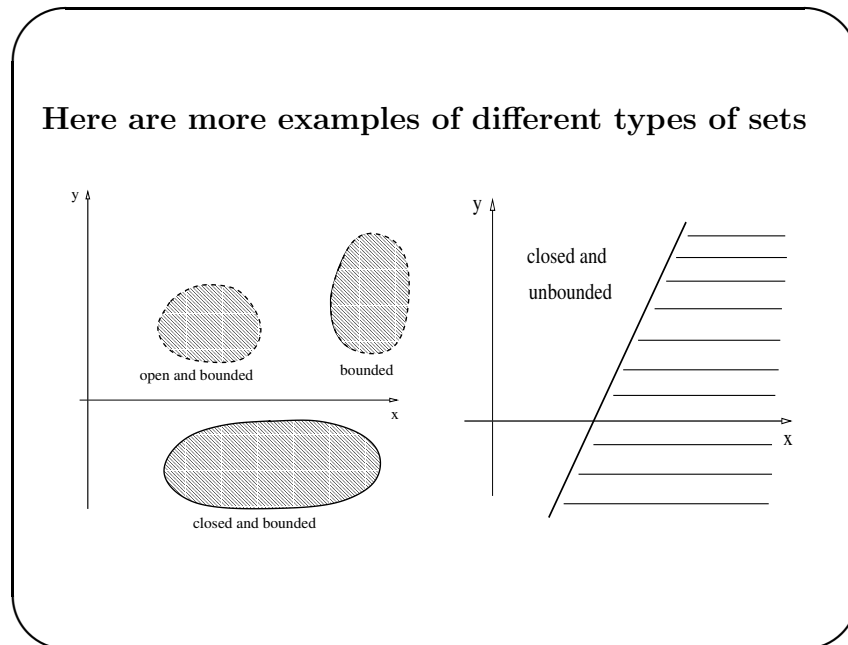
Closed and bounded.



$$\{x^2 + y^2 < 1\},$$

Open and bounded.

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**Continuous functions on bounded and closed sets always have absolute extrema**

**Theorem 8** *If  $f(x, y)$  is continuous in a closed and bounded set  $D \subset \mathbb{R}^2$ , then  $f$  has an absolute maximum and an absolute minimum in  $D$ .*

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**Suggestions to find absolute extrema of  $f(x, y)$  in a closed and bounded set**

- Find every stationary point of  $f$ .  
( $\nabla f(x, y) = \mathbf{0}$ . No second derivative test needed.)
- Find the extrema (max. and min.) values of  $f$  on the boundary of  $D$ .
- The biggest (smallest) of the previous steps is the absolute maximum (minimum).

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**Here is a typical exercise**

Find the absolute extrema of  $f(x, y) = 4x + 6y - x^2 - y^2$ ,  
on  $D = \{(x, y) \in \mathbb{R}^2, 0 \leq x \leq 4, 0 \leq y \leq 5\}$

Absolute minimum:  $(4, 0), (0, 0)$ .

Absolute maximum:  $(2, 3)$ .

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**Lagrange's multipliers**

- Example of the method.
- Maximization of functions subject to constraints.
- Examples.
- Generalization to more than one constraint.

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**Example: Find the rectangle of biggest area with fixed perimeter  $P_0$** 

One way to solve the problem is:

$$A(x, y) = xy, \quad P_0 = P(x, y) = 2x + 2y,$$

then  $y = P_0/2 - x$ , and replace it in  $A(x, y)$ ,

$$A(x) = \frac{P_0}{2}x - x^2.$$

The stationary points of this function are

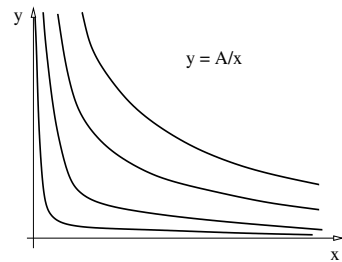
$$0 = A'(x) = \frac{P_0}{2} - 2x, \Rightarrow x = \frac{P_0}{4}, \Rightarrow y = \frac{P_0}{4}.$$

So the answer is the square of side

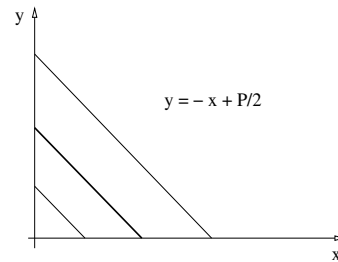
$$x = y = \frac{P_0}{4}.$$

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### Idea behind the Lagrange multipliers method



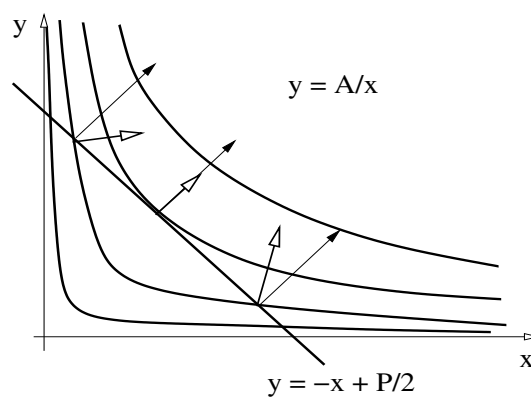
Level curves of  $A = xy$ ,



Level curves of the  
constraint  $P = 2x + 2y$ .

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### The gradient vectors of $A(x, y)$ and of the constraint $P = 2x + 2y$ are parallel at the solution



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**The same problem solved with the Lagrange multipliers method**

Find the maximum of  $A(x, y) = xy$  subject to the constraint  $P(x, y) = 2x + 2y = P_0$ .

One has to find the  $(x, y)$  such that

$$\nabla A(x, y) = \lambda \nabla P(x, y), \quad P(x, y) = P_0,$$

with  $\lambda \neq 0$ . From the first equation one has

$$\langle y, x \rangle = \lambda \langle 2, 2 \rangle, \quad \Rightarrow \quad x = 2\lambda, y = 2\lambda.$$

Then the constraint  $P_0 = 2x + 2y$  implies that  $P_0 = 8\lambda$ , so the answer is

$$x = y = \frac{P_0}{4}.$$

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**Lagrange multipliers method can be summarized as follows:**

The extrema values of  $f(x, y)$  subject to the constraint  $g(x, y) = k$  can be obtained as follows:

- Find all solutions  $(x_0, y_0)$  and  $\lambda$  of the equations

$$\begin{aligned} \nabla f(x_0, y_0) &= \lambda \nabla g(x_0, y_0), \\ g(x_0, y_0) &= k. \end{aligned}$$

- Evaluate  $f$  at every solution  $(x_0, y_0)$ . The largest and smallest values are respectively the maximum and minimum values of  $f$  subject to the constraint  $g = k$ .

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### Lagrange multipliers method for functions of three variables

The extrema values of  $f(x, y, z)$  subject to the constraint  $g(x, y, z) = k$  can be obtained as follows:

- Find all solutions  $(x_0, y_0, z_0)$  and  $\lambda$  of the equations

$$\begin{aligned}\nabla f(x_0, y_0, z_0) &= \lambda \nabla g(x_0, y_0, z_0), \\ g(x_0, y_0, z_0) &= k.\end{aligned}$$

- Evaluate  $f$  at every solution  $(x_0, y_0, z_0)$ . The largest and smallest values are respectively the maximum and minimum values of  $f$  subject to the constraint  $g = k$ .

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### Example: Find the rectangular box of maximum volume for fixed area.

The function is  $V(x, y, z) = xyz$ . The constraint function is  $A(x, y, z) = 2xy + 2xz + 2yz$ . The constraint is  $A(x, y, z) = A_0$ .

Find the  $(x, y, z)$  solutions of

$$\begin{aligned}\nabla V &= \lambda \nabla A, \\ A &= A_0.\end{aligned}$$

These equations are:

$$\begin{aligned}yz &= 2\lambda(z + y), \\ xz &= 2\lambda(x + z), \\ xy &= 2\lambda(x + y), \\ A_0 &= 2(xy + xz + zy).\end{aligned}$$

The solution is  $x = y = z = \sqrt{A_0/6}$ .

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**Example: Find the extrema values of**

$f(x, y) = x^2 + y^2/4$  **in the circle**  $x^2 + y^2 = 1$

Then,  $f(x, y) = x^2 + y^2/4$ , and  $g(x, y) = x^2 + y^2$ . The equations are:

$$\begin{aligned} \nabla f = \lambda \nabla g, & \quad \Rightarrow \quad \langle 2x, y/2 \rangle = \lambda \langle 2x, 2y \rangle, \\ g = 1, & \quad \Rightarrow \quad x^2 + y^2 = 1. \end{aligned}$$

Which imply

$$\begin{aligned} x = \lambda x, & \quad \Rightarrow \quad (1 - \lambda)x = 0, \\ y/2 = 2\lambda y, & \quad \Rightarrow \quad (1/4 - \lambda)y = 0, \\ x^2 + y^2 = 1. & \end{aligned}$$

The solutions are:  $P = (0, \pm 1)$ , and  $P = (\pm 1, 0)$ . Then:

$f(0, \pm 1) = 1/4$ , absolute minimum in the circle.

$f(\pm 1, 0) = 1$ , absolute maximum in the circle.

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**Generalization to two constraints**

The extrema values of  $f(x, y, z)$  subject to the constraints  $g(x, y, z) = k_1$  and  $h(x, y, z) = k_2$  can be obtained as follows:

- Find all solutions  $(x_0, y_0, z_0)$  and  $\lambda$  of the equations

$$\begin{aligned} \nabla f(x_0, y_0, z_0) &= \lambda \nabla g(x_0, y_0, z_0) + \mu \nabla h(x_0, y_0, z_0), \\ g(x_0, y_0, z_0) &= k_1, \\ h(x_0, y_0, z_0) &= k_2. \end{aligned}$$

- Evaluate  $f$  at every solution  $(x_0, y_0, z_0)$ . The largest and smallest values are respectively the maximum and minimum values of  $f$  subject to the constraint  $g = k_1$  and  $h = k_2$ .