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- Review: Decomposition of a polynomial.
- Slide 1
- Integration of rational functions: Cases I IV.
- Examples.
- The three main integrals.

$$
\frac{P_n(x)}{Q_m(x)} = S_p(x) + \frac{R_q(x)}{Q_m(x)}.
$$

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with $p = n - m$ and $0 \le q < m$.

Quotients of polynomials can always be integrated

They can be reduced into one of four cases

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There are four possible cases in the decomposition of a rational function

I: The denominator is a product of distinct linear factors.

II: The denominator is a product of linear factors, some of which are repeated.

III: The denominator contains irreducible quadratic factors, none of which are repeated.

IV: The denominator contains irreducible quadratic factors, some of which are repeated.

Case I: The denominator is a product of distinct linear factors

$$
\int \frac{2x^2 + 5x - 1}{x(x - 1)(x + 2)} dx.
$$

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Case II: The denominator is a product of linear factors, some of which are repeated

$$
\int \frac{x^2 + 2x + 3}{(x - 1)(x + 1)^2} \, dx
$$

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Case III: The denominator contains irreducible quadratic factors, none of which are repeated

$$
\int \frac{3x^2 + 2x - 2}{(x - 1)(x^2 + x + 1)} dx
$$

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Case IV: The denominator contains irreducible quadratic factors, some of which are repeated

$$
\int \frac{x^4 - x^3 + 2x^2 - x + 2}{(x - 1)(x^2 + 2)^2} \, dx
$$

Every polynomial can be decomposed into a product of polynomials of degree one and two

Theorem 1 Every polynomial $Q_m(x)$ with $m \geq 0$ and

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real coefficients can be decomposed as $Q_m(x) = a(x-a_1)^{\ell_1} \cdots (x-a_r)^{\ell_r} (x^2 + b_1 x + c_1)^{m_1} \cdots (x^2 + b_s x + c_s)^{m_s}.$ with $m = \ell_1 + \cdots + \ell_r + m_1 + \cdots + m_s$.

The a_1, \dots, a_r are roots of $Q_m(x)$, that is, $Q_m(a_i) = 0$, for $i = 1, \dots, r$.

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The problem of integrate a rational function reduces to that of calculating integrals of the form:

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$$
I_1 = \int \frac{dx}{(x+a)^m},
$$

$$
I_2 = \int \frac{x \, dx}{(x^2 + bx + c)^m}, \quad I_3 = \int \frac{dx}{(x^2 + bx + c)^m}.
$$

The solution for I_1 is:

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$$
I_1 = \int \frac{dx}{(x+a)^m} = \begin{cases} \ln(|x+a|) + c & m = -1, \\ \frac{1}{(1-m)(x+a)^{m-1}} + c & m \neq -1 \end{cases}
$$

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The integrals I_2 and I_3 can be transformed into the following:

$$
\tilde{I}_2 = \int \frac{u \, du}{(u^2 + \alpha^2)^m}, \quad \tilde{I}_3 = \int \frac{du}{(u^2 + \alpha^2)^m}.
$$

with the substitution

$$
u = x + \frac{b}{2},
$$
 $\alpha = \frac{1}{2}\sqrt{4c - b^2}.$

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The solution of \tilde{I}_2 is: $\tilde{I}_2 = \int \frac{u \, du}{\sqrt{u^2 + v^2}}$ $\frac{d^{2}u}{(u^{2}+\alpha^{2})^{m}}=$ $\begin{pmatrix} 1 \end{pmatrix}$ $\frac{1}{2}\ln(u^2 + \alpha^2) + c$ $m = -1$, $\frac{1}{2(1-m)(u^2+\alpha^2)^{m-1}}+c \quad m \neq -1/$

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The solution of \tilde{I}_3 is:

$$
\tilde{I}_3 = \int \frac{du}{(u^2 + \alpha^2)} = \frac{1}{\alpha} \arctan\left(\frac{u}{\alpha}\right) + c, \quad m = 1.
$$

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The case $m > 1$ is reduced to the case $m = 1$ by the following recursive formula

$$
\int \frac{du}{(u^2 + \alpha^2)^m} = \frac{1}{2(m-1)\alpha^2} \frac{u}{(u^2 + \alpha^2)^m} + \frac{2m-3}{2(m-1)\alpha^2} \int \frac{du}{(u^2 + \alpha^2)^{(m-1)}}.
$$

So, we have integrated all possible cases!

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The integral of algebraic functions is not always an algebraic function

Definition of logarithm:

$$
\int_1^x \frac{1}{t} dt =: \ln(x).
$$

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Definition of elliptic function:

$$
\int_0^x \frac{dt}{\sqrt{(1-t^2)(1-k^2t^2)}} =: u(x).
$$

Numerical methods just compute finite Riemann sums for different choices of sample points

Definition 1 (Riemann sum) Let $f(x)$ be a function defined on a interval $x \in [a, b]$. The Riemann sum of order n of $f(x)$ in [a, b] is the number given by

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$$
R_n = \sum_{i=0}^{n-1} f(x_i^*) \Delta x,
$$

Given a natural number n we have introduced a partition on [a, b] given by $\Delta x = (b - a)/n$. We denoted $x_i^* \in [x_i, x_{i+1}]$ a sample point.

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Some methods use different sample points $x_i^* \in [x_i, x_{i+1}]$

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- Left point rule: $x_i^* = x_i$.
- Right point rule: $x_i^* = x_{i+1}$.
- Midpoint rule: $x_i^* = (x_{i+1} + x_i)/2$.

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.

Other methods compute the area below f in different ways

• Trapezoidal rule:

$$
A_i = [f(x_{i+1}) + f(x_i)] \frac{\Delta x}{2}.
$$

• Simpson's rule:

$$
A_i = [f(x_{i+1}) + 4f(x_i) + f(x_{i-1})] \frac{\Delta x}{3}
$$

The resulting Riemann sums are the following

• Trapezoidal rule:

• Simpson's rule: $(n = 2m \text{ even})$

$$
T_n = \left[\frac{1}{2}f(x_0) + f(x_1) + \dots + f(x_{n-1}) + \frac{1}{2}f(x_n)\right]\Delta x.
$$

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$$
T_8 = [f(x_0) + 4f(x_1)
$$

+2f(x₂) + 4f(x₃) + 2f(x₄) + 4f(x₅) + 2f(x₆)
+4f(x₇) + f(x₈)] $\frac{\Delta x}{3}$.

- Slide 19
- Improper integrals type I and II.
- Type I: Three main possibilities.
- Examples.

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Generalizations of $\int_a^b f(x) dx$ in $I = [a, b]$

Integrals on infinite domains are called improper integrals of type I

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- Type I: The interval is infinite: $I = (-\infty, b]$, or $I = [a, \infty)$ or $I = (-\infty, \infty)$.

Integrals of divergent functions on finite domains are called improper integrals of type II.

• Type II: $f(x)$ is not bounded at one or more points in [a, b]. ($f(x)$ can have a vertical asymptote in [a, b].)

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then

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Type I: Infinite domains Possibility (a): **Definition 2** If $\int_a^x f(t) dt = F(x)$ exists for all $x \ge a$, then \int^{∞} $\int_a f(t) dt = \lim_{x \to \infty} F(x).$ The integral is said to converge if $\lim_{x\to\infty} F(x)$ exists and it is finite. Otherwise the integral is said to diverge.

Type I: Infinite domains

Possibility (b):

Definition 3 If $\int_x^b f(t) dt = F(x)$ exists for all $x \leq b$,

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$$
\int_{-\infty}^{b} f(t) dt = \lim_{x \to -\infty} F(x).
$$

The integral is said to converge if $\lim_{x\to-\infty} F(x)$ exists and it is finite.

Otherwise the integral is said to diverge.

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Type I: Infinite domains

Possibility (c):

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Definition 4 If both $\int_{-\infty}^{c} f(t) dt$ and $\int_{c}^{\infty} f(t) dt$ are convergent for some $c \in \mathbb{R}$, then

$$
\int_{-\infty}^{\infty} f(t) dt = \int_{-\infty}^{c} f(t) dt + \int_{c}^{\infty} f(t) dt.
$$