

Generalized Parking Function

GaYee Park (Dartmouth)

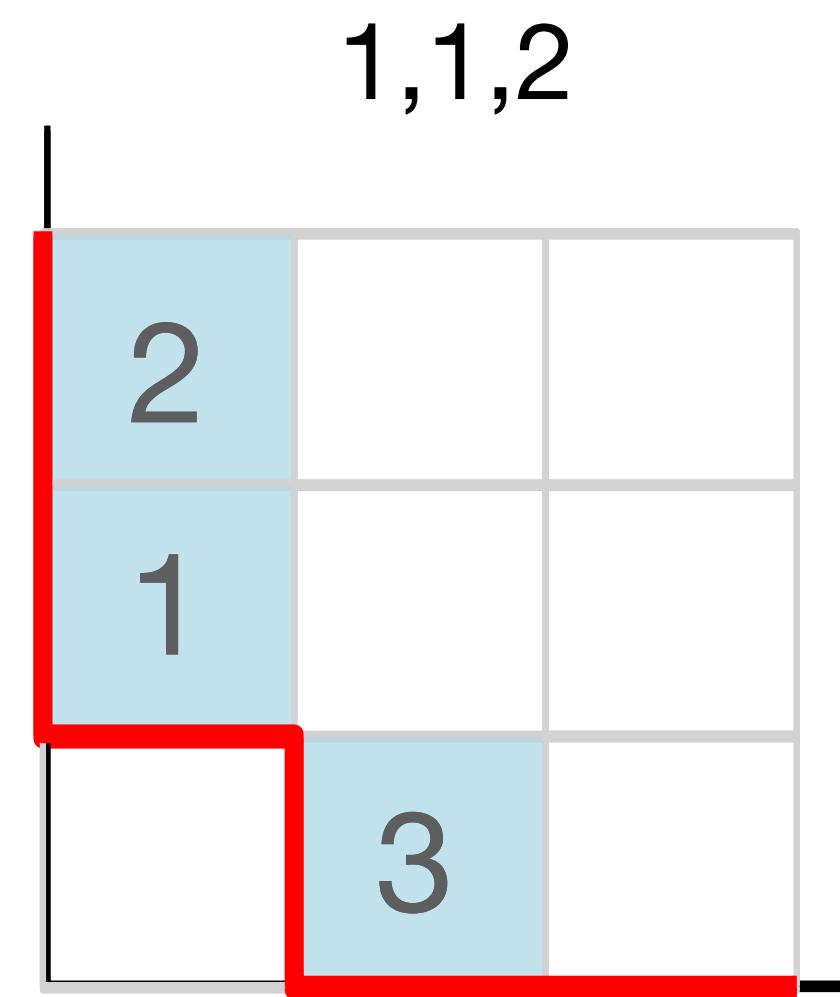
Joint work with François Bergeron and Yan Lanciault

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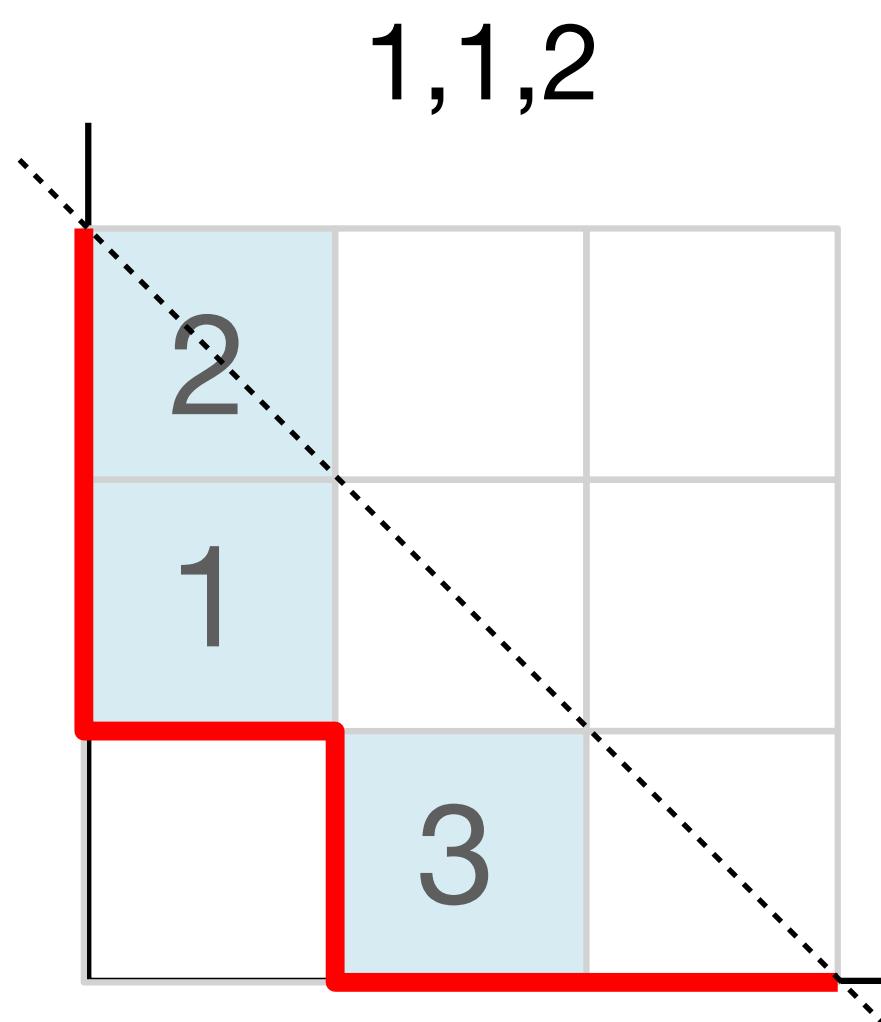
Classical Parking Function

A parking function is a sequence a_1, \dots, a_n such that if $b_1 \leq b_2 \leq \dots \leq b_n$ is the increasing rearrangement of a_1, \dots, a_n then $b_i \leq i$



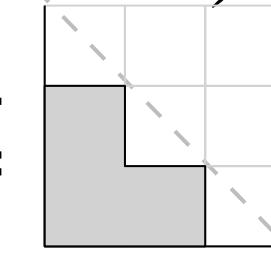
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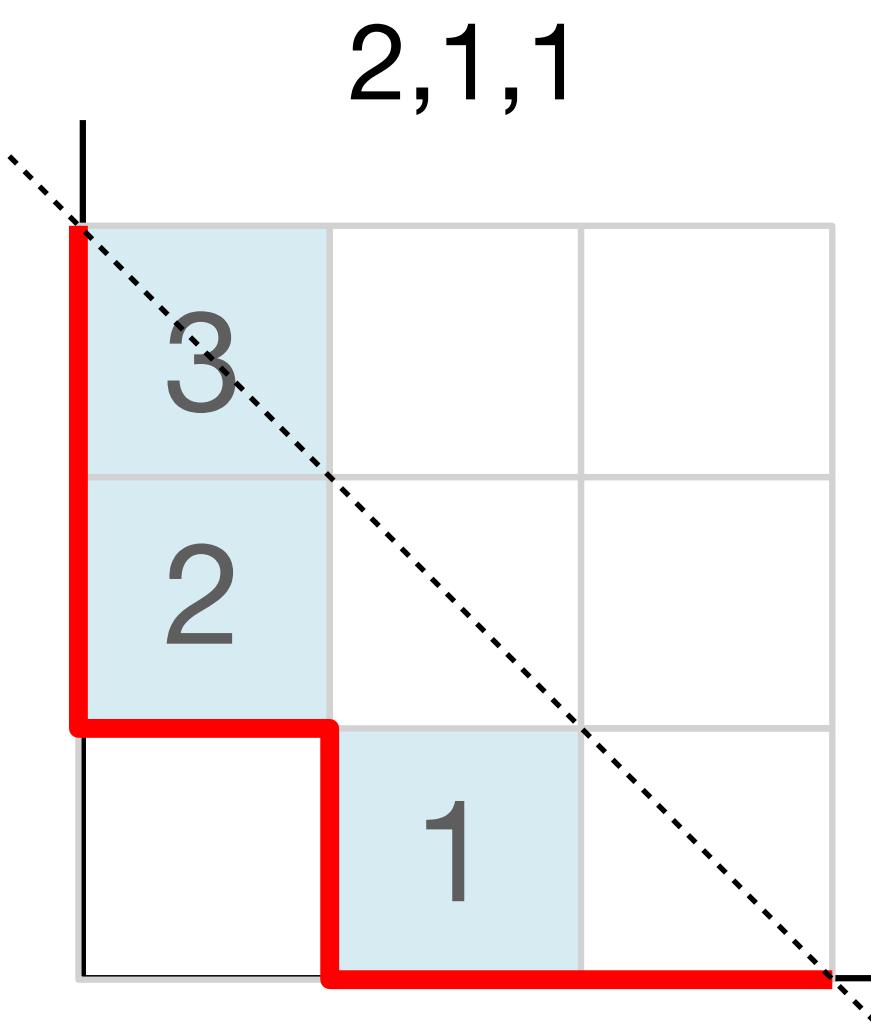


$$\text{PF}_n = \bigcup_{\alpha} \text{SYT}(\alpha + 1^n/\alpha)$$

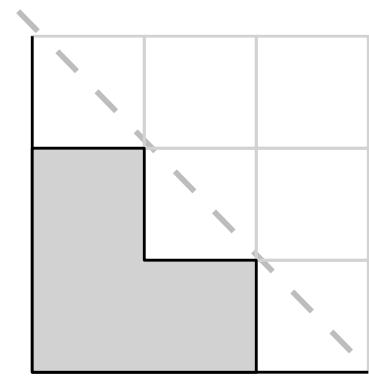
where $\alpha \subseteq$



S_n action!



Parking function Frobenius $\Rightarrow \mathcal{P}_n(\mathbf{x}) := \sum_{\alpha \subseteq \lambda} s_{\alpha+1^n/\alpha}(\mathbf{x})$, where $\lambda =$



Classical Parking Function

Frobenius character of a parking function:

$$\mathcal{P}_n(\mathbf{x}) := \sum_{\alpha \subseteq \lambda} s_{\alpha+1^n/\alpha}(\mathbf{x})$$

$$\mathcal{P}_3(\mathbf{x}) = S \begin{array}{|c|c|c|}\hline & & \\ \hline & & \\ \hline & & \\ \hline \end{array} + S \begin{array}{|c|c|c|}\hline & & \\ \hline & & \\ \hline & & \\ \hline \end{array} + S \begin{array}{|c|c|c|}\hline & & \\ \hline & & \\ \hline & & \\ \hline \end{array} + S \begin{array}{|c|c|c|}\hline & & \\ \hline & & \\ \hline & & \\ \hline \end{array} + S \begin{array}{|c|c|c|}\hline & & \\ \hline & & \\ \hline & & \\ \hline \end{array}$$

Classical Dyck path!

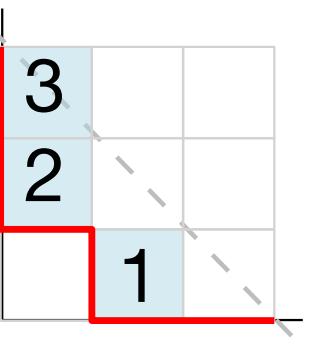
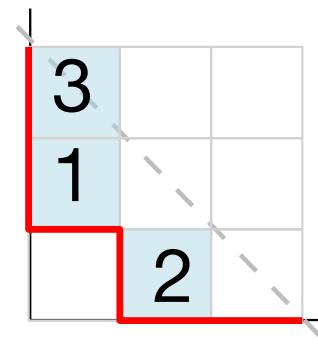
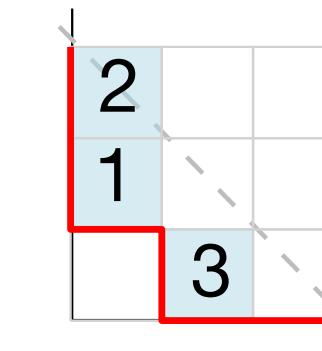
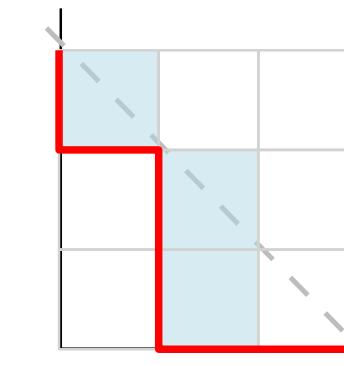
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Classical Dyck path!



1,1,2

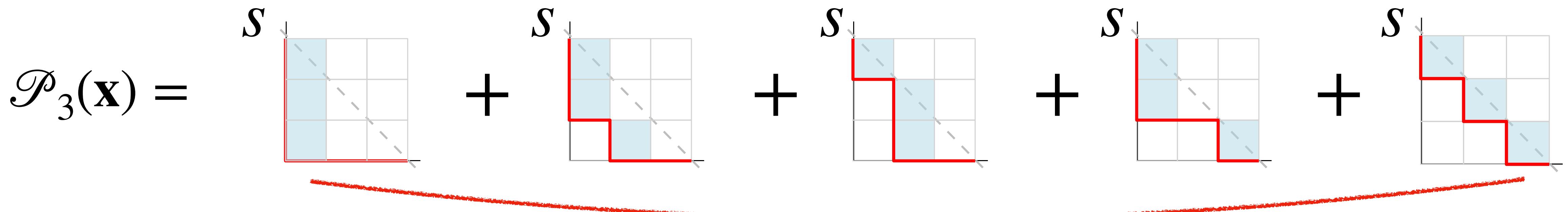
1,2,1

2,1,1

Classical Parking Function

Frobenius character of a parking function:

$$\mathcal{P}_n(\mathbf{x}) := \sum_{\alpha \subseteq \lambda} s_{\alpha+1^n/\alpha}(\mathbf{x})$$



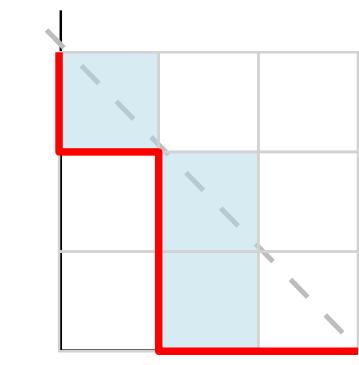
$$\mathcal{P}_3(\mathbf{x}) = S + S + S + S + S$$

Classical Dyck path!

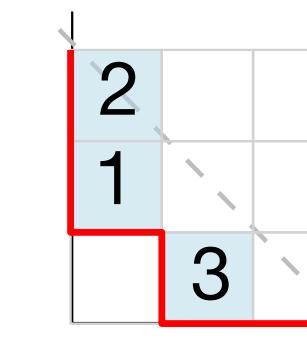
$$= e_3 + 3e_{21} + e_{111}$$

$$= \frac{1}{4} \binom{4}{3,1} e_3 + \frac{1}{4} \binom{4}{2,1,1} e_{21} + \frac{1}{4} \binom{4}{1,3} e_{111}$$

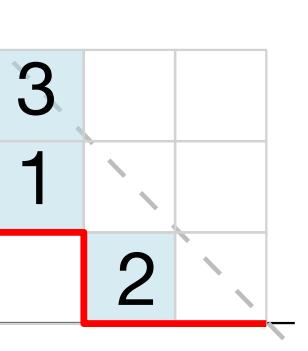
$$= \frac{1}{4} [t^3] (t^0 1 + t^1 e_1 + t^2 e_2 + t^3 e_3)^4$$



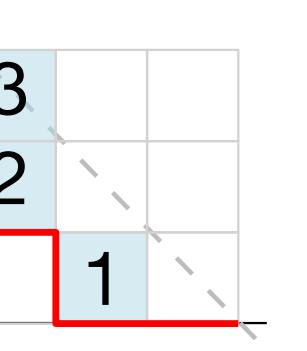
1,1,2



1,2,1



2,1,1



Classical Parking Function

Frobenius character of a parking function:

$$\mathcal{P}_n(\mathbf{x}; q) := \sum_{\alpha \subseteq \lambda} q^{|\alpha|} s_{\alpha+1^n/\alpha}(\mathbf{x})$$

$$\mathcal{P}_3(\mathbf{x}; q) = S \begin{array}{c} \text{Diagram of a 3x3 grid with a red border and light blue interior, labeled } S \end{array} + q S \begin{array}{c} \text{Diagram of a 3x3 grid with a red border and light blue interior, with a red step at the bottom labeled } q \end{array} + q^2 S \begin{array}{c} \text{Diagram of a 3x3 grid with a red border and light blue interior, with two red steps at the bottom labeled } q^2 \end{array} + q^2 S \begin{array}{c} \text{Diagram of a 3x3 grid with a red border and light blue interior, with three red steps at the bottom labeled } q^2 \end{array} + q^3 S \begin{array}{c} \text{Diagram of a 3x3 grid with a red border and light blue interior, with four red steps at the bottom labeled } q^3 \end{array}$$

Classical Dyck path!

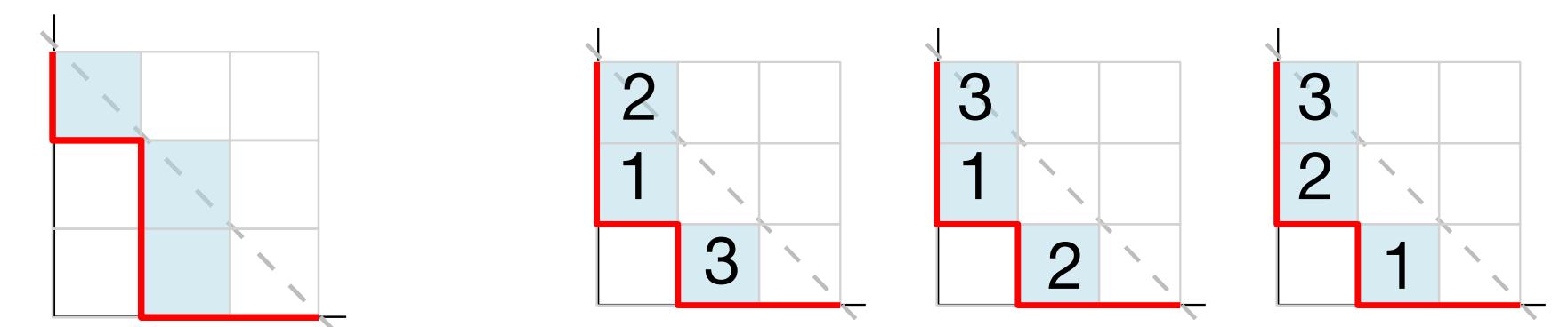
$$= e_3 + (2q^2 + q) e_{21} + q^3 e_{111}$$

$$= q^3 s_3 + (2q^3 + 2q^2 + q) s_{21} + (q^3 + 2q^2 + q + 1) s_{111}$$

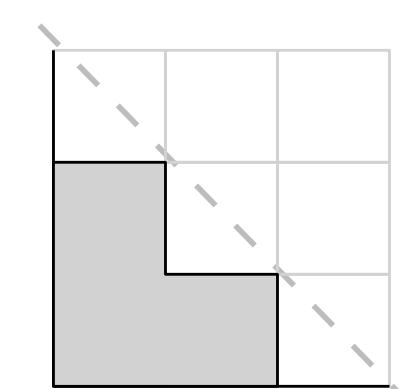
$$\langle \mathcal{P}_3(\mathbf{x}), p_1^3(\mathbf{x}) \rangle = (3+1)^{3-1}$$

$$\langle \mathcal{P}_3(\mathbf{x}), e_3(\mathbf{x}) \rangle = 5$$

We can generalize this concept by generalizing $\lambda =$



1,1,2 1,2,1 2,1,1



Diagonal Coinvariant ring

$$DR_n = \mathbb{C}[X, Y] / \left\langle \sum_{i=1}^n x_i^h y_i^k, \forall h + k > 0 \right\rangle$$

The set of polynomials $f(X, Y) \in \mathbb{C}[X, Y]$ such that for all $h + k \geq 0$, we have $\sum_{1 \leq j \leq n} \delta_{x_i}^h \delta_{y_i}^k f(X, Y) = 0$.

S_n -module: permutation acts on the indices $x_i y_i \rightarrow x_{\sigma(i)} y_{\sigma(i)}$

Shuffle Theorem (Haglund–Haiman–Loehr–Remmel–Ulyanov (2015), H–Morse–Zabrocki (2012), Carlsson–Mellit (2018)):

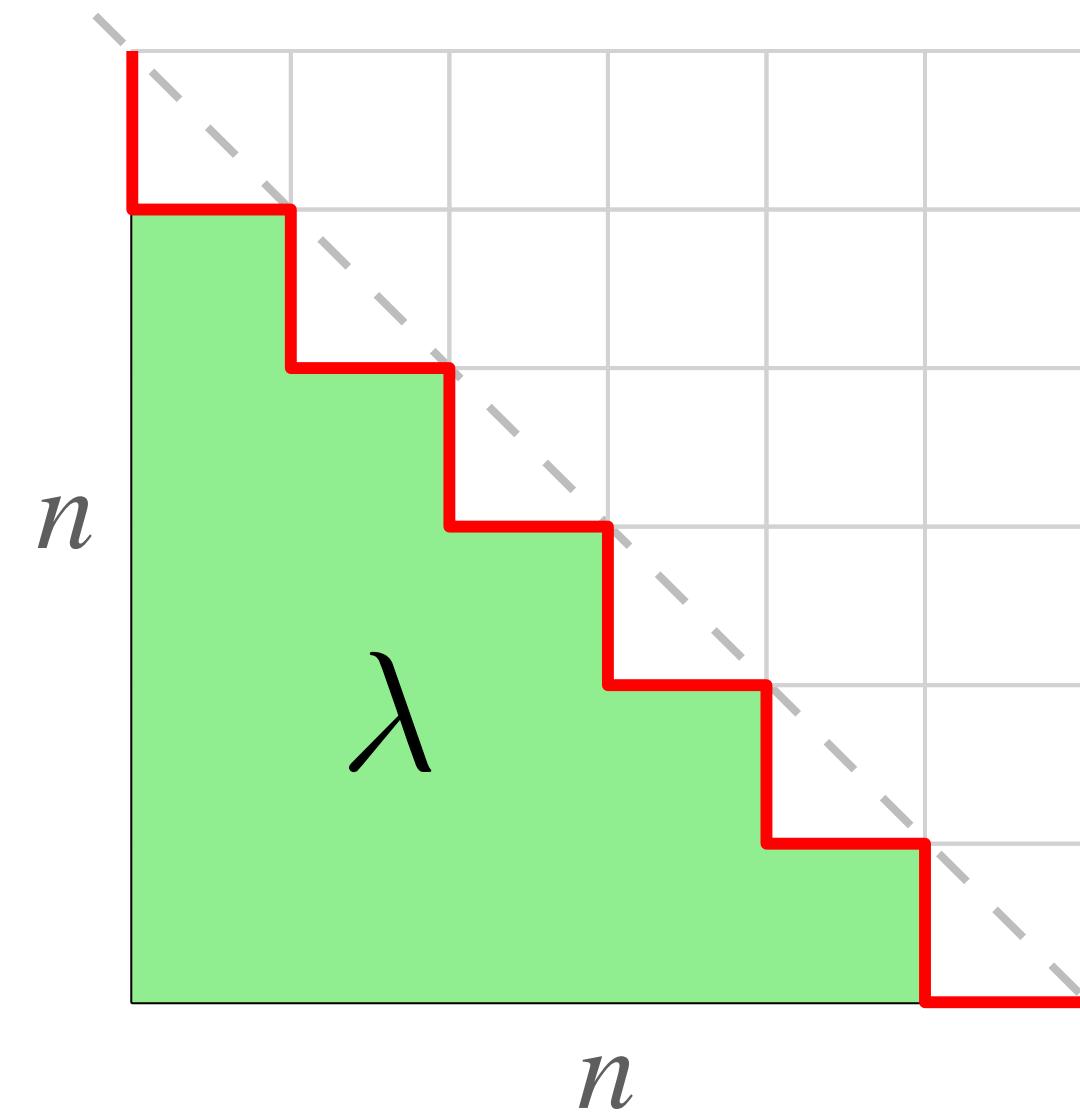
$$\mathcal{F}(DR_n; q, t) = \sum_{P \in PF_n} q^{\text{coarea}(P)} t^{\text{dinv}(P)} \chi^P = \nabla e_n$$

$$\mathcal{F}(DR_n; 1, 1) = \mathcal{P}_n(\mathbf{x})$$

$$\dim(DR_n) = (n+1)^{n-1}$$

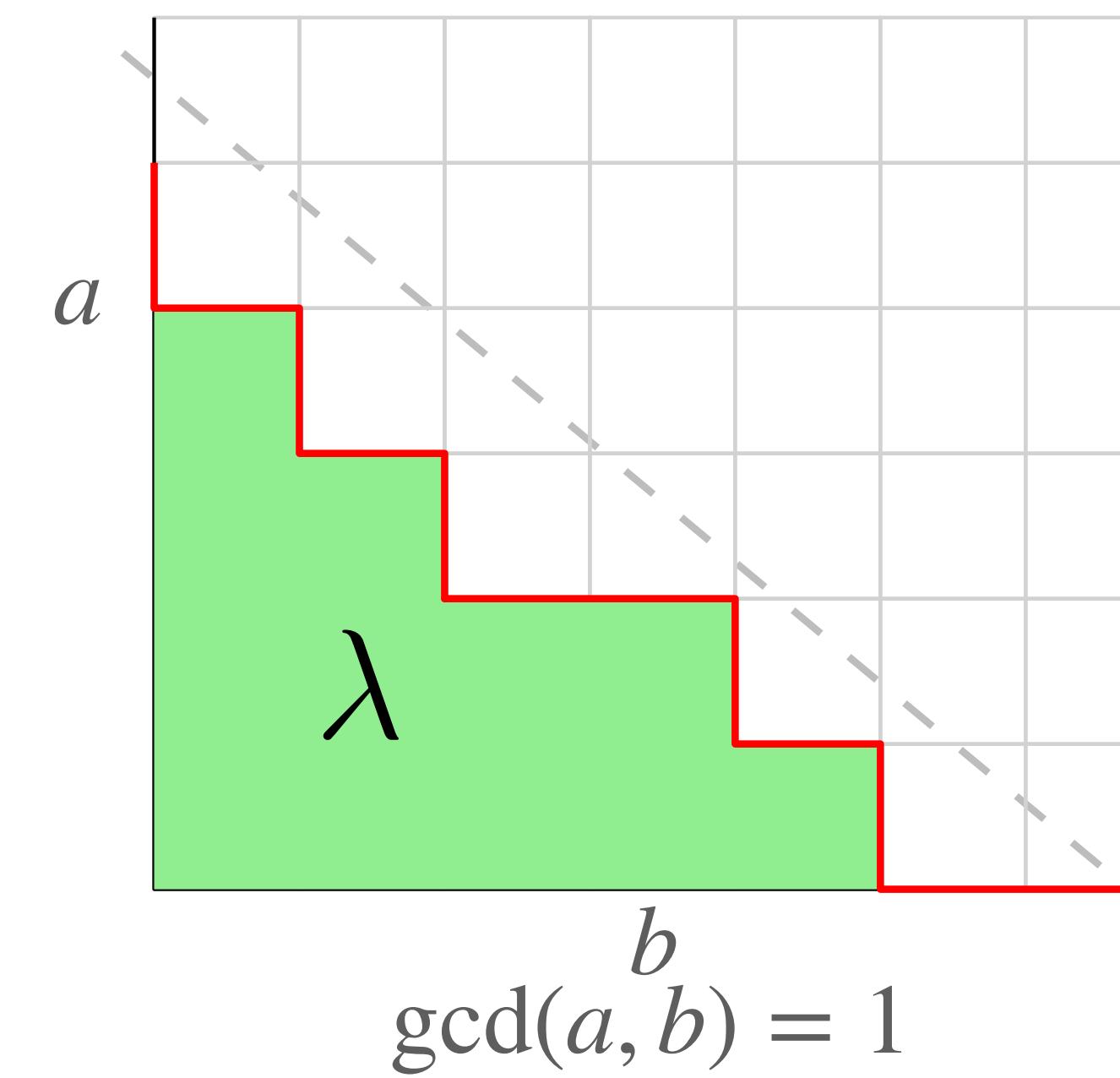
λ -Dyck path/parking function enumeration

Classical Catalan



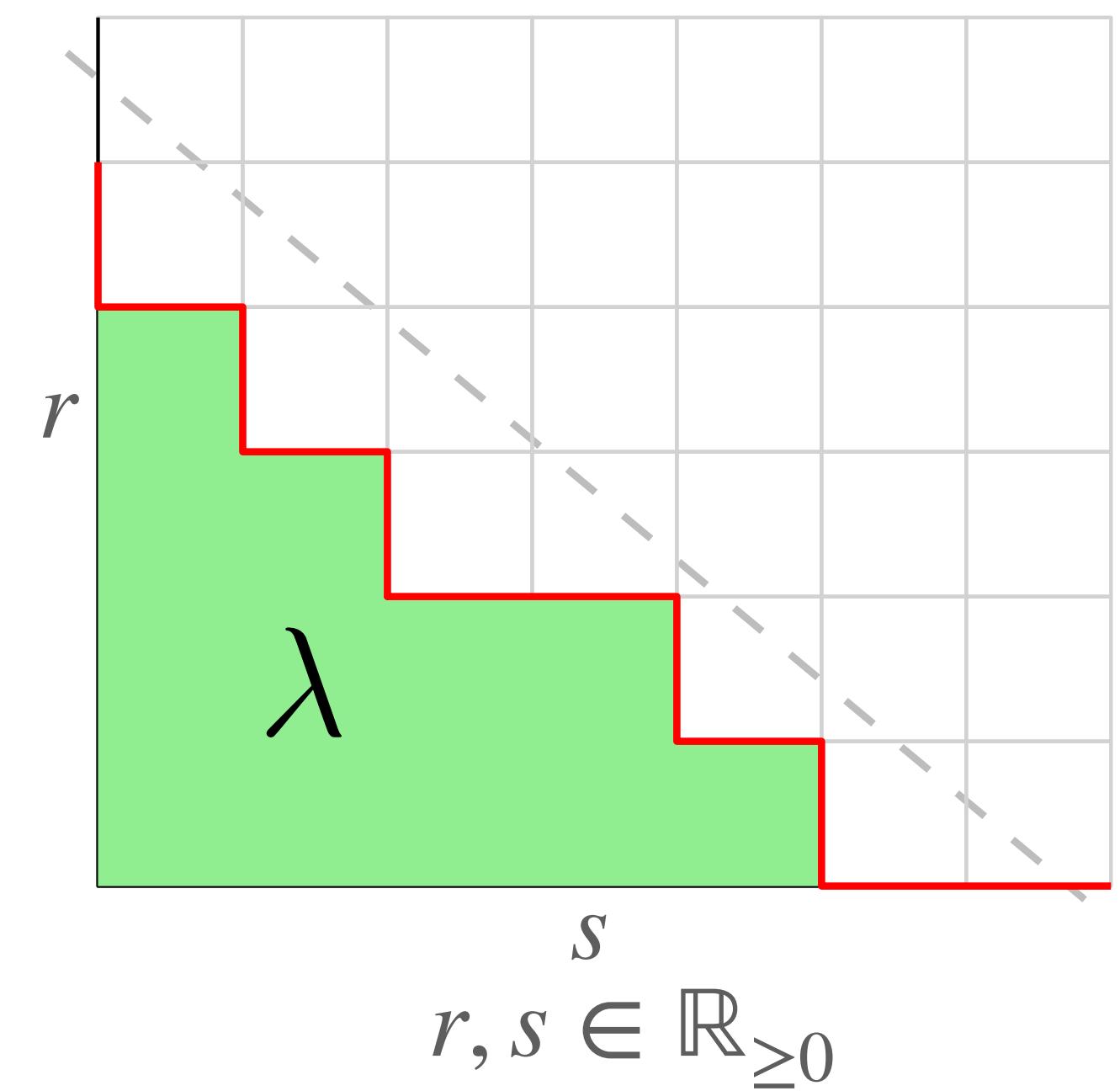
Rational Catalan

Bizley, 1954
Armstrong—Loehr—Warrington, 2014



Triangular Catalan

Blasiak—Haiman—Morse—Pun—Seelinger, 2023
Bergeron—Mazin, 2023
Elizalde—Galván, 2023



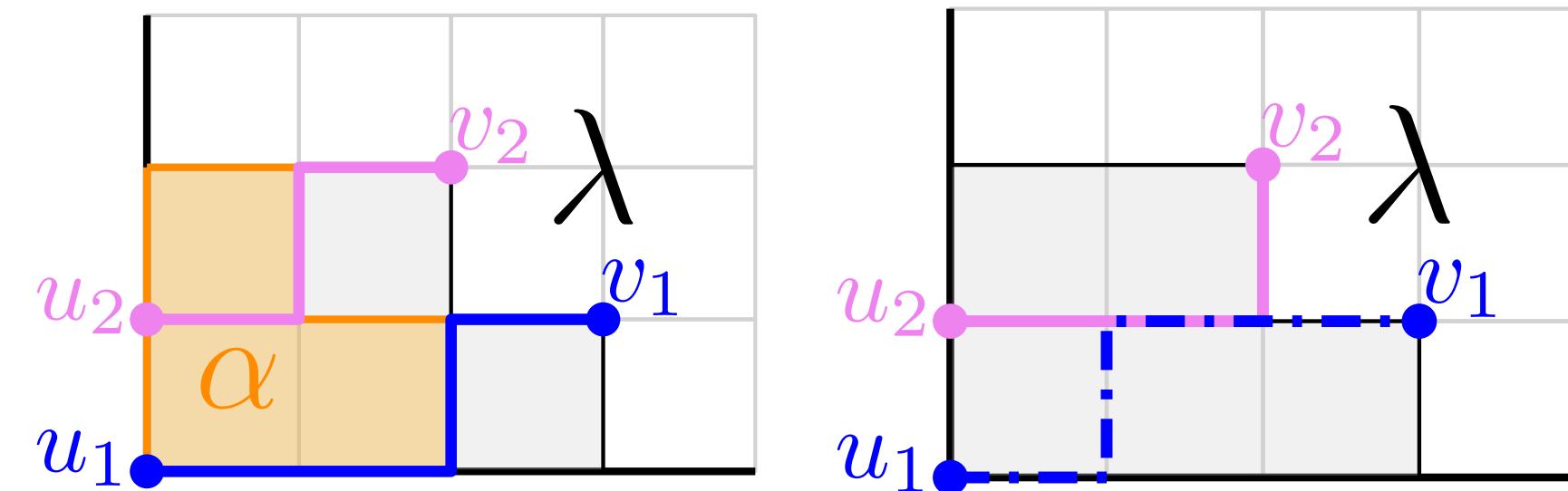
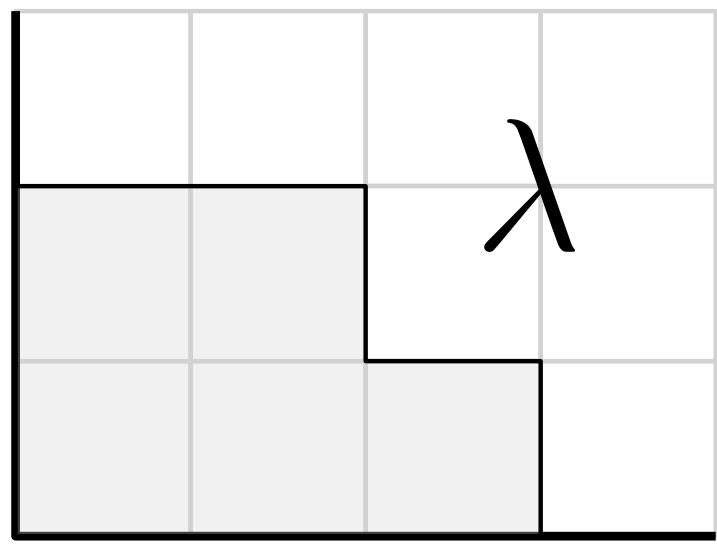
Today:

λ -Dyck path: sub-partitions α under any partition λ

λ -parking function: $\mathcal{P}_\lambda(\mathbf{x}) := \sum_{\alpha \subseteq \lambda} s_{\alpha+1^n/\alpha}(\mathbf{x})$

λ -Dyck path enumeration

Number of sub-partitions α under any partition λ



Lemma (Lindström–Gessel–Viennot, 1989)

Let G be a directed acyclic graph and $U = \{u_1, \dots, u_n\}$ and $V = \{v_1, \dots, v_n\}$ be two distinct sets of vertices that are compatible. Then the number of non-intersecting paths from $u_i \rightarrow v_i$ is $\det(p(u_i, v_j))_{1 \leq i, j \leq n}$, where $p(u_i, v_j)$ is the number of paths from $u_i \rightarrow v_j$.

Theorem (Gessel–Viennot, Loehr 1989, 2009)

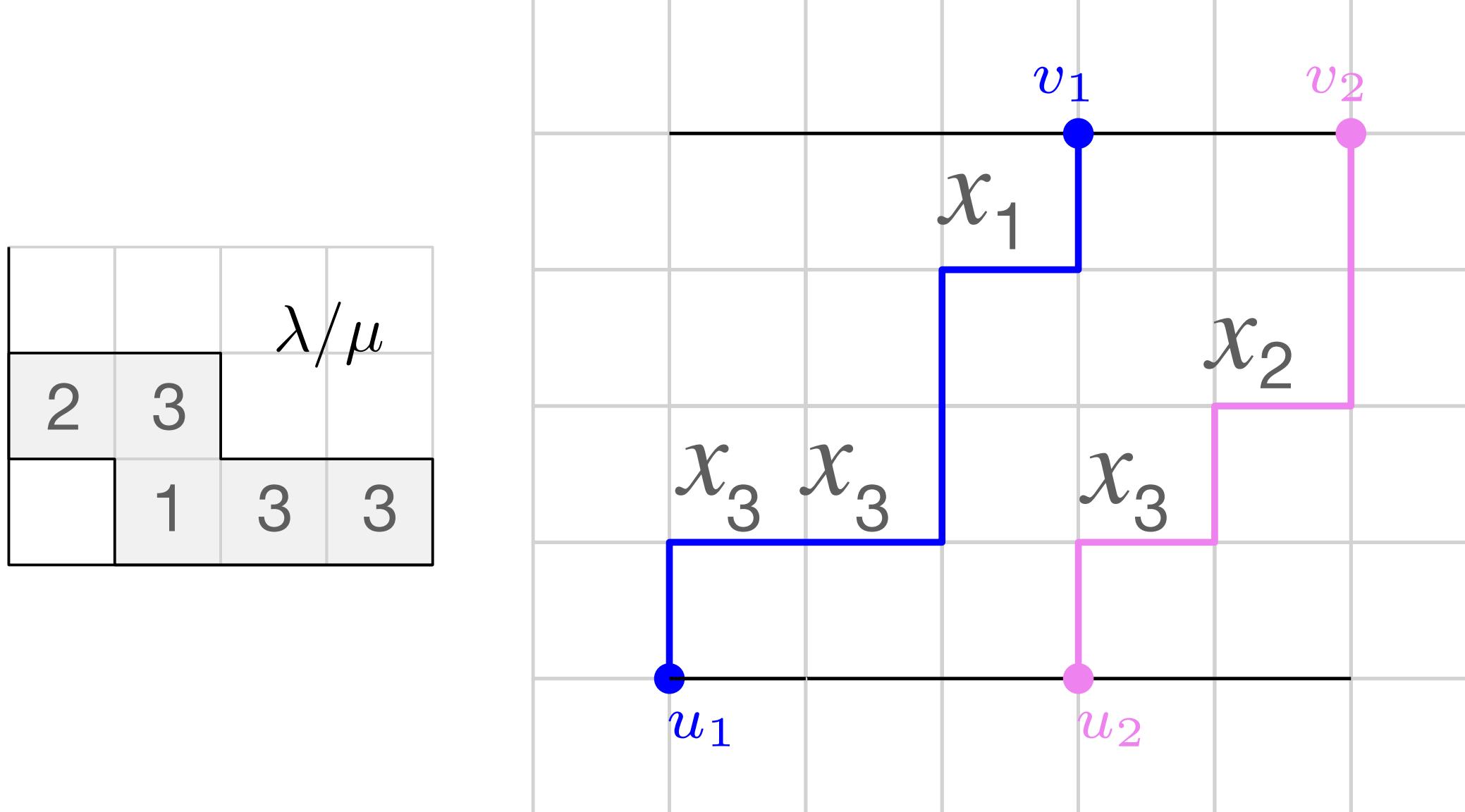
$$\sum_{\alpha \subseteq \lambda} q^{|\alpha|} = \det \left(q^{\binom{j-i+1}{2}} \binom{\lambda_j + 1}{j-i+1}_q \right)_{1 \leq i, j \leq \ell(\lambda)}$$

$$\begin{aligned} \#(u_1 \rightarrow v_1) &= \binom{4}{1} \quad \#(u_2 \rightarrow v_2) = \binom{3}{1} \\ \#(u_1 \rightarrow u_2) - \text{consecutive } \uparrow &= \binom{3}{2} \end{aligned}$$

$$\begin{aligned} \# \text{ of } \alpha \subseteq \lambda &= \binom{4}{1} \cdot \binom{3}{1} - \binom{3}{2} \\ \sum_{\alpha \subseteq \lambda} q^{|\alpha|} &= \det \begin{pmatrix} \binom{4}{1}_q & q \binom{3}{1}_q \\ 1 & \binom{3}{2}_q \end{pmatrix} \end{aligned}$$

λ -Parking function enumeration

$$\mathcal{P}_\lambda(\mathbf{x}) := \sum_{\alpha \subseteq \lambda} s_{\alpha+1^{n/\alpha}}(\mathbf{x})$$



$\#(u_1 \rightarrow v_1) = h_3(\mathbf{x})$	$\#(u_2 \rightarrow v_2) = h_2(\mathbf{x})$
$\#(u_2 \rightarrow v_1) = h_5(\mathbf{x})$	$\#(u_1 \rightarrow v_2) = h_0(\mathbf{x})$

By LGV lemma:

$$s_{(4,2)/(1)}(\mathbf{x}) = \det \begin{pmatrix} h_3(\mathbf{x}) & h_1(\mathbf{x}) \\ h_5(\mathbf{x}) & h_2(\mathbf{x}) \end{pmatrix}$$

Jacobi-Trudi Identity (1841)

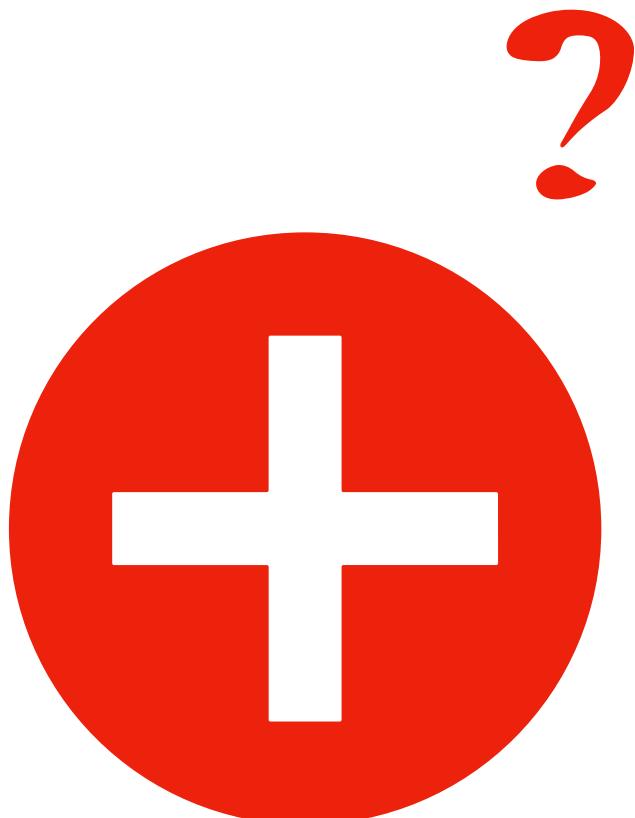
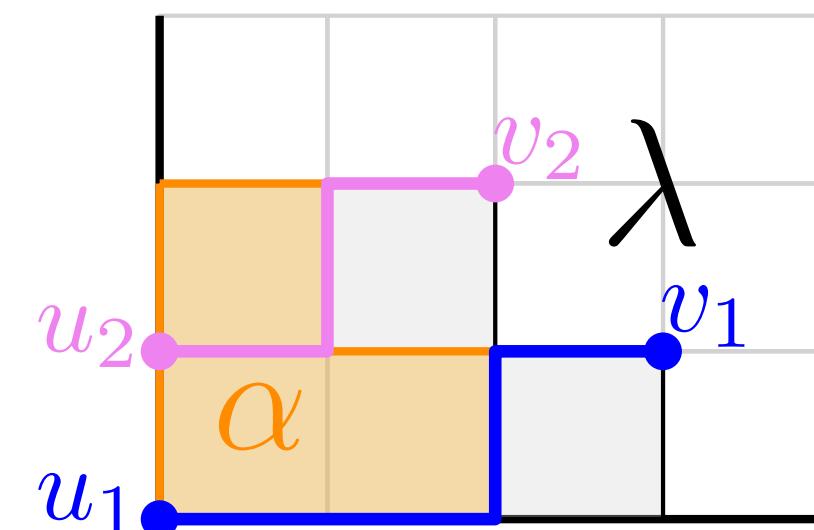
$$s_{\lambda/\mu}(\mathbf{x}) = \det \left(h_{\lambda_i - \mu_j - i + j}(\mathbf{x}) \right)_{1 \leq i, j \leq \ell(\lambda)}$$

λ -Parking function enumeration

$$\mathcal{P}_\lambda(\mathbf{x}) := \sum_{\alpha \subseteq \lambda} s_{\alpha+1^n/\alpha}(\mathbf{x})$$

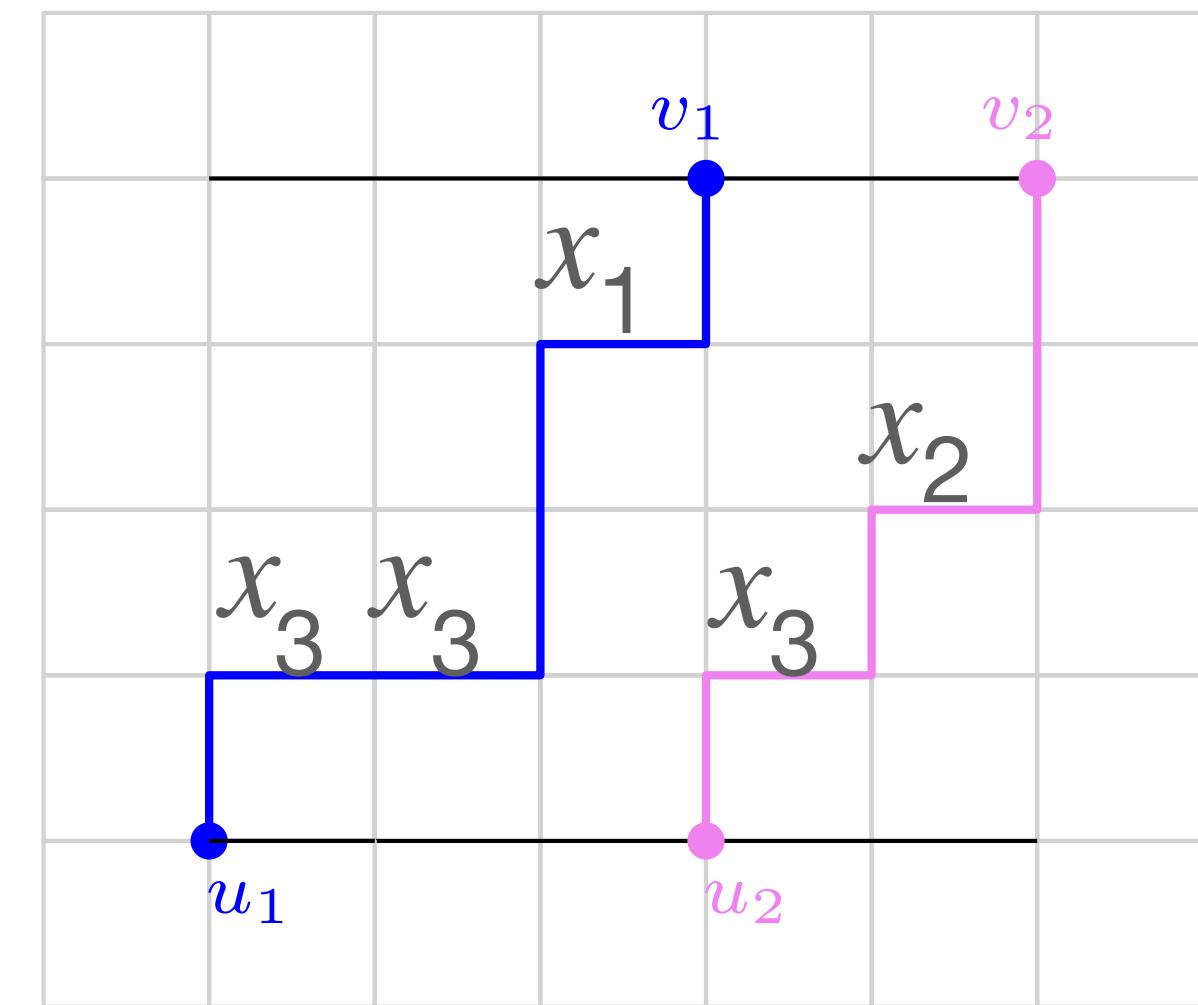
λ -Dyck path enumeration

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Jacobi-Trudi Identity

$$s_{\lambda/\mu}(\mathbf{x}) = \det (h_{\lambda_i - \mu_j - i + j}(\mathbf{x}))$$



Lemma (Lindström – Gessel – Viennot, year)

$$\# \text{ of non-intersecting paths from } u_i \rightarrow v_i = \det (p(u_i, v_j))_{1 \leq i,j \leq n}.$$

λ -Parking function enumeration

$$\mathcal{P}_\lambda(\mathbf{x}) = S + S + S + S + S + S + S + S + S$$

where S is defined as:

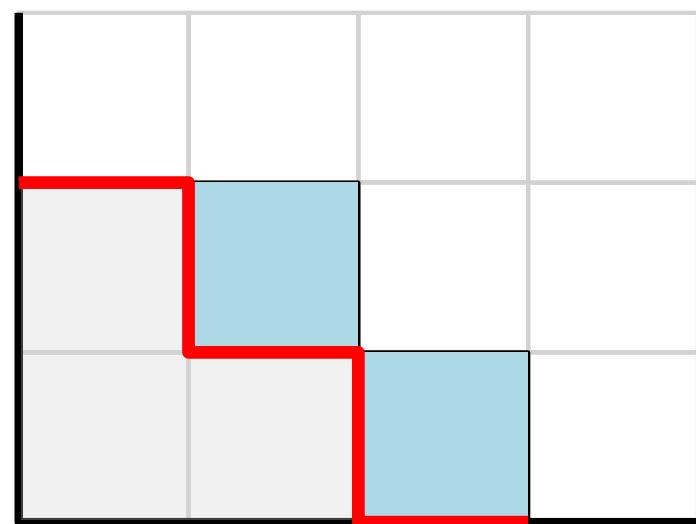
$$\mathcal{P}_\lambda(q; \mathbf{x}) := \sum_{\alpha \subseteq \lambda} q^\alpha s_{\alpha+1^n/\alpha}(\mathbf{x})$$

λ -Parking function enumeration

$$\mathcal{P}_\lambda(\mathbf{x}) = S + S + S + S + S + S + S + S + S$$

where S is a sum of terms, each consisting of a grid with colored cells (light blue and light gray) and red outlines. The grids represent parking functions of different shapes.

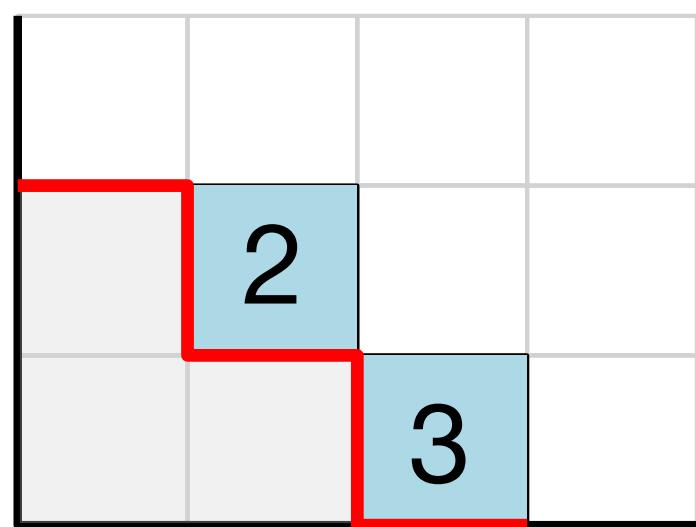
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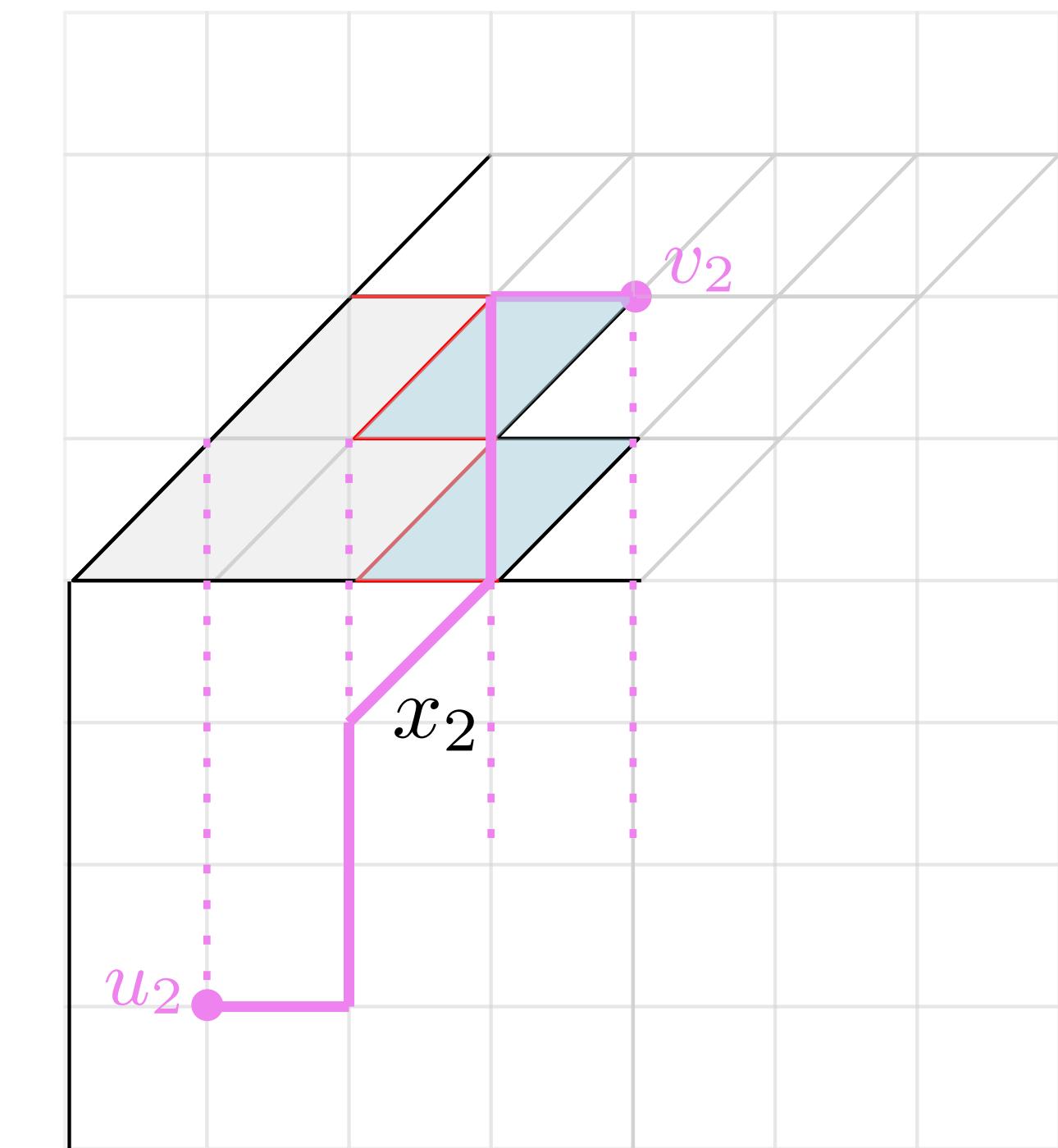
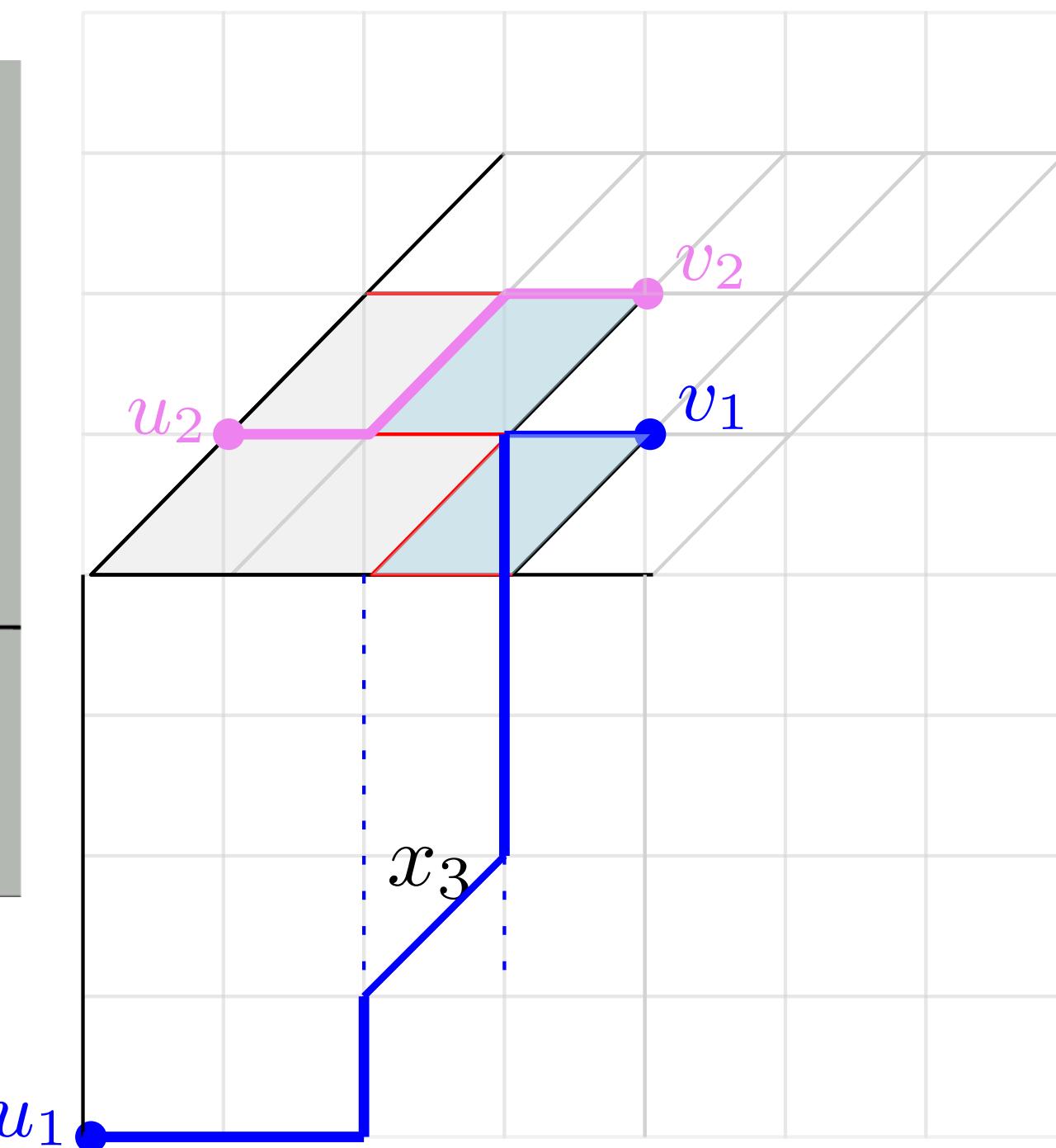
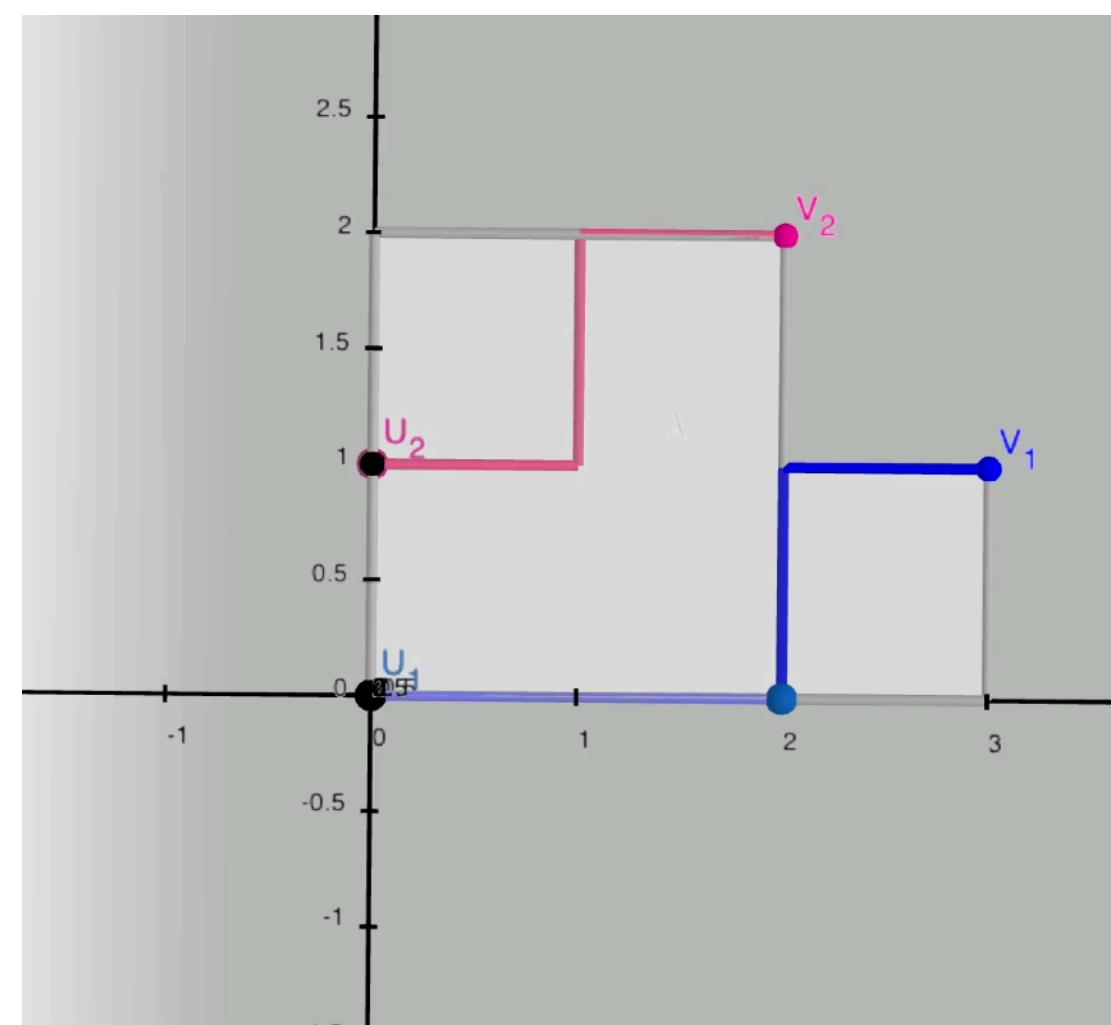
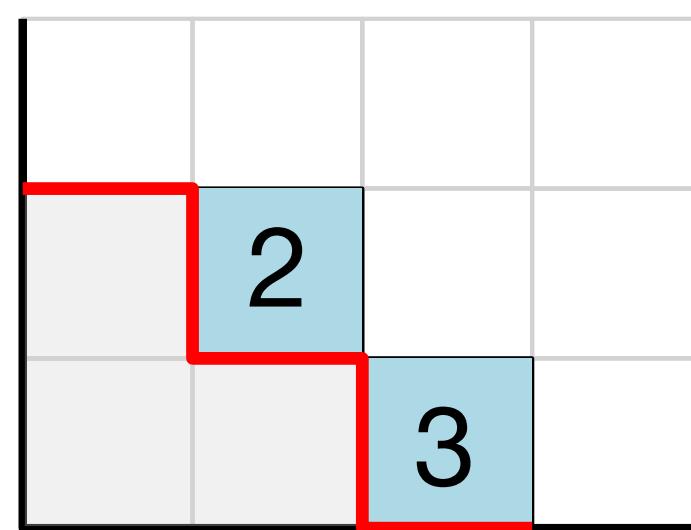
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λ -Parking function enumeration

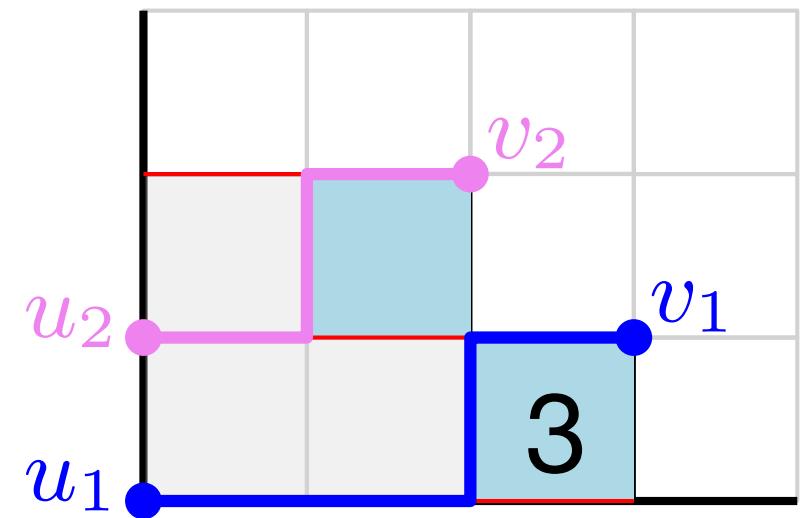
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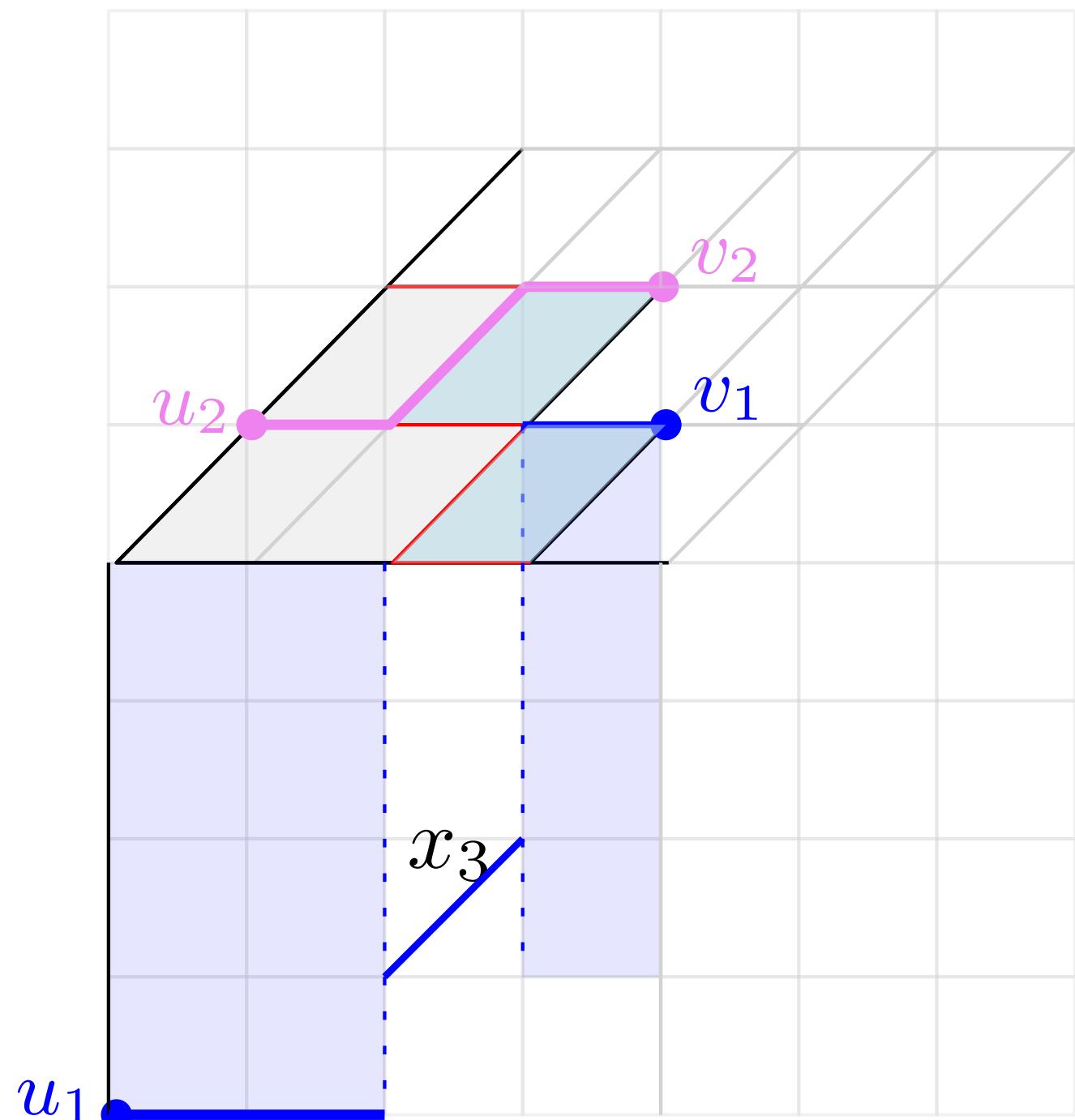
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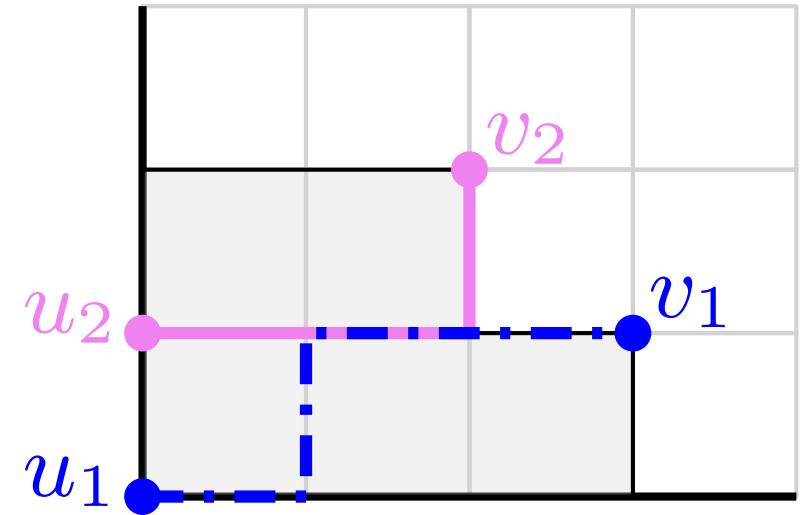
$$\#(u_1 \rightarrow v_1) = \binom{4}{1}_q \cdot h_1(\mathbf{x})$$

$$\#(u_2 \rightarrow v_2) = \binom{3}{1}_q \cdot h_1(\mathbf{x})$$



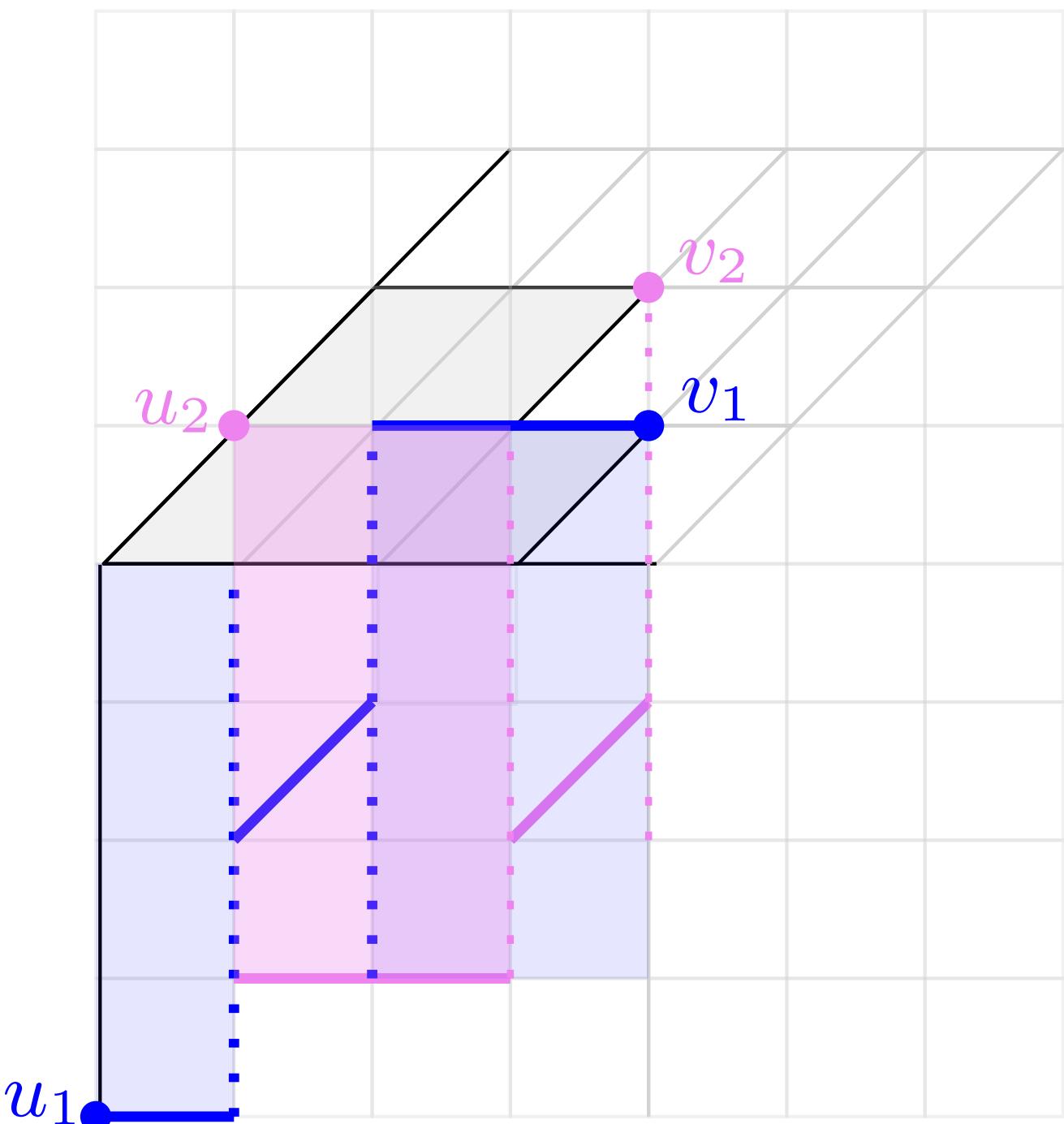
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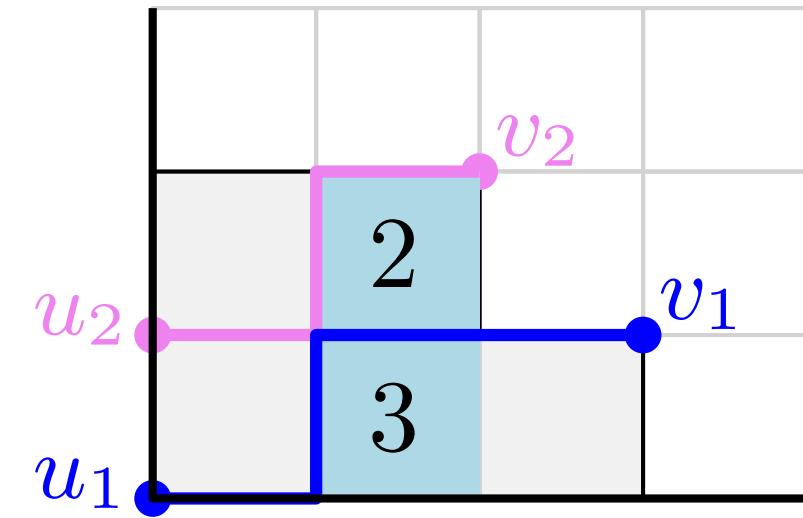
$$\#(u_2 \rightarrow v_2) = \binom{3}{1}_q \cdot h_1(\mathbf{x})$$



$$\#(u_1 \rightarrow v_2) = q \cdot \binom{3}{2}_q \cdot h_1^2(\mathbf{x})$$

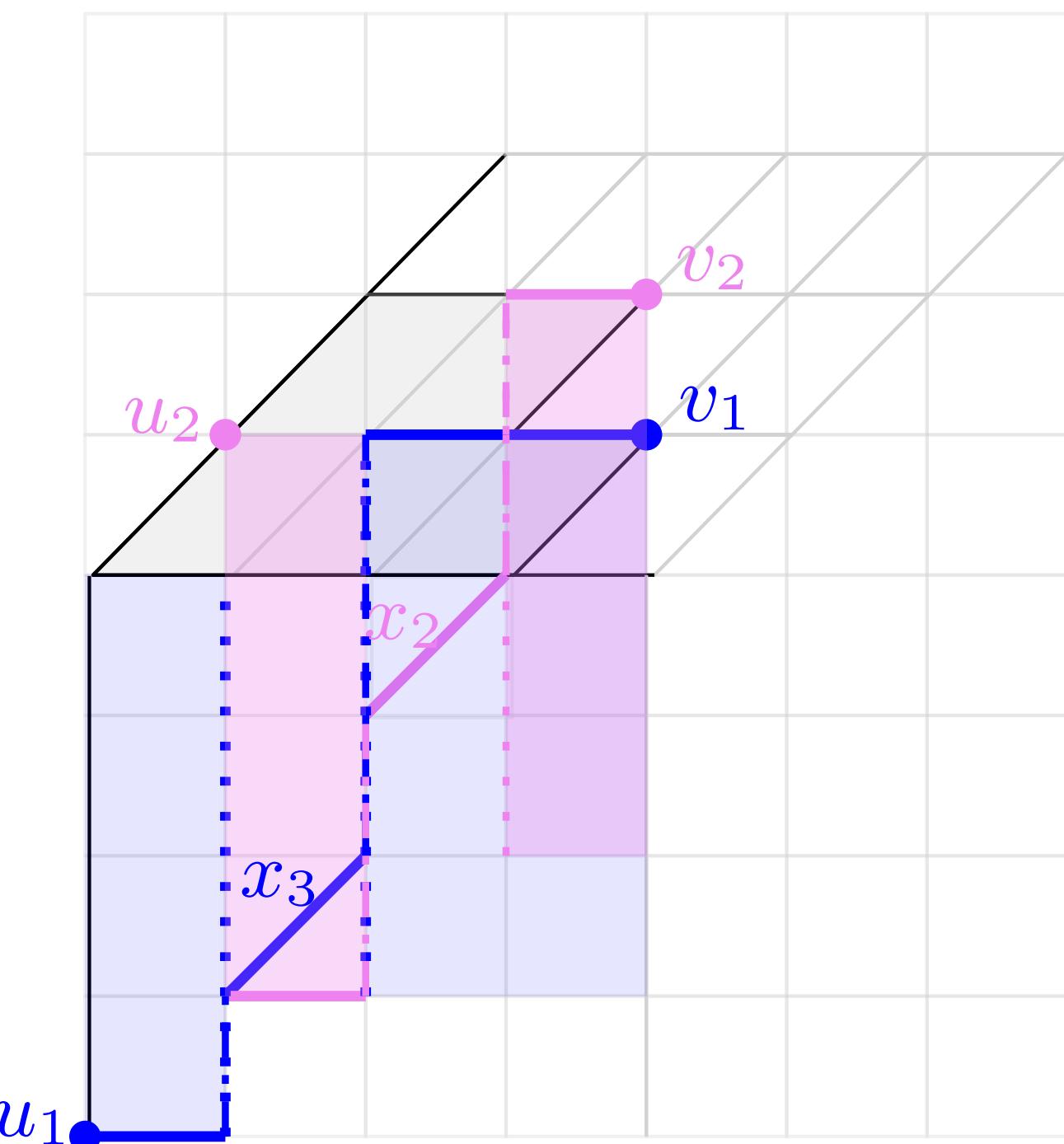
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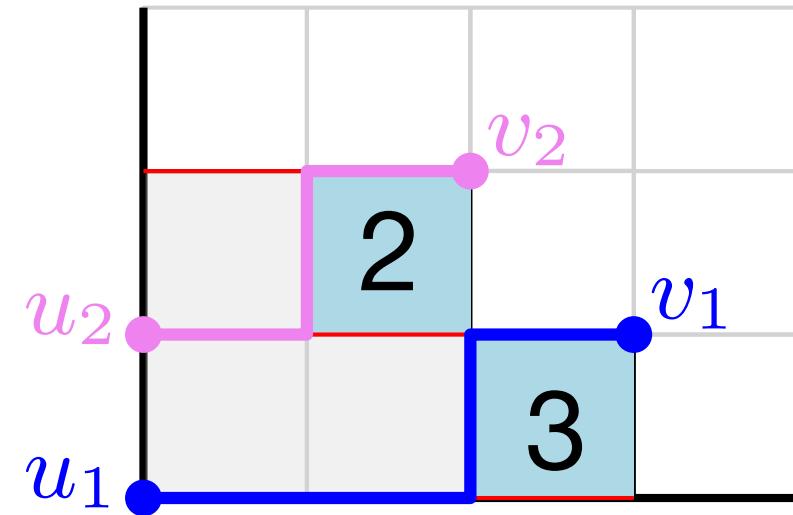
$$\#(u_2 \rightarrow v_2) = \binom{3}{1}_q \cdot h_1(\mathbf{x})$$



$$\#(u_1 \rightarrow v_2) = q \cdot \binom{3}{2}_q \cdot h_1^2(\mathbf{x}) + \binom{3}{1}_{q^2} \cdot h_2(\mathbf{x}) \quad \#(u_2 \rightarrow v_1) = 1$$

λ -Parking function enumeration

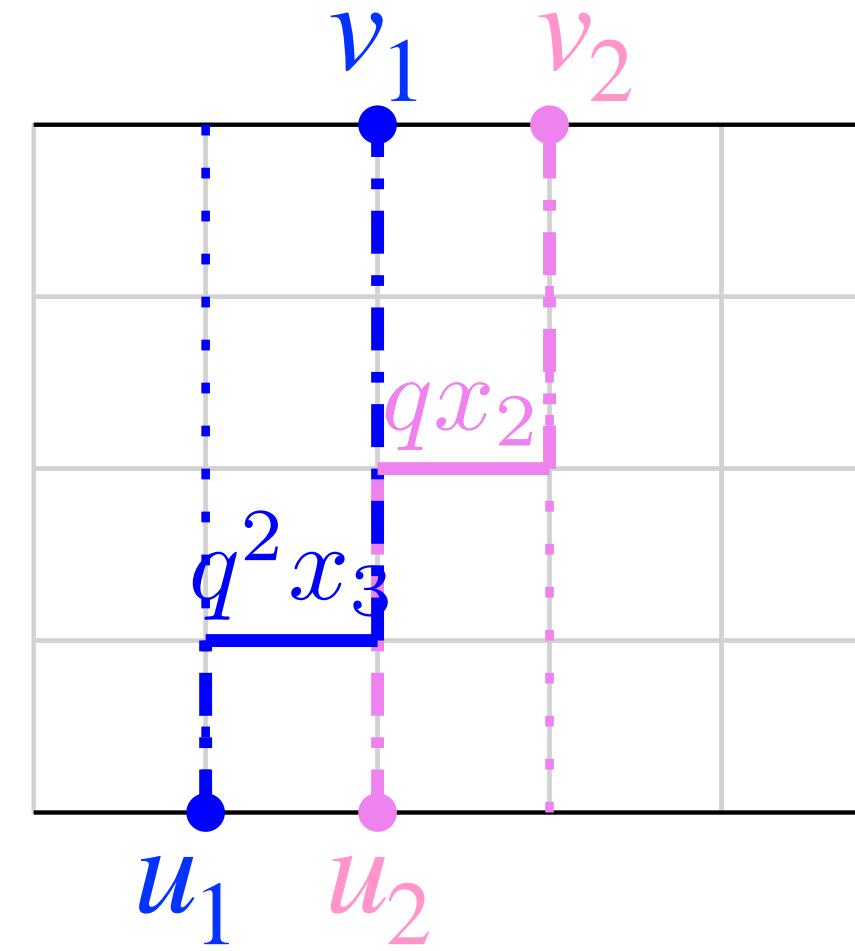
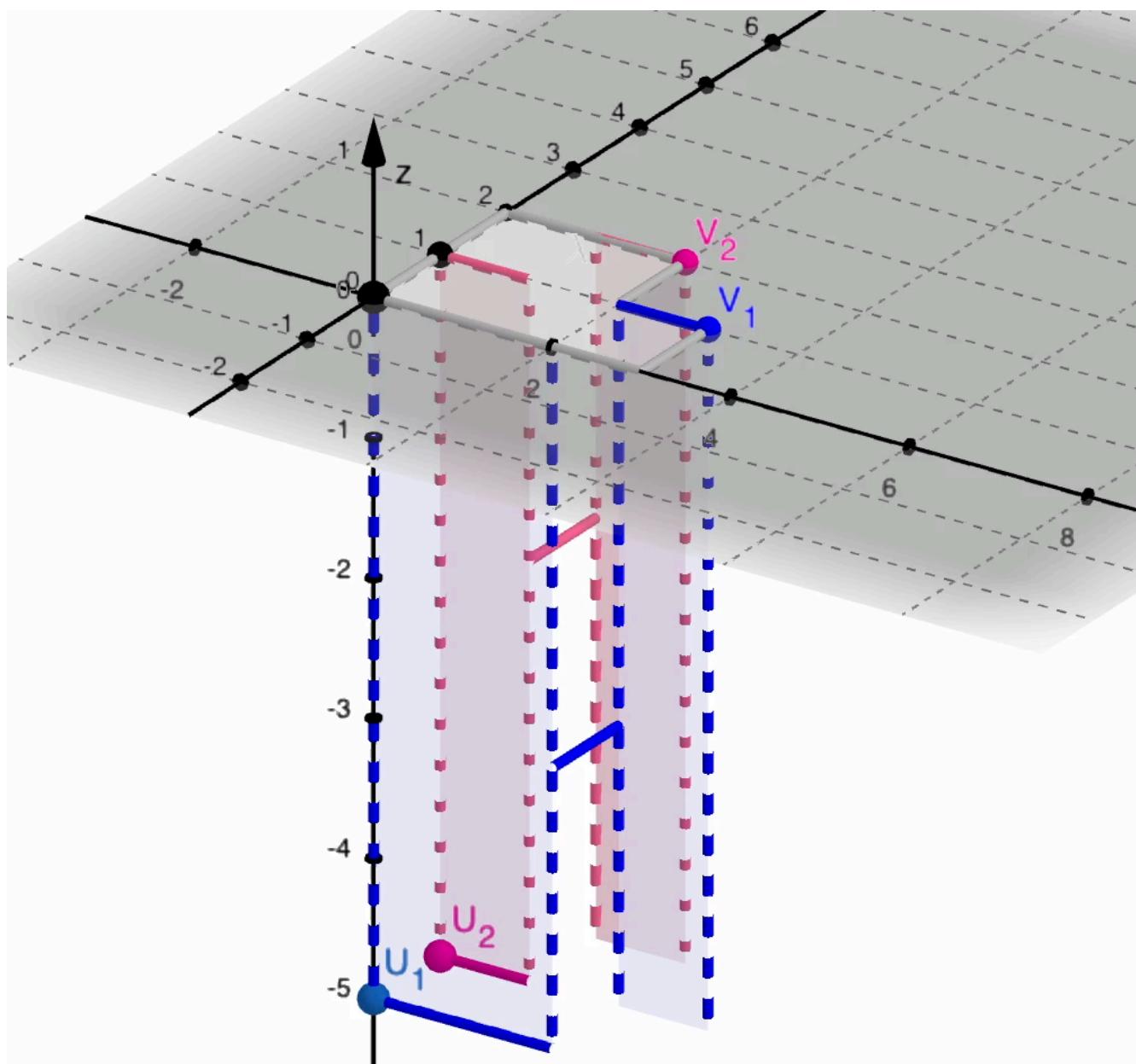
$$\mathcal{P}_\lambda(q; \mathbf{x}) := \sum_{\alpha \subseteq \lambda} q^{|\alpha|} s_{\alpha+1^n/\alpha}(\mathbf{x})$$



$$\begin{aligned} \#(u_1 \rightarrow v_1) &= \binom{4}{1}_q \cdot h_1(\mathbf{x}) \\ &= h_1[(1 + q + q^2 + q^3) \cdot \mathbf{x}] \end{aligned}$$

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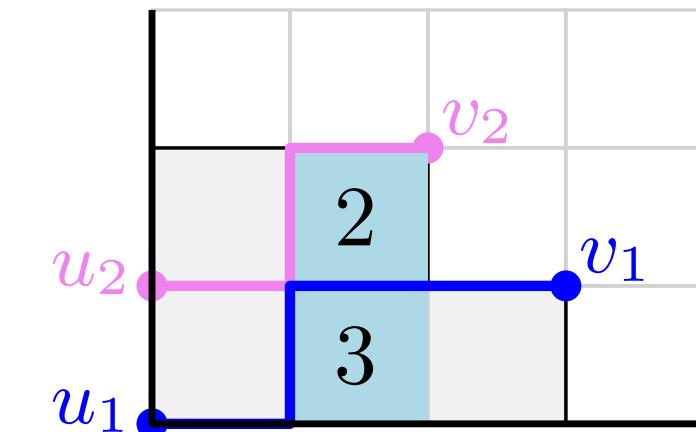
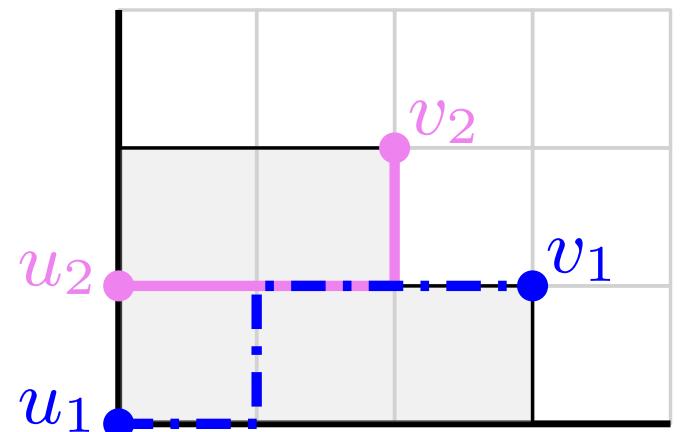


λ -Parking function enumeration

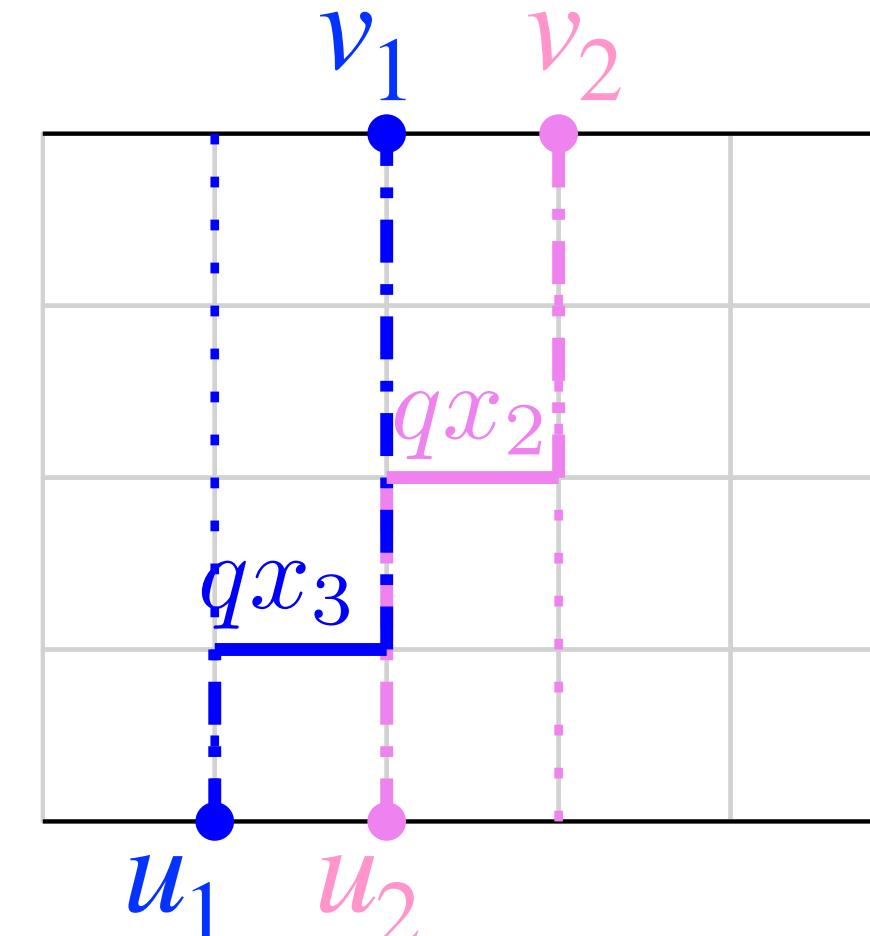
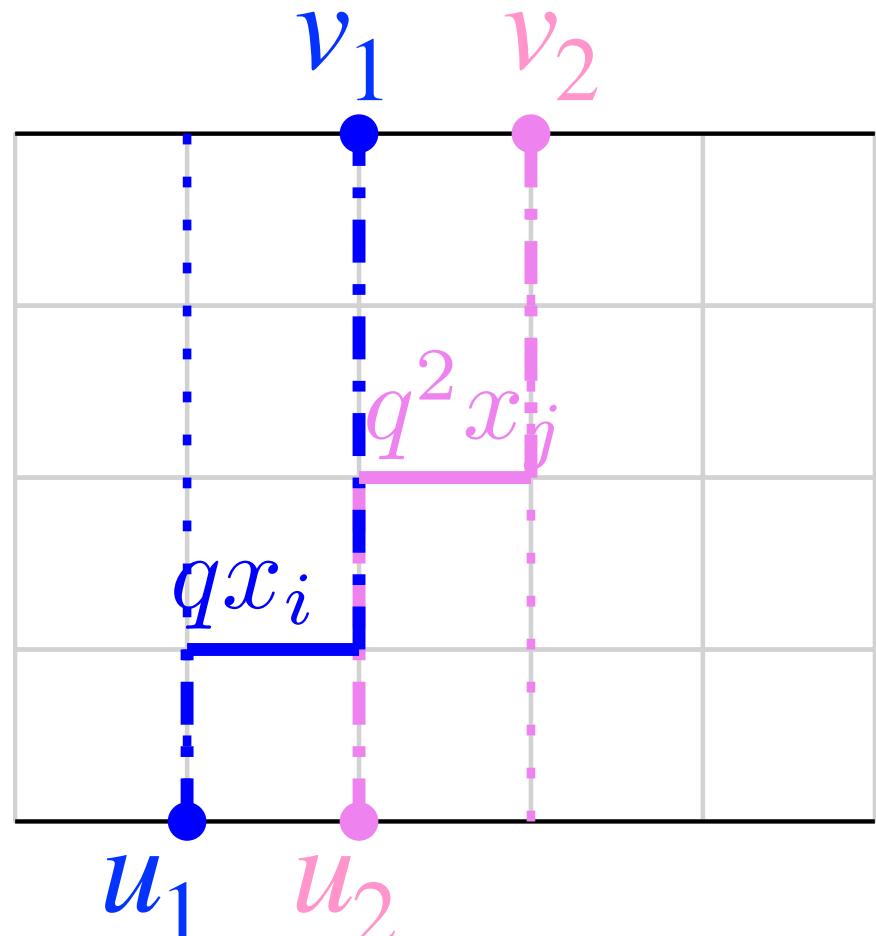
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$$\begin{aligned}\#(u_1 \rightarrow v_2) &= q \cdot \binom{3}{2}_q \cdot h_1^2(\mathbf{x}) + \binom{3}{1}_q \cdot h_2(\mathbf{x}) \\ &= h_2[(1 + q + q^2) \cdot \mathbf{x}]\end{aligned}$$



$$q^a x_i \leq q^b x_j$$

where $q^a x_i \leq q^b x_j$ if $a < b$ or $a = b$ and $i \geq j$

$$\begin{aligned}qx_3 &< q^2 x_2 \\ qx_2 &< qx_3\end{aligned}$$

λ -Parking function enumeration

$$\mathcal{P}_\lambda(q; \mathbf{x}) := \sum_{\alpha \subseteq \lambda} q^{|\alpha|} s_{\alpha+1^n/\alpha}(\mathbf{x})$$

$$\#(u_1 \rightarrow v_1) = \binom{4}{1}_q \cdot h_1(\mathbf{x})$$

$$= h_1[(1 + q + q^2 + q^3) \cdot \mathbf{x}]$$

$$\#(u_2 \rightarrow v_2) = \binom{3}{1}_q \cdot h_1(\mathbf{x})$$

$$= h_1[(1 + q + q^2) \cdot \mathbf{x}]$$

$$\#(u_1 \rightarrow v_2) = q \cdot \binom{3}{2}_q \cdot h_1^2(\mathbf{x}) + \binom{3}{1}_{q^2} \cdot h_2(\mathbf{x})$$

$$= h_2[(1 + q + q^2) \cdot \mathbf{x}]$$

By LGV Lemma, we have:

$$\mathcal{P}_\lambda(q; \mathbf{x}) = \det \begin{pmatrix} h_1[(1 + q + q^2 + q^3) \cdot \mathbf{x}] & h_2[(1 + q + q^2) \cdot \mathbf{x}] \\ 1 & h_1[(1 + q + q^2) \cdot \mathbf{x}] \end{pmatrix}$$

$$\mathcal{P}_{32}(q; \mathbf{x}) = (q^5 + 2q^4 + 2q^3 + 2q^2 + q + 1) h_{11}(\mathbf{x}) - (q^4 + q^2 + 1) h_2(\mathbf{x})$$

$$= (q^5 + q^4 + 2q^3 + q^2 + q) s_2(\mathbf{x}) + (q^5 + 2q^4 + 2q^3 + 2q^2 + q + 1) s_{11}(\mathbf{x})$$

(Bergeron – Lanciault – P. 2023+)

$$\mathcal{P}_\lambda(q; \mathbf{x}) = \det (h_{j-i+1}[(1 + \cdots + q^{\lambda_j}) \cdot \mathbf{x}])_{1 \leq i, j \leq \ell(\lambda)+1}$$

Observations

- Stabilization as n grows
- For $\lambda > \lambda'$ in dominance relation, $\mathcal{P}_{\lambda'}(q; \mathbf{x}) - \mathcal{P}_\lambda(q; \mathbf{x})$ is Schur positive
- (q, t) -Parking function?
- The positivity of the predicted (q, t) – polynomials is related to the concavity of λ

Stabilization

$$\mathcal{P}_{32}(\mathbf{x}; q) = e_3 + (q^4 + q^3 + 2q^2 + q) e_{21} + (q^5 + q^4 + q^3) e_{111}$$

$$= (q^5 + q^4 + q^3) s_3 + (2q^5 + 3q^4 + 3q^3 + 2q^2 + q) s_{21}$$

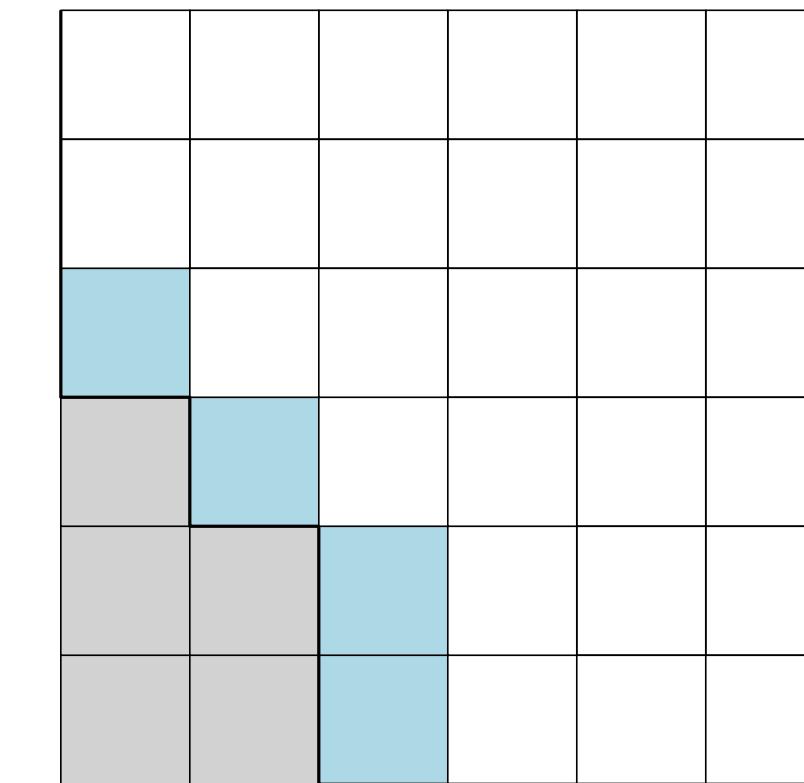
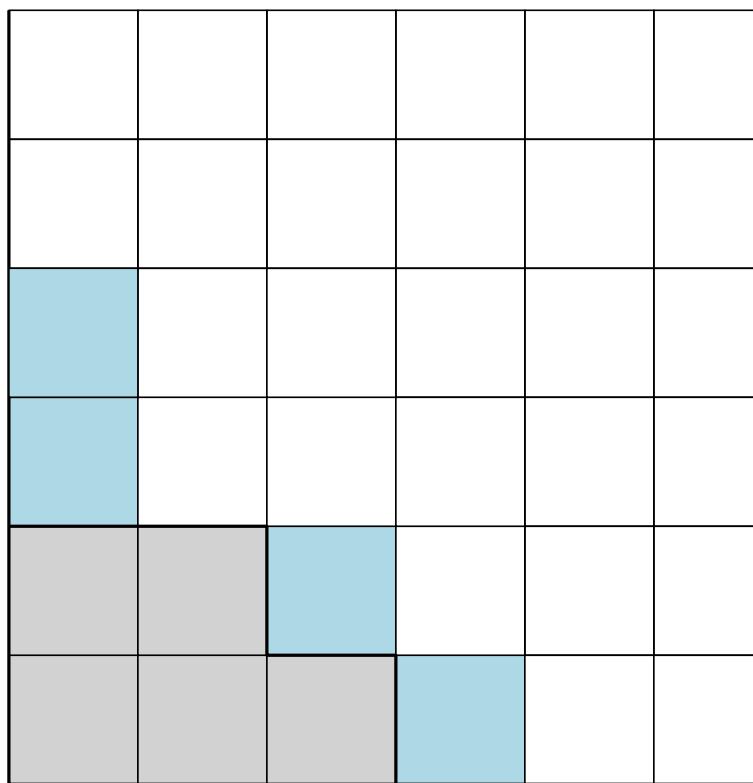
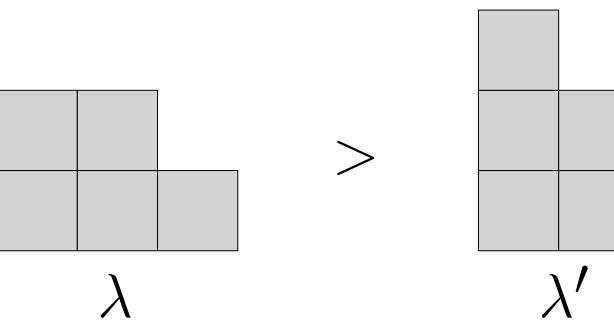
$$+ (q^5 + 2q^4 + 2q^3 + 2q^2 + q + 1) s_{111}$$

$$\mathcal{P}_{(32,0^{n-2})}(\mathbf{x}; q) = ((q^5 + q^4 + q^3)e_{11} + (q^4 + q^2)e_2) e_{n-2} + ((q^3 + q^2 + q)e_1) e_{n-1} + e_n$$

$$\mathcal{P}_{(32,0^3)} = (q^5 + q^4 + q^3) s_{311} + (q^5 + 2q^4 + q^3 + q^2) s_{221}$$

$$+ (2q^5 + 3q^4 + 3q^3 + 2q^2 + q) s_{2111} + (q^5 + 2q^4 + 2q^3 + 2q^2 + q + 1) s_{11111}$$

Dominant partition



$$\mathcal{P}_{(32,0^2)}(\mathbf{x}; q) - \mathcal{P}_{(221,0)}(\mathbf{x}; q) = 0$$

$$\mathcal{P}_{(32,0^3)}(\mathbf{x}; q) - \mathcal{P}_{(221,0^2)}(\mathbf{x}; q) = (q^5 + q^4) s_{32} + (q^5 + q^4 + q^3) s_{221}$$

Dinv & Sim

$$\mathcal{P}(\mathbf{x}; q, t) = \sum_{P \in PF_n} q^{\text{coarea}(P)} t^{\text{dinv}(P)} x^P$$

Definition. Similar cells (Bergeron – Mazin, 2022)

Let τ be a triangular partition.

$$\text{Sim}_\tau(\alpha) := \{c \in \alpha \mid t'(c, \alpha) \leq t_\tau < t''(c, \alpha)\}$$

Counting τ -Dyck path in q, t :

$$\mathcal{A}_\tau(q, t) := \sum_{\alpha \subseteq \tau} q^{\text{coarea}(\alpha)} t^{\text{sim}_\tau(\alpha)}$$

$\mathcal{A}_\tau(q, t)$ is symmetric in q, t .

$$(1, s_1)$$

$$(2, s_2)$$

$$(21, s_{11} + s_3)$$

$$(31, s_{21} + s_4)$$

$$(32, s_{31} + s_5)$$

$$(321, s_{31} + s_{41} + s_6)$$

$$(3, s_3)$$

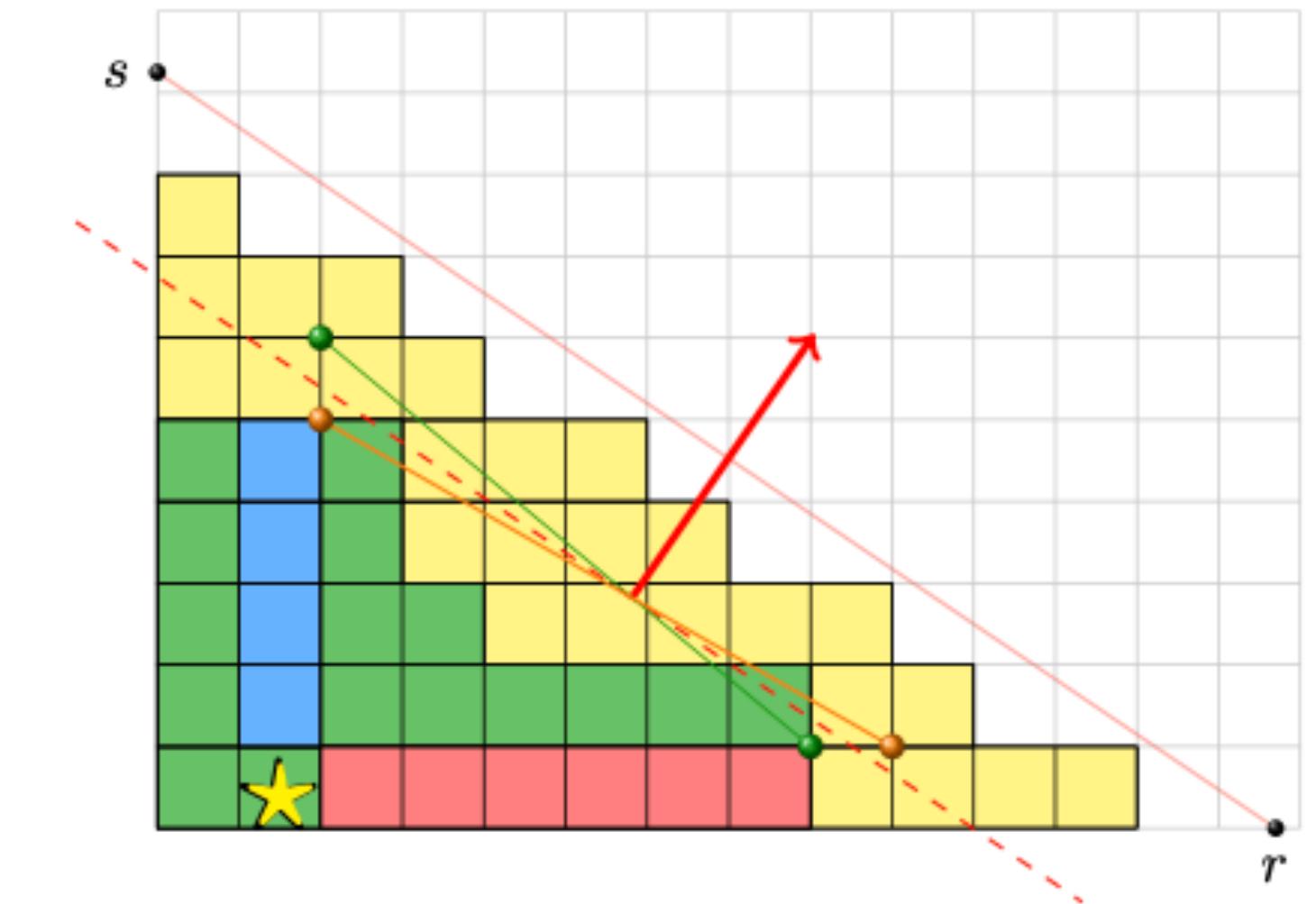
$$(4, s_4)$$

$$(41, s_{31} + s_5)$$

$$(5, s_5)$$

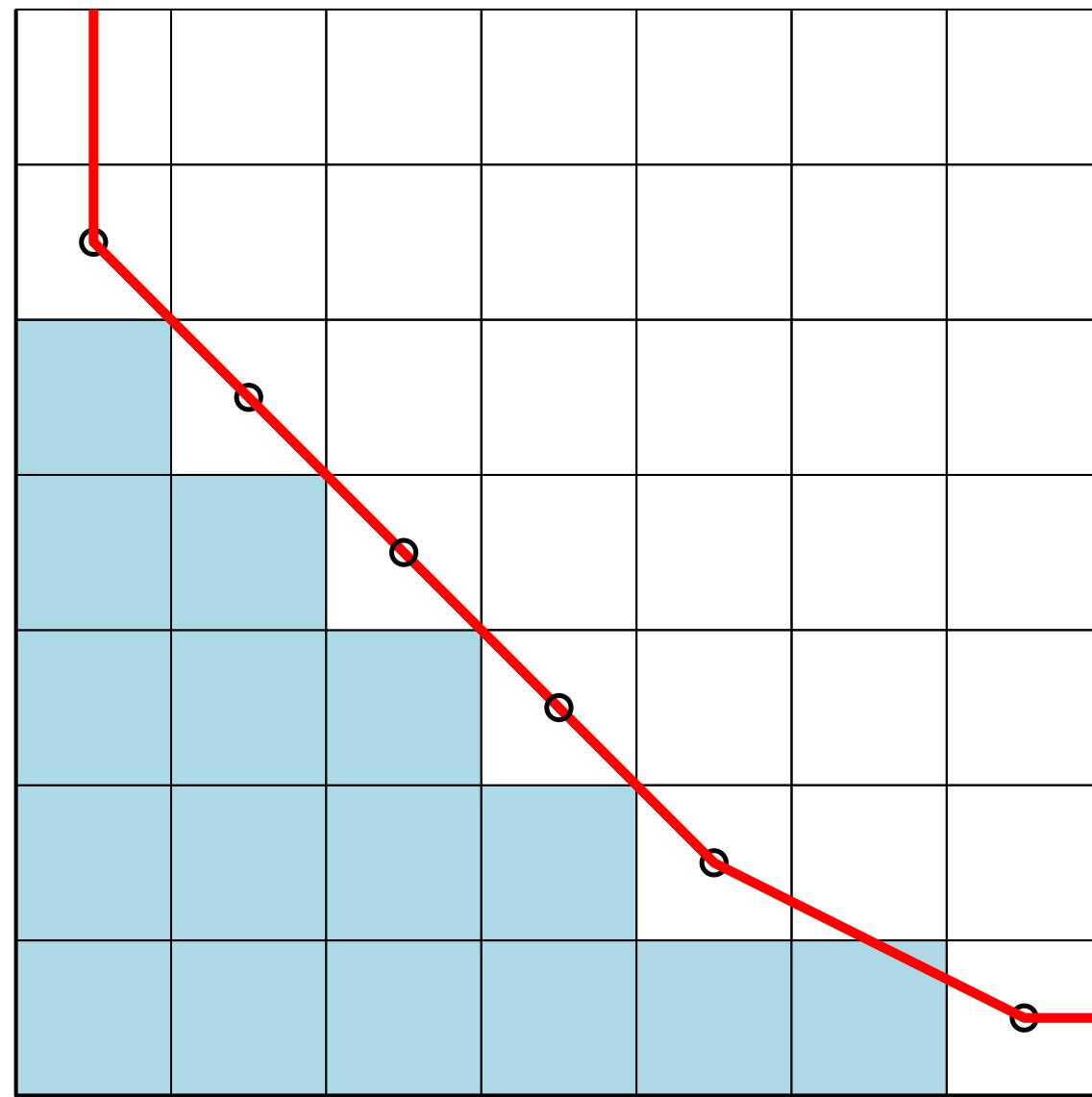
$$(42, s_{22} + s_{41} + s_6) \quad (51, s_{41} + s_6)$$

$$(6, s_6)$$



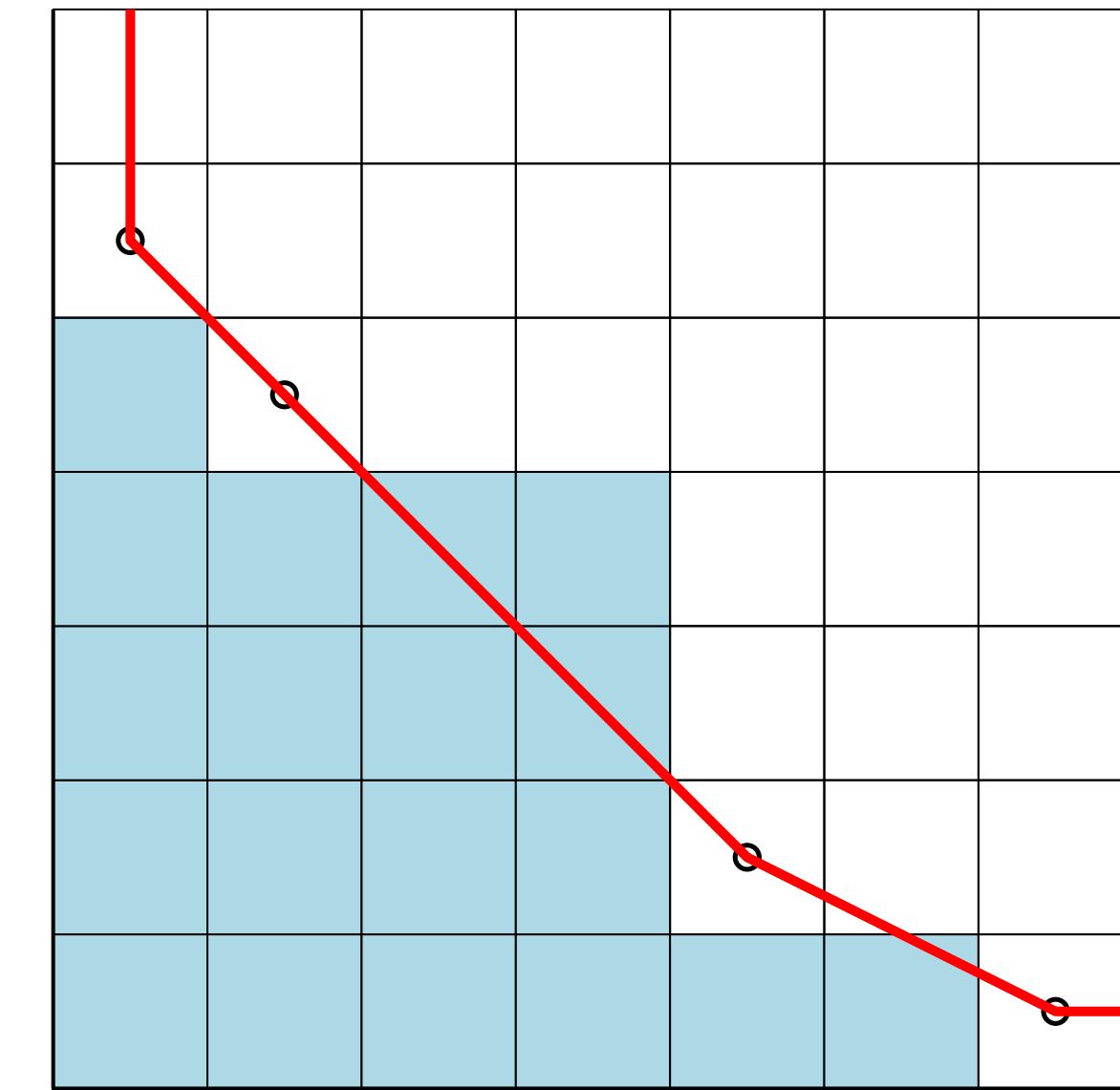
Concave partitions

A partition is concave if no cell of its diagram lies in the convex-hull of its complement



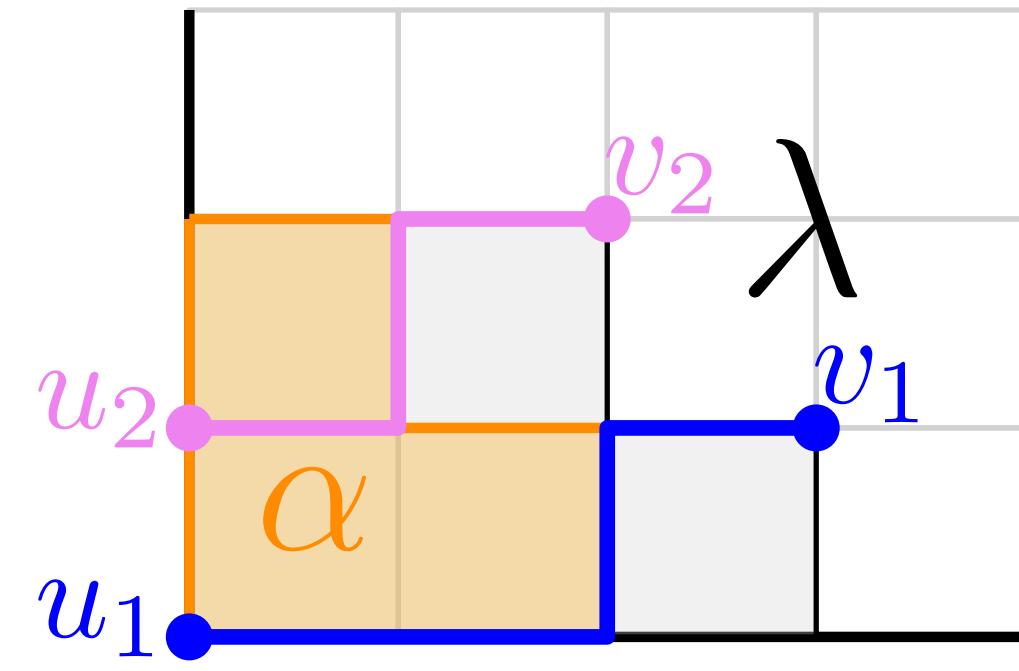
Concave

coefficients $\in \mathbb{N}(q, t)$

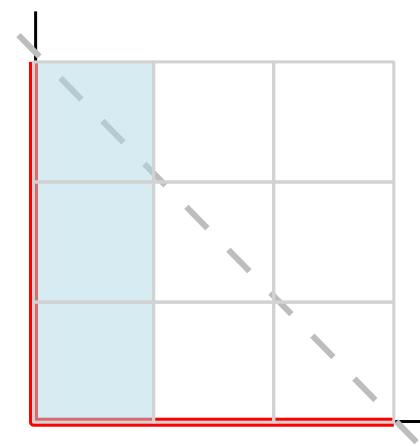
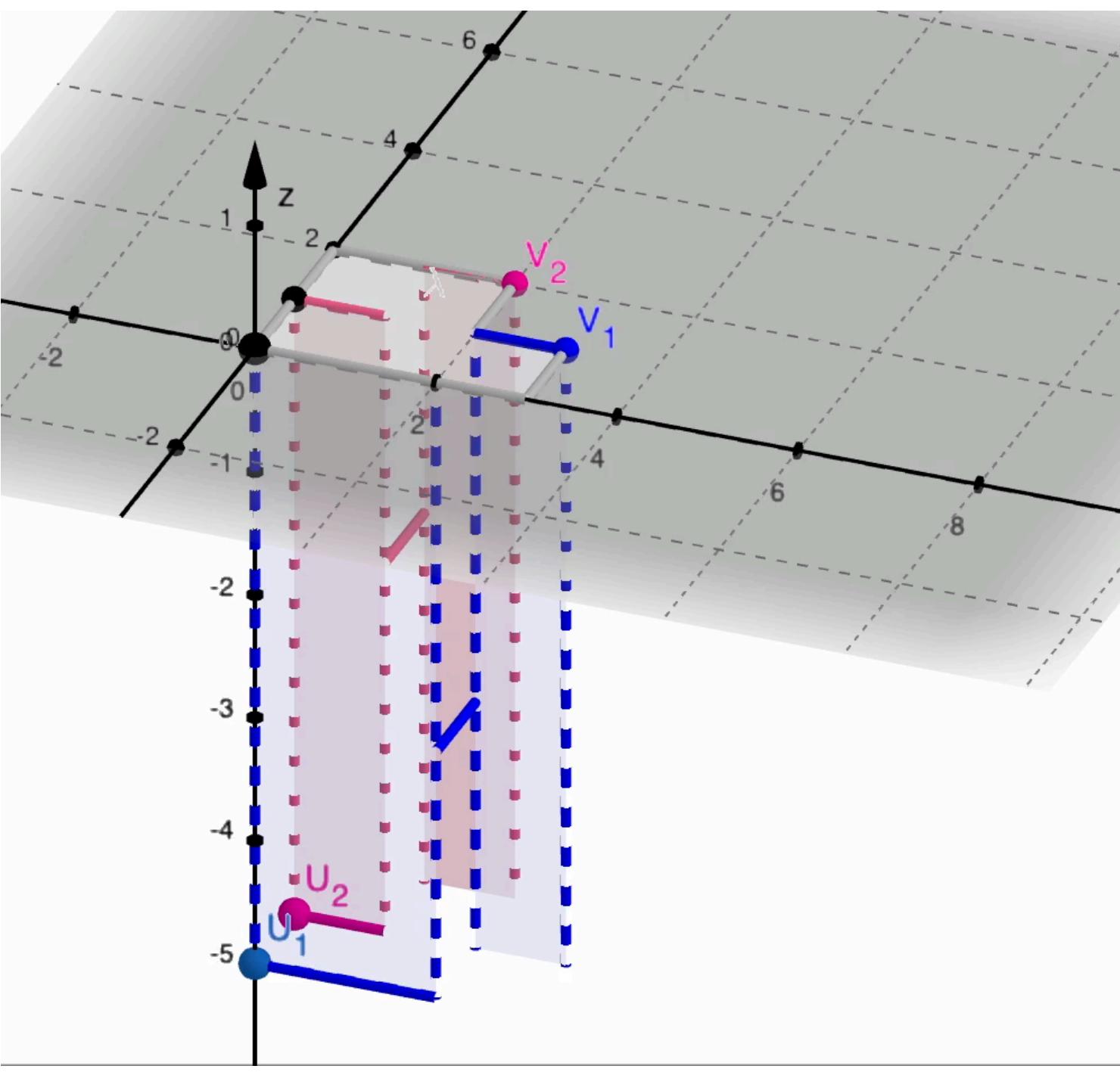


NOT Concave

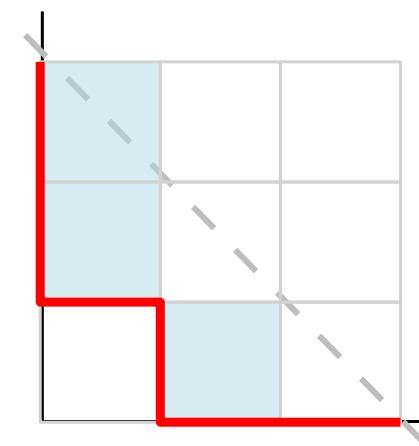
$$(s_4(q, t) + s_{3,1}(q, t) + s_1(q, t) - s_3(q, t) - s_2(q, t) - s_{1,1}(q, t)) s_6(\mathbf{x}) + \dots$$



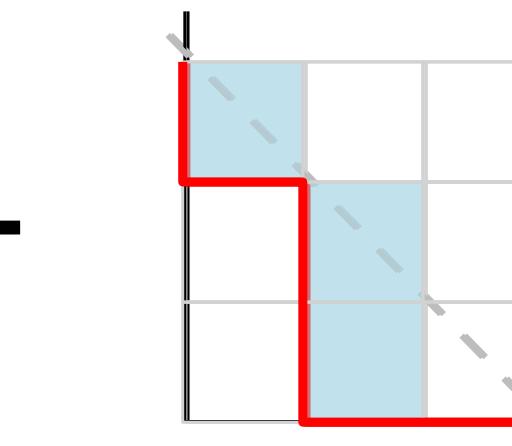
Thank you!



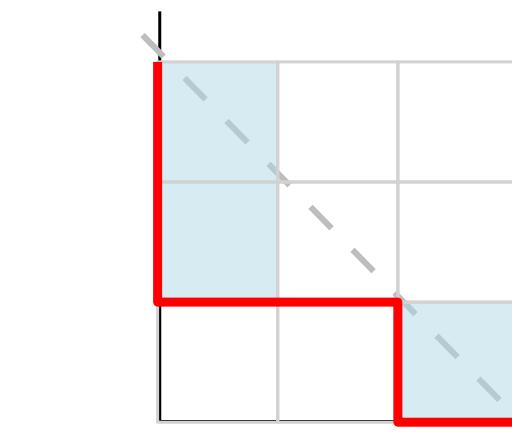
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