ON THE VECTORIAL HAMILTON-JACOBI SYSTEM

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We discuss some recent developments in the study of regularity and stability for a first order Hamilton-Jacobi system: $\nabla u(x) \in K$, where K is a closed set of $n \times m$ -matrices and u is a map from a domain $\Omega \subset \mathbb{R}^m$ to \mathbb{R}^n . For regularity of solutions, we obtain a higher integrability from a very weak integral coercivity condition known as the L^p -mean coercivity. For the stability, we study $W^{1,p}$ sequences $\{u_j\}$ for which $\{\nabla u_j\}$ converges weakly and approaches the set K in some point-wise sense, and describe a new approach to study the weak limits by the so-called $W^{1,p}$ -quasiconvex hull of K. Computation of quasiconvex hulls is usually extremely hard, but some important new developments in the nonlinear partial differential equations turn out to be greatly useful for our study.

1 Introduction

Many partial differential equations arising from problems in analysis, geometry and mechanics can be written as a first order Hamilton-Jacobi system:

$$\nabla u(x) \in K, \quad a.e. \ x \in \Omega \subseteq \mathbb{R}^m,$$
(1)

where $u: \Omega \to \mathbb{R}^n$ and K is a subset of $M^{n \times m}$, the set of all real $n \times m$ matrices. Here $\nabla u(x)$ denotes the Jacobian matrix or the gradient of map u:

$$(\nabla u)_{ij} = \partial u^i / \partial x_j; \quad 1 \le i \le n, \ 1 \le j \le m.$$

A systematic study of Hamilton-Jacobi equations (when n = 1) has been largely developed in P. L. Lions²¹; while for the vectorial cases where $m, n \ge 2$, some recent attempt for such a study has been made by Dacorogna and Marcellini^{8,9}, Müller and Šverák²⁵, Šverák^{29,30}, Yan^{33,35}, and Yan and Zhou ^{36,37,38}.

In this note, I report on some recent developments in the study of regularity and stability concerning the system (1). For regularity, the ultimate goal is to obtain the *right* conditions on K which guarantee that the solutions be smooth, for example, the $C^{1,\alpha}$ -regularity for *p*-Laplacians of K. Uhlenbeck ³²; for stability, we are interested in certain convergence behaviors of the sequences that satisfy (1) approximately.

A sequence $\{u_j\}$ is called an approximating sequence of (1) if there exists a non-negative continuous function f vanishing exactly on K such that

$$\lim_{j \to \infty} \int_{\Omega'} f(\nabla u_j(x)) \, dx = 0 \quad \text{for all } \Omega' \subset \subset \Omega.$$
(2)

An important problem is to study weakly convergent approximating sequences of (1) and their weak limits in the Sobolev space $W^{1,p}(\Omega; \mathbb{R}^n)$ consisting of all L^p -integrable maps with L^p -integrable gradients. The notion of strong and weak convergence in $W^{1,p}(\Omega; \mathbb{R}^n)$ is defined as usual and denoted by " \rightarrow " and " \rightarrow ", respectively. In particular, we say K is $W^{1,p}$ -stable if for any weakly (weakly* if $p = \infty$) convergent approximating sequence in $W^{1,p}(\Omega; \mathbb{R}^n)$ the weak limit u_0 satisfies (1); we say K is $W^{1,p}$ -compact if every weakly convergent approximating sequence of (1) converges strongly in $W^{1,1}_{loc}(\Omega; \mathbb{R}^n)$. From the definition, it is obvious that every $W^{1,p}$ -compact set is $W^{1,p}$ -stable.

An algebraic structure pertaining to both regularity and stability for (1) is the so-called *rank-one connections* in K, which, by definition, are the closed line segments connecting any two matrices in K that differ by a rank-one matrix 3,31 . A necessary condition for K to be $W^{1,\infty}$ -stable is that K contains all its rank-one connections, while a necessary condition for K to be $W^{1,\infty}$ -compact is that K contains no rank-one connections. Moreover, if K has a rank-one connection, some solutions to (1) may have discontinuous gradients²⁵.

In order to obtain the optimal conditions for $W^{1,p}$ -stability of the sets, we introduce an important concept of $W^{1,p}$ -quasiconvex hulls or simply pquasiconvex hulls of the sets using Morrey's notion of quasiconvex functions ²³. Our p-quasiconvex hulls generalize the usual quasiconvex hulls introduced in the study of microstructures of certain elastic materials using the theory of Young measures ^{3,20,29,31}. As we shall see later, $W^{1,p}$ -stability for (1) is essentially determined by the p-quasiconvex hull of the set K.

In many problems, however, computing the *p*-quasiconvex hulls is an infinite dimensional problem and usually is extremely difficult for a given set. Nevertheless, some new developments in the nonlinear PDEs including methods of compensated compactness 6,10,24,31 of F. Murat and L. Tartar and nonlinear Hodge decompositions of T. Iwaniec 17,19 can be very useful in these studies.

2 $W^{1,p}$ -Quasiconvex Hulls and $W^{1,p}$ -Stability

Given $f: M^{n \times m} \to R^1$, define the quasiconvexification f^{qc} of f to be

$$f^{qc}(A) = \inf_{\phi \in C_0^{\infty}(\Omega, R^n)} \frac{1}{|\Omega|} \int_{\Omega} f(A + \nabla \phi(x)) \, dx, \quad A \in M^{n \times m}.$$
 (3)

 $\mathbf{2}$

We say f is quasiconvex if $f^{qc} \equiv f$. It is well-known that f^{qc} is independent of the domain Ω and, under some mild conditions, is also quasiconvex⁷. By Jensen's inequality, every convex function is quasiconvex, but V. Šverák²⁸ has shown that the class of quasiconvex functions is strictly larger if, e.g., $n, m \geq 3$.

Let K be a subset of $M^{n \times m}$ and $1 \le p \le \infty$. We denote by $Q_p^+(K)$ the set of all quasiconvex continuous functions f on $M^{n \times m}$ which satisfy $f|_K = 0$ and

$$0 \le f(X) < C_f(|X|^p + 1), \quad X \in M^{n \times m}$$
(4)

for a constant $C_f < \infty$. If $p = \infty$, condition (4) simply means $0 \le f(X) < \infty$. Let Z(f) denote the zero set of f. We now define the *p*-quasiconvex hulls.

Definition 2.1 The set

$$Q_p(K) = \cap \{Z(f) \mid f \in Q_p^+(K)\}$$

is called the $W^{1,p}$ - or p-quasiconvex hull of K. We say K is p-quasiconvex if $Q_p(K) = K$.

Remarks. 1. It is well-known that ^{1,4} the functional $I_S(u) = \int_S f(\nabla u)$ is weakly lower semicontinuous on $W^{1,p}(\Omega; \mathbb{R}^n)$ for any $f \in Q_p^+(K)$ and measurable set $S \subseteq \Omega$.

2. If f(X) is a continuous and quasiconvex function on $M^{n \times m}$ satisfying $0 \le f(X) < C(|X|^p + 1)$ and $Z(f) \ne \emptyset$, then K = Z(f) is p-quasiconvex.

3. It is easily seen that $Q_q(K) \subseteq Q_p(K)$ for all $1 \leq p < q \leq \infty$. Moreover, if $\operatorname{conv}(K)$ is the closed convex hull of K, then $Q_1(K) \subseteq \operatorname{conv}(K)$. So, all $Q_p(K)$ are compact sets if K is bounded.

Using the Chacon biting convergence lemma⁵, we can prove the following result ³⁵.

Theorem 2.2 Suppose $\{u_j\}$ is an approximating sequence of (1) and $u_j \rightarrow u_0$ weakly in $W^{1,p}(\Omega; \mathbb{R}^n)$ (weakly * if $p = \infty$). Then $\nabla u_0(x) \in Q_p(K)$ for almost every $x \in \Omega$. Therefore, K is $W^{1,p}$ -stable if it is p-quasiconvex.

For bounded sets, using a Luzin type approximation result 1,20,39 , we can prove the following necessary and sufficient condition for $W^{1,p}$ -stability of compact sets 35 .

Theorem 2.3 Let K be a compact set. Then, the p-quasiconvex hulls $Q_p(K)$ are all the same for $1 \le p \le \infty$ and will be denoted by Q(K). Moreover, K is $W^{1,p}$ -stable if and only if K is quasiconvex, i.e., Q(K) = K.

3 Integral Growth Conditions and $W^{1,p}$ -Compactness

We now study the $W^{1,p}$ -compactness based on the integral growth condition similar to the uniformly strict quasiconvexity of Evans and Gariepy ¹⁴. The following results have been proved in Yan³⁵.

Theorem 3.1 Let $1 and <math>f \in Q_p^+(K)$ with Z(f) = K. Suppose for each $\epsilon > 0$ there exists $C_{\epsilon} > 0$ such that

$$\int_{D} |\nabla \phi| \le \epsilon \int_{D} \left(|\nabla \phi|^{p} + 1 \right) + C_{\epsilon} \int_{D} f(A + \nabla \phi)$$
(5)

holds for all $A \in K$ and $\phi \in W_0^{1,p}(D; \mathbb{R}^n)$, where D is a fixed cube in Ω . Then K is $W^{1,q}$ -compact for all q > p.

The usefulness of this theorem is that we only need to check the condition (5) for all $A \in K$ and this condition is much weaker than the uniformly strict quasiconvexity ¹⁴.

Theorem 3.2 Let K be compact, and let $D \subseteq \Omega$ be a cube and 1 . $Then, K is <math>W^{1,1}$ -compact if and only if for each $\epsilon > 0$ there exists a constant $C_{\epsilon} < \infty$ such that

$$\int_{D} \left(d_{K}(A) + |\nabla\phi| \right) \le \epsilon |D| + C_{\epsilon} \int_{D} d_{K}^{p}(A + \nabla\phi)$$
(6)

holds for all $A \in M^{n \times m}$ and $\phi \in W_0^{1,p}(D; \mathbb{R}^n)$.

4 Special Structures in *p*-Quasiconvex Hulls

In order to compute $Q_p(K)$, we need some special structures besides those consisting of rank-one connections mentioned earlier in the introduction.

For any set K and number $p \in [1, \infty]$, let $\beta_p(K)$ be the set of all matrices A for which (1) has a solution $u \in W^{1,p}(\Omega; \mathbb{R}^n)$ that satisfies $u(x) = u_A(x) \equiv Ax$ on $\partial\Omega$, and let $\omega_p(K)$ be the set of all matrices A for which there exists an approximating sequence $\{u_j\}$ of (1) such that $u_j \rightharpoonup u_A$ weakly in $W^{1,p}(\Omega; \mathbb{R}^n)$ (weakly * if $p = \infty$).

Directly from the definition, we can easily prove the following.

Theorem 4.1 (a) $\beta_p(K) \subseteq \omega_p(K) \cap Q_p(K)$ and furthermore, if K is $W^{1,p}$ compact then the only solution to (1) with $u = u_A$ on $\partial\Omega$ is $u \equiv u_A$.

(b) $\omega_{\infty}(K) \subseteq Q_p(K)$ and $\omega_{\infty}(K)$ contains all rank-one connections in K. (c) If K is compact, then $Q(K) = \omega_{\infty}(K)$.

Remark. There has been some recent study of the set $\beta_p(K)$ defined above by Dacorogna and Marcellini^{8,9} using the Baire category theory, and by Müller and Šverák²⁵ using Gromov's idea of convex integration.

5 L^p-Mean Coercivity and Higher Regularity

We consider the case when K is a closed cone in $M^{n \times m}$, i.e., $\lambda K \subseteq K$ for all $\lambda \geq 0$. Let d_K be the corresponding distance function and let B be the unit ball in R^m . Define

$$\mu(p;K) = \inf \left\{ \int_{B} d_{K}^{p}(\nabla\phi) \, \Big| \, \phi \in C_{0}^{\infty}(B;R^{n}), \, \|\nabla\phi\|_{L^{p}(B)} = 1 \right\}.$$
(7)

We say that K satisfies the L^p -mean coercivity provided that $\mu(p; K) > 0$. **Theorem 5.1** If p > 1 and $\mu(p; K) > 0$, then there exists $\epsilon \in (0, p - 1)$ such that $\mu(r; K) > 0$ for all $r \in [p - \epsilon, p + \epsilon]$.

The proof of this theorem relies on the following stability result on the *nonlinear Hodge decompositions* due to Iwaniec ¹⁷. We refer to Iwaniec and Sbordone¹⁹ for a proof of this result using the L^p -estimates of nonlinear paracommutators.

Lemma 5.2 Let r > 1 and B be the open unit ball in \mathbb{R}^m . Then, for any $u \in W_0^{1,r}(B;\mathbb{R}^n)$ and $\epsilon \in (-1, r-1)$, the matrix $|\nabla u|^{\epsilon} \nabla u \in L^{\frac{r}{1+\epsilon}}(B;M^{n\times m})$ can be decomposed as $|\nabla u(x)|^{\epsilon} \nabla u(x) = \nabla \psi(x) + h(x)$ for a.e. $x \in B$, where $\psi \in W_0^{1,\frac{r}{1+\epsilon}}(B;\mathbb{R}^n)$, and $h \in L^{\frac{r}{1+\epsilon}}(\mathbb{R}^m;M^{n\times m})$ is a divergence free matrix field satisfying

$$\|h\|_{L^{\frac{r}{1+\epsilon}}(\mathbb{R}^m)} \le C(m,n,r,\epsilon) \,|\epsilon| \, \|\nabla u\|_{L^r(B)}^{1+\epsilon}.$$

$$\tag{8}$$

Moreover, for any constants $1 < r_1 < r_2 < \infty$,

$$\sup_{|\epsilon| \le \frac{r_1 - 1}{r_1 + 1}, \ r_1 \le r \le r_2} C(m, n, r, \epsilon) \equiv \alpha(r_1, r_2) < \infty.$$
(9)

We now sketch the proof of Theorem 5.1 given in Yan and Zhou 38 . Let

$$r_1 = \frac{\sqrt{8p+1}-1}{2}, \quad \epsilon_0 = \frac{r_1-1}{r_1+1}, \quad r_2 = (1+\epsilon_0)p.$$
 (10)

Let $|\epsilon| \leq \epsilon_0$ and $r = (1 + \epsilon) p$; then $r_1 \leq r \leq r_2$. Let $\phi \in C_0^{\infty}(B; \mathbb{R}^n)$. Using Lemma 5.2, we decompose $|\nabla \phi|^{\epsilon} \nabla \phi \in L^p(B; M^{n \times m})$ as follows:

$$|\nabla\phi(x)|^{\epsilon}\nabla\phi(x) = \nabla\psi(x) + h(x) \quad a.e. \ x \in B,$$
(11)

where $\psi \in W_0^{1,p}(B; \mathbb{R}^n)$, $h \in L^p(\mathbb{R}^m; M^{n \times m})$ and

$$\|h\|_{L^p(\mathbb{R}^m)} \le \alpha_p \,|\epsilon| \, \|\nabla\phi\|_{L^r(B)}^{1+\epsilon},\tag{12}$$

where α_p depends only on p. Hence,

$$\|\nabla\psi\|_{L^p(B)} \ge (1 - \alpha_p|\epsilon|) \|\nabla\phi\|_{L^r(B)}^{1+\epsilon}.$$
(13)

From (11), we have $\nabla \psi(x) = |\nabla \phi(x)|^{\epsilon} \nabla \phi(x) - h(x)$ and hence

$$d_K(\nabla\psi(x)) \le |\nabla\phi(x)|^{\epsilon} d_K(\nabla\phi(x)) + |h(x)| \quad \forall x \in B.$$

Let $\sigma_0 = \mu(p; K)^{1/p}$. We have by the L^p -mean coercivity

$$\sigma_0 \|\nabla \psi\|_{L^p(B)} \le \|d_K(\nabla \psi)\|_{L^p(B)} \le \||\nabla \phi|^{\epsilon} d_K(\nabla \phi)\|_{L^p(B)} + \|h\|_{L^p(B)}.$$
 (14)

Combining (12)–(14), we have

$$\left(\sigma_0 - \alpha_p(1+\sigma_0) \left|\epsilon\right|\right) \|\nabla\phi\|_{L^r(B)}^{1+\epsilon} \le \||\nabla\phi|^{\epsilon} d_K(\nabla\phi)\|_{L^p(B)}.$$
 (15)

From this, it follows that if $|\epsilon| \leq \epsilon_0$ is further chosen sufficiently small then

$$\int_{B} d_K^r(\nabla \phi) \ge C_p \, \|\nabla \phi\|_{L^r(B)}^r, \quad C_p > 0, \quad r = (1+\epsilon) \, p, \tag{16}$$

proving the theorem. Indeed, if $\epsilon < 0$, using $|\nabla \phi|^{\epsilon} \leq [d_K(\nabla \phi)]^{\epsilon}$, we have

$$\||\nabla\phi|^{\epsilon}d_{K}(\nabla\phi)\|_{L^{p}(B)} \leq \|d_{K}^{1+\epsilon}(\nabla\phi)\|_{L^{p}(B)} = \|d_{K}(\nabla\phi)\|_{L^{r}(B)}^{1+\epsilon}$$

hence (16) follows by using (15) if $|\epsilon|$ is sufficiently small. Let $\epsilon > 0$; then, by Hölder's inequality, we have

$$\||\nabla\phi|^{\epsilon}d_{K}(\nabla\phi)\|_{L^{p}(B)} \leq \|d_{K}(\nabla\phi)\|_{L^{r}(B)}\|\nabla\phi\|_{L^{r}(B)}^{\epsilon}.$$

So, we still obtain (16) using (15) for all sufficiently small $|\epsilon|$.

The L^p -mean coercivity and the Ekeland variational principle ¹² enable us to adapt the standard Caccioppoli-type estimates ¹⁶ to obtain some higher regularity results using the technique of reverse Hölder inequalities. This technique was first introduced by Gehring ¹⁵ in the study of higher integrability of quasiconformal mappings and used later successfully for studying the nonlinear elliptic systems ^{16,22}.

The following results concerning the regularity and stability for system (1) have been proved in Yan and Zhou^{37,38}.

Theorem 5.3 Let K be a closed cone and $S(K) = \{p > 1 \mid \mu(p; K) > 0\} \neq \emptyset$. Then $Q_p(K)$ is constant for all p belonging to each of the connected components of S(K).

Theorem 5.4 Let K be a closed cone and $[\alpha, \beta] \subset S(K)$. Then any solution $u \in W^{1,\alpha}_{loc}(\Omega; \mathbb{R}^n)$ to system (1) must belong to $W^{1,\beta}_{loc}(\Omega; \mathbb{R}^n)$.

Remarks. 1. An application of these results will be discussed in the next section concerning the regularity and stability of the *weakly quasiregular mappings*.

2. It remains extremely difficult and quite challenging to describe the set S(K) in terms of any intrinsic properties of the cone K.

3. Another problem is to find a necessary and sufficient condition such that K is p-quasiconvex, which would have a profound impact on the study of Hamilton-Jacobi system (1).

6 Weakly Quasiregular Mappings

As an example of our study, we consider the case m = n and the class of closed cones K_l defined by

$$K_l = \{A \in M^{n \times n} \mid |A|^n \le \ln^{n/2} \det A\}$$

for all $l \geq 1$; the set K_1 is called the *conformal set* and denoted by C_n . A map $u \in W_{loc}^{1,p}(\Omega; \mathbb{R}^n)$ is called (weakly if p < n) *l*-quasiregular ^{17,18,27} if it satisfies $\nabla u(x) \in K_l$ a.e. $x \in \Omega$.

In order to study the regularity and stability of (weakly) quasiregular mappings, we shall try to compute the set $S(K_l)$. Consider the function

$$F_l(X) = \max\{0, |X|^n - \ln^{n/2} \det X\}.$$

It is easily seen that $F_l \ge 0$ is *n*-homogeneous, quasiconvex and $Z(F_l) = K_l$, and we also have that $\int_B F_l(\nabla \phi) \ge \int_B |\nabla \phi|^n$ for all $\phi \in C_0^{\infty}(B; \mathbb{R}^n)$. From this, using the homogeneity, we obtain that there is a $\Gamma > 0$ such that

$$\int_{B} d_{K_{l}}^{n}(\nabla \phi) \geq \Gamma \int_{B} |\nabla \phi|^{n}, \quad \forall \phi \in C_{0}^{\infty}(B; \mathbb{R}^{n}).$$

Hence, by definition and Theorems 5.3 and 5.4, we have the following regularity and stability result.

Theorem 6.1 For all $l \ge 1$, it follows that $n \in S(K_l)$ and $Q_p(K_l) = K_l$ for $p \in [n - \epsilon, n + \epsilon] \subset S(K_l)$ for some $\epsilon > 0$. Therefore, we have both the stability and higher regularity for weakly quasiregular mappings in $W_{loc}^{1,p}$ with p slightly below the dimension n.

Remarks. 1. Observe that the nonlinear homothety $u_l(x) = x|x|^{(1-l)/l}$ satisfies $\nabla u_l(x) \in K_l$ for $x \neq 0$, and $u_l \in W^{1,n}(B; \mathbb{R}^n)$, but $u_l \notin W^{1,\frac{nl}{l-1}}(B; \mathbb{R}^n)$. By Theorem 5.4, there must be a $q \in [n, nl/(l-1)]$ such that $q \notin S(K_l)$.

2. On a basis of Theorem 5.4 and a conjecture made by Iwaniec ¹⁷ concerning regularity of weakly quasiregular mappings, we conjecture that $S(K_l) = \left(\frac{nl}{l+1}, \frac{nl}{l-1}\right)$ for all n and $l \ge 1$. For even dimensions n, it is indeed true that $S(C_n) = (n/2, \infty)$, but question concerning all other cases remains open ^{18,26,34}.

3. This conjecture is closely related to an open problem on the *p*-Laplacian equation regarding whether the $C^{1,\alpha}$ -regularity result of Uhlenbeck³² holds for weak solutions in $W^{1,q}$ with q > p - 1.

The following theorem gives the compactness results concerning the weakly conformal mappings proved in Müller, Šverák and Yan²⁶ and in Yan and Zhou³⁶.

Theorem 6.2 There exists a $p_n \in [n/2, n)$, $p_n = n/2$ if n is even, such that if $p \ge p_n$ and if $u_j \rightharpoonup u_0$ in $W^{1,p}(\Omega; \mathbb{R}^n)$ and $\int_{\Omega} d^p_{C_n}(\nabla u_j) \to 0$ then $u_j \to u_0$ strongly in $W^{1,1}_{loc}(\Omega; \mathbb{R}^n)$.

Remarks. 1. If $p \ge n$, the result follows from a strong convergence result of Evans and Gariepy ¹⁴ by a theory of *strictly uniformly polyconvex* functions. However, as proved in Yan³⁴, such functions do not exist if p < n.

2. If $p_n \leq p < n$, Theorem 6.2 generalizes the classical stability result of quasiregular mappings²⁷: If $\{u_j\}$ is a sequence of l_j -quasiregular mappings bounded in $W^{1,n}$ and $l_j \to 1$, then $\{u_j\}$ converges strongly to a Möbius map in $W^{1,1}_{loc}(\Omega; \mathbb{R}^n)$. In this case, it is easily seen that the conformal energy $I_p(u_j) = \int_{\Omega} d_{C_n}^p(\nabla u_j)$ approaches 0. 3. The result in the even dimension case is sharp. A key to the proof is the

3. The result in the even dimension case is sharp. A key to the proof is the fact that for n = 2l the conformality of a matrix can be (almost) characterized by a *linear* condition that involves $l \times l$ -minors^{11,18}. This characterization gives a nonlinear version of Cauchy-Riemann equations and hence enables us to use the elliptic estimates and compensated compactness^{6,26,31}.

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