

Exam 3

Directions: Do all problems (100 points total). You must *show all steps and explain your reasoning* to receive full credit. No books, notes, or electronic devices are allowed.

1. (18 points) Let V and W be vector spaces. Complete the definitions *as briefly as possible*:

(a) Two $n \times n$ matrices A and B are *similar* if there is an invertible $n \times n$ matrix S such that:

$$B = S^{-1}AS$$

(b) An $n \times n$ matrix Q is *orthogonal* if

$$Q^T Q = I_n$$

(c) The *orthogonal complement* of a subspace S of \mathbb{R}^n is defined by

$$S^\perp = \{ x \in \mathbb{R}^n \mid x \cdot y = 0 \ \forall y \in S \}$$

(d) In a vector space V with inner product $\langle \cdot, \cdot \rangle$,

- The *norm* of a vector x is defined by the formula $\|x\| = \sqrt{\langle x, x \rangle}$

- $\{e_1, e_2, \dots, e_k\}$ is an *orthonormal set* if ...

$$\langle e_i, e_j \rangle = \delta_{ij} = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$$

(e) To compute the correlation coefficient between two data vectors $x, y \in \mathbb{R}^n$, one first the deviation vectors x_D and y_D (by subtracting the means \bar{x}, \bar{y}). Then, in terms of x_D and y_D ,

- The formula for the *correlation coefficient* is $r = \frac{x_D \cdot y_D}{\|x_D\| \cdot \|y_D\|}$

- Geometrically, r is ... $\cos \Theta$ where $\Theta =$ angle between x_D and y_D .

2. (14 points) Circle (T) for TRUE, circle (F) for FALSE.

(a) If A and B are similar matrices, then $\det A = \det B$. (T) F

(b) If A and B are similar matrices, then A^2 is similar to B^2 . (T) F

(c) For an $m \times n$ matrix A , the null space $N(A)$ and the range $R(A)$ are orthogonal subspaces of \mathbb{R}^n . T (F)

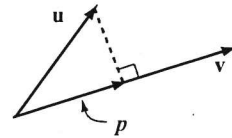
(d) If $\langle \cdot, \cdot \rangle$ is an inner product on a vector space V , then $\langle x, y \rangle = \langle y, x \rangle$ for all $x, y \in V$. (T) F

(e) If $\langle \cdot, \cdot \rangle$ is an inner product on a vector space V , then $\langle \mathbf{x}, \mathbf{x} \rangle = 0$ only if $\mathbf{x} = \mathbf{0}$. (T) F

(f) Each vector space V has a unique inner product. T (F)

(g) Every finite-dimensional inner product space has an orthonormal basis. (T) F

3. (12 points) Let θ denote the angle between the vectors $\mathbf{u} = (1, 1, 2, 2)^T$ and $\mathbf{v} = (-2, 1, 2, 0)^T$ in \mathbb{R}^4 . Let \mathbf{p} be the orthogonal projection of \mathbf{u} onto \mathbf{v} . Find:



$$\mathbf{u} \cdot \mathbf{v} = 1 \cdot (-2) + 1 \cdot 1 + 2 \cdot 2 + 2 \cdot 0 = 3$$

$$\cos \theta = \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\| \cdot \|\mathbf{v}\|} = \frac{3}{\sqrt{10} \sqrt{9}} = \frac{1}{\sqrt{10}}$$

$$\mathbf{p} = \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{v}\|^2} \mathbf{v} = \frac{3}{9} \mathbf{v} = \frac{1}{3} \begin{pmatrix} -2 \\ 1 \\ 2 \\ 0 \end{pmatrix}$$

4. (10 points) Consider the vector space $C[0, 1]$ with inner product defined by $\langle f, g \rangle = \int_0^1 f(x)g(x) dx$.

(a) Show that 1 and $2x - 1$ are orthogonal:

$$\langle 1, 2x-1 \rangle = \int_0^1 1 \cdot (2x-1) dx = x^2 - x \Big|_0^1 = 1 - 1 = 0$$

(b) Calculate $\|2x - 1\|$:

$$\begin{aligned} \|2x-1\|^2 &= \langle 2x-1, 2x-1 \rangle = \int_0^1 (2x-1)^2 dx \\ &= \int_0^1 4x^2 - 4x + 1 dx \\ &= \left. \frac{4}{3}x^3 - 2x^2 + x \right|_0^1 \\ &= \left(\frac{4}{3} - 2 + 1 \right) - 0 \\ &= \frac{1}{3} \end{aligned}$$

Answer: $\|2x - 1\| = \frac{1}{\sqrt{3}}$

don't forget to take square root!

5. (10 points) Let V be a vector space with inner product $\langle \cdot, \cdot \rangle$. Prove that

$$\|x+y\|^2 + \|x-y\|^2 = 2(\|x\|^2 + \|y\|^2) \quad \forall x, y \in V.$$

Use two-column format, giving a reason for each step in terms of properties of the inner product.

$$\begin{aligned} \|x+y\|^2 + \|x-y\|^2 &= \langle x+y, x+y \rangle + \langle x-y, x-y \rangle && \text{Def. of norm} \\ &= [\langle x, x \rangle + \langle x, y \rangle + \langle y, x \rangle + \langle y, y \rangle] \\ &\quad + [\langle x, x \rangle - \langle x, y \rangle - \langle y, x \rangle + \langle y, y \rangle] && \text{inner product is bilinear} \\ &= 2[\langle x, x \rangle + \langle y, y \rangle] \\ &= 2(\|x\|^2 + \|y\|^2) && \text{Def. of norm.} \end{aligned}$$

6. (20 points) Use the Gram-Schmidt process to find an orthonormal basis of \mathbb{R}^3 starting from the vectors

$$x_1 = \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} \quad x_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \quad x_3 = \begin{pmatrix} -1 \\ 4 \\ 2 \end{pmatrix}$$

Number your steps and show your work.

Step 1 $e_1 = \frac{x_1}{\|x_1\|} = \frac{1}{3} \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix}$

Step 2 $y_2 = x_2 - \langle x_2, e_1 \rangle e_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} - \left[\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \cdot \frac{1}{3} \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} \right] \cdot \frac{1}{3} \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix}$
 $= \frac{1}{3} \begin{pmatrix} 3 \\ 3 \\ 0 \end{pmatrix} - \frac{1}{3} \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} 1 \\ 2 \\ -2 \end{pmatrix}$

$e_2 = \frac{1}{3} \begin{pmatrix} 1 \\ 2 \\ -2 \end{pmatrix}$ already normalized!

Step 3 $y_3 = x_3 - \langle x_3, e_1 \rangle e_1 - \langle x_3, e_2 \rangle e_2$
 $= \begin{pmatrix} -1 \\ 4 \\ 2 \end{pmatrix} - \left[\begin{pmatrix} -1 \\ 4 \\ 2 \end{pmatrix} \cdot \frac{1}{3} \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} \right] \cdot \frac{1}{3} \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} - \left[\begin{pmatrix} -1 \\ 4 \\ 2 \end{pmatrix} \cdot \frac{1}{3} \begin{pmatrix} 1 \\ 2 \\ -2 \end{pmatrix} \right] \cdot \frac{1}{3} \begin{pmatrix} 1 \\ 2 \\ -2 \end{pmatrix}$

easier to make common factor of $\frac{1}{3}$

$= \frac{1}{3} \begin{pmatrix} -3 \\ 12 \\ 6 \end{pmatrix} - \frac{2}{3} \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} - \frac{1}{3} \begin{pmatrix} 1 \\ 2 \\ -2 \end{pmatrix}$
 $= \frac{1}{3} \begin{pmatrix} -8 \\ 8 \\ 4 \end{pmatrix}$

normalizing this is the same as normalizing $\begin{pmatrix} -2 \\ 2 \\ 1 \end{pmatrix}$

$e_3 = \text{normalization of } \begin{pmatrix} -2 \\ 2 \\ 1 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} -2 \\ 2 \\ 1 \end{pmatrix}$

ON basis: $\frac{1}{3} \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix}, \frac{1}{3} \begin{pmatrix} 1 \\ 2 \\ -2 \end{pmatrix}, \frac{1}{3} \begin{pmatrix} -2 \\ 2 \\ 1 \end{pmatrix}$

7. (16 points) Use the Least Squares Procedure to find the line $y = ax + b$ in the plane that best fits the data points $\{(-2, -2), (-1, 0), (1, 1), (2, 3)\}$.

(a) What is the overdetermined linear system to be solved?

$$\left. \begin{array}{l} \text{Passing thru } (-2, -2) \Rightarrow -2a + b = -2 \\ \text{thru } (-1, 0) \Rightarrow -a + b = 0 \\ \text{thru } (1, 1) \Rightarrow a + b = 1 \\ \text{thru } (2, 3) \Rightarrow 2a + b = 3 \end{array} \right\} \text{L System.}$$

(b) This system has the form $Ax = b$ for what matrix A and vector b ?

$$A = \begin{pmatrix} -2 & 1 \\ -1 & 1 \\ 1 & 1 \\ 2 & 1 \end{pmatrix} \quad b = \begin{pmatrix} -2 \\ 0 \\ 1 \\ 3 \end{pmatrix}$$

(c) Find the Least Square solution.

$$A^T A = \begin{pmatrix} -2 & -1 & 1 & 2 \\ 1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -2 & 1 \\ -1 & 1 \\ 1 & 1 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} 10 & 0 \\ 0 & 4 \end{pmatrix} \quad \Rightarrow (A^T A)^{-1} = \frac{1}{40} \begin{pmatrix} 4 & 0 \\ 0 & 10 \end{pmatrix}$$

$$A^T b = \begin{pmatrix} -2 & -1 & 1 & 2 \\ 1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -2 \\ 0 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 11 \\ 2 \end{pmatrix}$$

$$\text{Least Square Soln: } \vec{x} = (A^T A)^{-1} A^T b = \frac{1}{20} \begin{pmatrix} 2 & 0 \\ 0 & 5 \end{pmatrix} \begin{pmatrix} 11 \\ 2 \end{pmatrix} = \frac{1}{20} \begin{pmatrix} 22 \\ 10 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 1.1 \\ \frac{1}{2} \end{pmatrix}$$

(d) What is the equation of the line of best fit?

$$\boxed{y = 1.1x + \frac{1}{2}}$$