

1a. The Jacobian derivatives of $f(x, y)$ and $P(r, \theta) = (r \cos(\theta), r \sin(\theta))$ are:

$$[Df_{(x,y)}] = \nabla f(x, y) = \left[\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right], \quad [DP_{(r,\theta)}] = \begin{bmatrix} \cos(\theta) & -r \sin(\theta) \\ \sin(\theta) & r \cos(\theta) \end{bmatrix}.$$

By the Chain Rule, the derivative of $g(r, \theta) = f(P(r, \theta))$ is the product matrix:

$$\begin{aligned} [Dg_{(r,\theta)}] &= \nabla g(r, \theta) = \left[\frac{\partial f}{\partial x}(P(r, \theta)), \frac{\partial f}{\partial y}(P(r, \theta)) \right] \cdot \begin{bmatrix} \cos(\theta) & -r \sin(\theta) \\ \sin(\theta) & r \cos(\theta) \end{bmatrix}, \\ &= \left[\frac{\partial f}{\partial x} \cos(\theta) + \frac{\partial f}{\partial y} \sin(\theta), -\frac{\partial f}{\partial x} r \sin(\theta) + \frac{\partial f}{\partial y} r \cos(\theta) \right] \end{aligned}$$

where $\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}$ are taken at $P(r, \theta)$.

1b. We get the same result in Leibnitz notation, writing $z = f(x, y)$, $x = r \cos(\theta)$, $y = r \sin(\theta)$ and computing:

$$\frac{\partial z}{\partial r} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial r} = \frac{\partial f}{\partial x}(x, y) \cos(\theta) + \frac{\partial f}{\partial y}(x, y) \sin(\theta),$$

and similarly for $\frac{\partial z}{\partial \theta}$.

2. For $\mathbf{c}(\theta) = P(r(\theta), \theta)$, we have:

$$\begin{aligned} \mathbf{c}'(\theta) &= [DP_{(r(\theta), \theta)}] \cdot [D(r(\theta), \theta)]_{\theta} \\ &= \begin{bmatrix} \cos(\theta) & -r(\theta) \sin(\theta) \\ \sin(\theta) & r(\theta) \cos(\theta) \end{bmatrix} \cdot \begin{bmatrix} r'(\theta) \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} \cos(\theta)r'(\theta) - r(\theta) \sin(\theta) \\ \sin(\theta)r'(\theta) + r(\theta) \cos(\theta) \end{bmatrix} \\ &= r'(\theta) \begin{bmatrix} \cos(\theta) \\ \sin(\theta) \end{bmatrix} + r(\theta) \begin{bmatrix} \cos(\theta) \\ \sin(\theta) \end{bmatrix}' \end{aligned}$$

The last expression agrees with the Product Rule applied to $\mathbf{c}(\theta) = r(\theta)(\cos(\theta), \sin(\theta))$.

3. For $m(x, y) = xy$ and $F(x, y) = (f(x, y), g(x, y))$, the Jacobians are:

$$[Dm_{x,y}] = \nabla m(x, y) = [y \ x], \quad [DF_{(x,y)}] = \begin{bmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{bmatrix}.$$

Letting $F(a, b) = (f(a, b), g(a, b)) = (f, g)$, the Chain Rule says:

$$\begin{aligned} \nabla(fg)(a, b) &= [D(m \circ F)_{(a,b)}] = [Dm_{F(a,b)}] \cdot [DF_{(a,b)}] \\ &= \nabla m(f, g) \cdot \begin{bmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{bmatrix} = [g \ f] \cdot \begin{bmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{bmatrix} \\ &= \left[g \frac{\partial f}{\partial x} + f \frac{\partial g}{\partial x}, g \frac{\partial f}{\partial y} + f \frac{\partial g}{\partial y} \right] \\ &= g \left[\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right] + f \left[\frac{\partial g}{\partial x}, \frac{\partial g}{\partial y} \right] \\ &= g(a, b) \nabla f(a, b) + f(a, b) \nabla g(a, b). \end{aligned}$$

4. Given $h(x, y) = f(x, g(x, y))$, we define $G(x, y) = (x, g(x, y))$ and compute:

$$\begin{aligned}\nabla h(a, b) &= [D(f \circ G)_{(a,b)}] = [Df_{G(a,b)}] \cdot [DG_{(a,b)}] \\ &= \nabla f(a, g(a, b)) \cdot \begin{bmatrix} 1 & 0 \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{bmatrix} \\ &= \left[\frac{\partial f}{\partial x}(a, g(a, b)) + \frac{\partial f}{\partial y}(a, g(a, b)) \frac{\partial g}{\partial x}(a, b), \frac{\partial f}{\partial y}(a, g(a, b)) \frac{\partial g}{\partial y}(a, b) \right]\end{aligned}$$

Notice that $\frac{\partial f}{\partial y}$ means the partial derivative of $f(x, y)$ with respect to the second variable, *before* substituting $g(x, y)$ for that variable.

This might be clearer in Leibnitz letter-notation:

$$z = f(x, y), \quad x = u, \quad y = g(u, v),$$

$$\frac{\partial z}{\partial u} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial u} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial u} = \frac{\partial f}{\partial x}(u, g(u, v)) + \frac{\partial f}{\partial y}(u, g(u, v)) \frac{\partial g}{\partial u}(u, v),$$

$$\frac{\partial z}{\partial v} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial v} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial v} = 0 + \frac{\partial f}{\partial y}(u, g(u, v)) \frac{\partial g}{\partial v}(u, v),$$