

## Non-homogeneous equations (Sect. 2.5).

- ▶ We study:  $y'' + a_1 y' + a_0 y = b(t)$ .
- ▶ Operator notation and preliminary results.
- ▶ Summary of the undetermined coefficients method.
- ▶ Using the method in few examples.
- ▶ The guessing solution table.

## Operator notation and preliminary results.

**Notation:** Given functions  $p, q$ , denote

$$L(y) = y'' + p(t)y' + q(t)y.$$

Therefore, the differential equation

$$y'' + p(t)y' + q(t)y = f(t)$$

can be written as

$$L(y) = f.$$

The homogeneous equation can be written as

$$L(y) = 0.$$

The function  $L$  acting on a function  $y$  is called an **operator**.

## Operator notation and preliminary results.

**Remark:** The operator  $L$  is a linear function of  $y$ .

### Theorem

For every continuously differentiable functions  $y_1, y_2 : (t_1, t_2) \rightarrow \mathbb{R}$  and every  $c_1, c_2 \in \mathbb{R}$  holds that

$$L(c_1y_1 + c_2y_2) = c_1L(y_1) + c_2L(y_2).$$

**Proof:**

$$L(c_1y_1 + c_2y_2) = (c_1y_1 + c_2y_2)'' + p(t)(c_1y_1 + c_2y_2)' + q(t)(c_1y_1 + c_2y_2)$$

$$\begin{aligned} L(c_1y_1 + c_2y_2) &= (c_1y_1'' + p(t)c_1y_1' + q(t)c_1y_1) \\ &\quad + (c_2y_2'' + p(t)c_2y_2' + q(t)c_2y_2) \end{aligned}$$

$$L(c_1y_1 + c_2y_2) = c_1L(y_1) + c_2L(y_2). \quad \square$$

## Operator notation and preliminary results.

### Theorem

Given functions  $p, q, f$ , let  $L(y) = y'' + p(t)y' + q(t)y$ . If the functions  $y_1$  and  $y_2$  are fundamental solutions of the homogeneous equation

$$L(y) = 0,$$

and  $y_p$  is any solution of the non-homogeneous equation

$$L(y_p) = f, \tag{1}$$

then any other solution  $y$  of the non-homogeneous equation above is given by

$$y(t) = c_1y_1(t) + c_2y_2(t) + y_p(t), \tag{2}$$

where  $c_1, c_2 \in \mathbb{R}$ .

**Notation:** The expression for  $y$  in Eq. (2) is called the **general solution** of the **non-homogeneous** Eq. (1).

## Operator notation and preliminary results.

### Theorem

Given functions  $p, q$ , let  $L(y) = y'' + p(t)y' + q(t)y$ .

If the function  $f$  can be written as  $f(t) = f_1(t) + \cdots + f_n(t)$ , with  $n \geq 1$ , and if there exist functions  $y_{p_1}, \cdots, y_{p_n}$  such that

$$L(y_{p_i}) = f_i, \quad i = 1, \cdots, n,$$

then the function  $y_p = y_{p_1} + \cdots + y_{p_n}$  satisfies the non-homogeneous equation

$$L(y_p) = f.$$

## Non-homogeneous equations (Sect. 2.5).

- ▶ We study:  $y'' + a_1 y' + a_0 y = b(t)$ .
- ▶ Operator notation and preliminary results.
- ▶ **Summary of the undetermined coefficients method.**
- ▶ Using the method in few examples.
- ▶ The guessing solution table.

## Summary of the undetermined coefficients method.

**Problem:** Given a constant coefficients linear operator  $L(y) = y'' + a_1y' + a_0y$ , with  $a_1, a_2 \in \mathbb{R}$ , find every solution of the non-homogeneous differential equation

$$L(y) = f.$$

**Remarks:**

- ▶ The undetermined coefficients is a method to find solutions to linear, non-homogeneous, constant coefficients, differential equations.
- ▶ It consists in **guessing** the solution  $y_p$  of the non-homogeneous equation

$$L(y_p) = f,$$

for particularly simple source functions  $f$ .

## Summary of the undetermined coefficients method.

**Summary:**

- (1) Find the general solution of the homogeneous equation  $L(y_h) = 0$ .
- (2) If  $f$  has the form  $f = f_1 + \cdots + f_n$ , with  $n \geq 1$ , then look for solutions  $y_{p_i}$ , with  $i = 1, \dots, n$  to the equations

$$L(y_{p_i}) = f_i.$$

Once the functions  $y_{p_i}$  are found, then construct

$$y_p = y_{p_1} + \cdots + y_{p_n}.$$

- (3) Given the source functions  $f_i$ , guess the solutions functions  $y_{p_i}$  following the **Table** below.

## Summary of the undetermined coefficients method.

Summary (cont.):

$f_i(t)$ ( $K, m, a, b$ , given.)	$y_{p_i}(t)$ (Guess) ( $k$ not given.)
$Ke^{at}$	$ke^{at}$
$Kt^m$	$k_m t^m + k_{m-1} t^{m-1} + \dots + k_0$
$K \cos(bt)$	$k_1 \cos(bt) + k_2 \sin(bt)$
$K \sin(bt)$	$k_1 \cos(bt) + k_2 \sin(bt)$
$Kt^m e^{at}$	$e^{at}(k_m t^m + \dots + k_0)$
$Ke^{at} \cos(bt)$	$e^{at}[k_1 \cos(bt) + k_2 \sin(bt)]$
$Ke^{at} \sin(bt)$	$e^{at}[k_1 \cos(bt) + k_2 \sin(bt)]$
$Kt^m \cos(bt)$	$(k_m t^m + \dots + k_0)[a_1 \cos(bt) + a_2 \sin(bt)]$
$Kt^m \sin(bt)$	$(k_m t^m + \dots + k_0)[a_1 \cos(bt) + a_2 \sin(bt)]$

## Summary of the undetermined coefficients method.

Summary (cont.):

- (4) If any guessed function  $y_{p_i}$  satisfies the homogeneous equation  $L(y_{p_i}) = 0$ , then change the guess to the function

$$t^s y_{p_i}, \quad \text{with } s \geq 1,$$

and  $s$  sufficiently large such that  $L(t^s y_{p_i}) \neq 0$ .

- (5) Impose the equation  $L(y_{p_i}) = f_i$  to find the undetermined constants  $k_1, \dots, k_m$ , for the appropriate  $m$ , given in the table above.
- (6) The general solution to the original differential equation  $L(y) = f$  is then given by

$$y(t) = y_h(t) + y_{p_1} + \dots + y_{p_n}.$$

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- ▶ **Using the method in few examples.**
- ▶ The guessing solution table.

### Using the method in few examples.

#### Example

Find all solutions to the non-homogeneous equation

$$y'' - 3y' - 4y = 3e^{2t}.$$

**Solution:** Notice:  $L(y) = y'' - 3y' - 4y$  and  $f(t) = 3e^{2t}$ .

(1) Find all solutions  $y_h$  to the homogeneous equation  $L(y_h) = 0$ .

The characteristic equation is

$$r^2 - 3r - 4 = 0 \quad \Rightarrow \quad \begin{cases} r_1 = 4, \\ r_2 = -1. \end{cases}$$

$$y_h(t) = c_1 e^{4t} + c_2 e^{-t}.$$

(2) Trivial in our case. The source function  $f(t) = 3e^{2t}$  cannot be simplified into a sum of simpler functions.

(3) Table says: For  $f(t) = 3e^{2t}$  guess  $y_p(t) = k e^{2t}$

## Using the method in few examples.

### Example

Find all solutions to the non-homogeneous equation

$$y'' - 3y' - 4y = 3e^{2t}.$$

**Solution:** Recall:  $y_p(t) = k e^{2t}$ . We need to find  $k$ .

(4) Trivial here, since  $L(y_p) \neq 0$ , we do not modify our guess.

(Recall:  $L(y_h) = 0$  iff  $y_h(t) = c_1 e^{4t} + c_2 e^{-t}$ .)

(5) Introduce  $y_p$  into  $L(y_p) = f$  and find  $k$ .

$$(2^2 - 6 - 4)k e^{2t} = 3e^{2t} \Rightarrow -6k = 3 \Rightarrow k = -\frac{1}{2}.$$

We have obtained that  $y_p(t) = -\frac{1}{2} e^{2t}$ .

(6) The general solution to the inhomogeneous equation is

$$y(t) = c_1 e^{4t} + c_2 e^{-t} - \frac{1}{2} e^{2t}.$$

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## Using the method in few examples.

### Example

Find all solutions to the non-homogeneous equation

$$y'' - 3y' - 4y = 3e^{4t}.$$

**Solution:** We know that the general solution to homogeneous equation is  $y_h(t) = c_1 e^{4t} + c_2 e^{-t}$ .

Following the table we guess  $y_p$  as  $y_p = k e^{4t}$ .

However, this guess satisfies  $L(y_p) = 0$ .

So we modify the guess to  $y_p = kt e^{4t}$ .

Introduce the guess into  $L(y_p) = f$ . We need to compute

$$y_p' = k e^{4t} + 4kt e^{4t}, \quad y_p'' = 8k e^{4t} + 16kt e^{4t}.$$

## Using the method in few examples.

### Example

Find all solutions to the non-homogeneous equation

$$y'' - 3y' - 4y = 3e^{4t}.$$

Solution: Recall:

$$y_p = kt e^{4t}, \quad y'_p = k e^{4t} + 4kt e^{4t}, \quad y''_p = 8k e^{4t} + 16kt e^{4t}.$$

$$[(8k + 16kt) - 3(k + 4kt) - 4kt] e^{4t} = 3e^{4t}.$$

$$[(8 + 16t) - 3(1 + 4t) - 4t] k = 3 \quad \Rightarrow \quad [5 + (16 - 12 - 4)t] k = 3$$

We obtain that  $k = \frac{3}{5}$ . Therefore,  $y_p(t) = \frac{3}{5} t e^{4t}$ , and

$$y(t) = c_1 e^{4t} + c_2 e^{-t} + \frac{3}{5} t e^{4t}. \quad \triangleleft$$

## Using the method in few examples.

### Example

Find all the solutions to the inhomogeneous equation

$$y'' - 3y' - 4y = 2 \sin(t).$$

Solution: We know that the general solution to homogeneous equation is  $y(t) = c_1 e^{4t} + c_2 e^{-t}$ .

Following the table: Since  $f = 2 \sin(t)$ , then we guess

$$y_p = k_1 \sin(t) + k_2 \cos(t).$$

This guess satisfies  $L(y_p) \neq 0$ .

Compute:  $y'_p = k_1 \cos(t) - k_2 \sin(t)$ ,  $y''_p = -k_1 \sin(t) - k_2 \cos(t)$ .

$$\begin{aligned} L(y_p) &= [-k_1 \sin(t) - k_2 \cos(t)] - 3[k_1 \cos(t) - k_2 \sin(t)] \\ &\quad - 4[k_1 \sin(t) + k_2 \cos(t)] = 2 \sin(t), \end{aligned}$$



## Using the method in few examples.

### Example

Find all the solutions to the inhomogeneous equation

$$y'' - 3y' - 4y = 2 \sin(t).$$

Solution: Recall:

$$\begin{aligned} L(y_p) &= [-k_1 \sin(t) - k_2 \cos(t)] - 3[k_1 \cos(t) - k_2 \sin(t)] \\ &\quad - 4[k_1 \sin(t) + k_2 \cos(t)] = 2 \sin(t), \end{aligned}$$

$$(-5k_1 + 3k_2) \sin(t) + (-3k_1 - 5k_2) \cos(t) = 2 \sin(t).$$

This equation holds for all  $t \in \mathbb{R}$ . In particular, at  $t = \frac{\pi}{2}$ ,  $t = 0$ .

$$\left. \begin{aligned} -5k_1 + 3k_2 &= 2, \\ -3k_1 - 5k_2 &= 0, \end{aligned} \right\} \Rightarrow \begin{cases} k_1 = -\frac{5}{17}, \\ k_2 = \frac{3}{17}. \end{cases}$$

## Using the method in few examples.

### Example

Find all the solutions to the inhomogeneous equation

$$y'' - 3y' - 4y = 2 \sin(t).$$

Solution: Recall:  $k_1 = -\frac{5}{17}$  and  $k_2 = \frac{3}{17}$ .

So the particular solution to the inhomogeneous equation is

$$y_p(t) = \frac{1}{17} [-5 \sin(t) + 3 \cos(t)].$$

The general solution is

$$y(t) = c_1 e^{4t} + c_2 e^{-t} + \frac{1}{17} [-5 \sin(t) + 3 \cos(t)]. \quad \triangleleft$$

## Using the method in few examples.

### Example

Find all the solutions to the inhomogeneous equation

$$y'' - 3y' - 4y = 3e^{2t} + 2\sin(t).$$

**Solution:** We know that the general solution  $y$  is given by

$$y(t) = y_h(t) + y_{p_1}(t) + y_{p_2}(t),$$

where  $y_h(t) = c_1 e^{4t} + c_2 e^{2t}$ ,  $L(y_{p_1}) = 3e^{2t}$ , and  $L(y_{p_2}) = 2\sin(t)$ .

We have just found out that

$$y_p(t) = -\frac{1}{2} e^{2t}, \quad y_{p_2}(t) = \frac{1}{17} [-5\sin(t) + 3\cos(t)].$$

We conclude that

$$y(t) = c_1 e^{4t} + c_2 e^{2t} - \frac{1}{2} e^{2t} + \frac{1}{17} [-5\sin(t) + 3\cos(t)]. \quad \triangleleft$$

## Using the method in few examples.

### Example

- ▶ For  $y'' - 3y' - 4y = 3e^{2t} \sin(t)$ , guess

$$y_p(t) = [k_1 \sin(t) + k_2 \cos(t)] e^{2t}.$$

- ▶ For  $y'' - 3y' - 4y = 2t^2 e^{3t}$ , guess

$$y_p(t) = (k_0 + k_1 t + k_2 t^2) e^{3t}.$$

- ▶ For  $y'' - 3y' - 4y = 3t \sin(t)$ , guess

$$y_p(t) = (1 + k_1 t) [k_2 \sin(t) + k_3 \cos(t)].$$

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## The guessing solution table.

Guessing Solution Table.

$f_i(t)$ ( $K, m, a, b$ , given.)	$y_{p_i}(t)$ (Guess) ( $k$ not given.)
$Ke^{at}$	$ke^{at}$
$Kt^m$	$k_m t^m + k_{m-1} t^{m-1} + \dots + k_0$
$K \cos(bt)$	$k_1 \cos(bt) + k_2 \sin(bt)$
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