## Review for Exam 2

- Tuesday Recitations: Sections 13.1-13.3. 14.1-14.6.
- Thursday Recitations: Sections 13.1-13.3. 14.1-14.7.
- 50 minutes.
- From five 10 -minute problems to ten 5-minutes problems.
- Problems similar to homework problems.
- No calculators, no notes, no books, no phones.


## Section 13.2: Projectile motion

## Example

Find the position $\mathbf{r}$ and velocity functions $\mathbf{v}$ of a particle moving with an acceleration $\mathbf{a}(t)=\langle 0,0,-10\rangle \mathrm{m} / \mathrm{sec}^{2}$. The initial velocity and position are, $\mathbf{v}(0)=\langle 0,2,1\rangle \mathrm{m} / \mathrm{sec}$ and $\mathbf{r}(0)=\langle 0,0,2\rangle \mathrm{m}$.

Solution: Since $\mathbf{a}(t)=\langle 0,0,-10\rangle$,

$$
\left.\begin{array}{rl}
\mathbf{v}(t)= & \left\langle v_{0 x}, v_{0 y},-10 t+v_{0 z}\right\rangle, \\
& \mathbf{v}(0)=\langle 0,2,1\rangle,
\end{array}\right\} \Rightarrow\left\{\begin{array}{l}
v_{0 x}=0 \\
v_{0 y}=2 \\
v_{0 z}=1
\end{array}\right.
$$

The velocity is $\mathbf{v}(t)=\langle 0,2,-10 t+1\rangle$. the position is

$$
\left.\begin{array}{c}
\mathbf{r}(t)=\left\langle r_{0 x}, 2 t+r_{0 y},-5 t^{2}+t+r_{0 z}\right\rangle, \\
\mathbf{r}(0)=\langle 0,0,2\rangle,
\end{array}\right\} \Rightarrow\left\{\begin{array}{l}
r_{0 x}=0 \\
r_{0 y}=0 \\
r_{0 z}=2
\end{array}\right.
$$

We conclude that $\mathbf{r}(t)=\left\langle 0,2 t,-5 t^{2}+t+2\right\rangle$.

## Section 13.2: Projectile motion

## Example

Find the trajectory of the particle in the previous example.
Solution: Recall $\mathbf{r}(t)=\left\langle 0,2 t,-5 t^{2}+t+2\right\rangle$.

$$
x(t)=0, \quad y(t)=2 t, \quad z(t)=-5 t^{2}+t+2
$$

The trajectory is $z(y)=-\frac{5}{4} y^{2}+\frac{y}{2}+2$.


## Section 13.3

## Example

Reparametrize with respect to its arclength, starting at $t=0$, the position function $\mathbf{r}$ corresponding to the acceleration
$\mathbf{a}(t)=\langle[-\sin (t)-\cos (t)],[\cos (t)-\sin (t)], 0\rangle$ and initial velocity $\mathbf{v}_{0}=\langle 1,1,1\rangle$ and initial position $\mathbf{r}_{0}=\langle 0,0,0\rangle$.

Solution: First, we need to find $\mathbf{r}(t)$. Then, we reparametrize.

$$
\mathbf{v}(t)=\left\langle\left[\cos (t)-\sin (t)+v_{0 x}\right],\left[\sin (t)+\cos (t)+v_{0 y}\right], v_{0 z}\right\rangle .
$$

The initial condition implies

$$
\begin{aligned}
& \left\langle 1+v_{0 x}, 1+v_{0 y}, v_{0 z}\right\rangle=\langle 1,1,1\rangle \quad \Rightarrow \quad v_{0 x}=0=v_{0 y}, \quad v_{0 z}=1 . \\
& \mathbf{v}(t)=\langle[\cos (t)-\sin (t)],[\sin (t)+\cos (t)], 1\rangle .
\end{aligned}
$$

## Section 13.3

## Example

Reparametrize with respect to its arclength, starting at $t=0$, the position function $\mathbf{r}$ corresponding to the acceleration $\mathbf{a}(t)=\langle[-\sin (t)-\cos (t)],[\cos (t)-\sin (t)], 0\rangle$ and initial velocity $\mathbf{v}_{0}=\langle 1,1,1\rangle$ and initial position $\mathbf{r}_{0}=\langle 0,0,0\rangle$.

Solution: Recall: $\mathbf{v}(t)=\langle[\cos (t)-\sin (t)],[\sin (t)+\cos (t)], 1\rangle$.
The position function is

$$
\mathbf{r}(t)=\left\langle\left[\sin (t)+\cos (t)+r_{0 x}\right],\left[-\cos (t)+\sin (t)+r_{0 y}\right], t+r_{0 z}\right\rangle
$$

The initial condition implies

$$
\begin{gathered}
\left\langle 1+r_{0 x},-1+r_{0 y}, r_{0 z}\right\rangle=\langle 0,0,0\rangle \Rightarrow r_{0 x}=-1, r_{0 y}=1, r_{0 z}=0 . \\
\mathbf{r}(t)=\langle[\sin (t)+\cos (t)-1],[-\cos (t)+\sin (t)+1], t\rangle .
\end{gathered}
$$

## Section 13.3

## Example

Reparametrize with respect to its arclength, starting at $t=0$, the position function $\mathbf{r}$.

Solution: Recall: $\mathbf{v}(t)=\langle[\cos (t)-\sin (t)],[\sin (t)+\cos (t)], 1\rangle$, and recall $\mathbf{r}(t)=\langle[\sin (t)+\cos (t)-1],[-\cos (t)+\sin (t)+1], t\rangle$.
Then, $|\mathbf{v}(t)|^{2}=[\cos (t)-\sin (t)]^{2}+[\cos (t)+\sin (t)]^{2}+1$

$$
\begin{gathered}
|\mathbf{v}(t)|^{2}=\cos ^{2}(t)+\sin ^{2}(t)-2 \sin (t) \cos (t) \\
+\cos ^{2}(t)+\sin ^{2}(t)+2 \sin (t) \cos (t)+1 \\
|\mathbf{v}(t)|=\sqrt{3}, \text { therefore } \ell(t)=\int_{0}^{t} \sqrt{3} d \tau \text { implies } \ell=\sqrt{3} t . \\
\hat{\mathbf{r}}(\ell)=\left\langle\left[\sin \left(\frac{\ell}{\sqrt{3}}\right)+\cos \left(\frac{\ell}{\sqrt{3}}\right)-1\right],\left[-\cos \left(\frac{\ell}{\sqrt{3}}\right)+\sin \left(\frac{\ell}{\sqrt{3}}\right)+1\right], \frac{\ell}{\sqrt{3}}\right\rangle .
\end{gathered}
$$

## Section 13.3

## Example

Reparametrize the curve $\mathbf{r}(t)=\left\langle\frac{3}{2} \sin \left(t^{2}\right), 2 t^{2}, \frac{3}{2} \cos \left(t^{2}\right)\right\rangle$ with respect to its arc length measured from $t=1$ in the direction of increasing $t$.

## Solution:

We first compute the arc length function. We start with the derivative

$$
\mathbf{r}^{\prime}(t)=\left\langle 3 t \cos \left(t^{2}\right), 4 t,-3 \sin \left(t^{2}\right)\right\rangle
$$

We now need its magnitude,

$$
\begin{gathered}
\left|\mathbf{r}^{\prime}(t)\right|=\sqrt{9 t^{2} \cos ^{2}\left(t^{2}\right)+16 t^{2}+9 \sin ^{2}\left(t^{2}\right)} \\
\left|\mathbf{r}^{\prime}(t)\right|=\sqrt{9 t^{2}+16 t^{2}}=(\sqrt{9+16}) t \quad \Rightarrow \quad\left|\mathbf{r}^{\prime}(t)\right|=5 t
\end{gathered}
$$

## Section 13.3

## Example

Reparametrize the curve $\mathbf{r}(t)=\left\langle\frac{3}{2} \sin \left(t^{2}\right), 2 t^{2}, \frac{3}{2} \cos \left(t^{2}\right)\right\rangle$ with respect to its arc length measured from $t=1$ in the direction of increasing $t$.

Solution: Recall: $\left|\mathbf{r}^{\prime}(t)\right|=5 t$. The arc length function is

$$
s(t)=\int_{1}^{t} 5 \tau d \tau=\frac{5}{2}\left(\left.\tau^{2}\right|_{1} ^{t}\right)=\frac{5}{2}\left(t^{2}-1\right)
$$

Inverting this function for $t^{2}$, we obtain $t^{2}=\frac{2}{5} s+1$.
The reparametrization of $\mathbf{r}(t)$ is given by

$$
\hat{\mathbf{r}}(s)=\left\langle\frac{3}{2} \sin \left(\frac{2}{5} s+1\right), 2\left(\frac{2}{5} s+1\right), \frac{3}{2} \cos \left(\frac{2}{5} s+1\right)\right\rangle .
$$

## Section 14.2

## Example

Find an equation for the level surface of $f(x, y, z)=z-x^{2}-y^{2}$ containing the point $P_{0}=(3,-1,1)$.

Solution: Any level surface is the set of points is space solution of

$$
z-x^{2}-y^{2}=k, \quad k \in \mathbb{R}
$$

To find $k$, we evaluate the equation above at $P_{0}$,

$$
1-9-1=k \quad \Rightarrow \quad k=-9
$$

We conclude that $z-x^{2}-y^{2}=-9$.

## Section 14.2

## Example

Compute the limit $\lim _{(x, y) \rightarrow(4,3)} \frac{\sqrt{x}-\sqrt{y+1}}{x-y-1}$.
Solution: Remark: $f(x, y)=\frac{\sqrt{x}-\sqrt{y+1}}{x-y-1}$ is not defined at $(4,3)$.
Recall from Calculus I: Multiply by the conjugate.

$$
\begin{gathered}
f(x, y)=\left[\frac{\sqrt{x}-\sqrt{y+1}}{x-y-1}\right]\left[\frac{\sqrt{x}+\sqrt{y+1}}{\sqrt{x}+\sqrt{y+1}}\right] \\
f(x, y)=\frac{[x-(y+1)]}{(x-y-1)[\sqrt{x}+\sqrt{y+1}]}=\frac{1}{\sqrt{x}+\sqrt{y+1}} .
\end{gathered}
$$

We conclude that, $\lim _{(x, y) \rightarrow(4,3)} f(x, y)=\frac{1}{4}$.

## Section 14.2

Example
Compute the limit $\lim _{(x, y) \rightarrow(0,0)} \frac{x^{2}+y^{2}}{x y}$.
Solution: Remark: $f(x, y)=\frac{x^{2}+y^{2}}{x y}$ is not defined at $(0,0)$.
Recall: It is often easier to prove that a limit does not exist.
The two paths theorem. Paths $x=0$ or $y=0$ are not useful.
First path, $y=x$. Then

$$
\lim _{x \rightarrow 0} f(x, x)=\lim _{x \rightarrow 0} \frac{x^{2}+x^{2}}{x^{2}}=\lim _{x \rightarrow 0} 2=2
$$

Second path, $y=2 x$. Then

$$
\lim _{x \rightarrow 0} f(x, 2 x)=\lim _{x \rightarrow 0} \frac{x^{2}+4 x^{2}}{x(2 x)}=\lim _{x \rightarrow 0} \frac{5}{2}=\frac{5}{2}
$$

Therefore, $\lim _{(x, y) \rightarrow(0,0)} f(x, y)$ DNE.

## Section 14.3

## Example

Given a function $z$ defined by the equation $x y+z^{3} x-2 y z=0$, find $\partial_{x} z$ in terms of $x, y$ and $z$.

Solution: We use implicit differentiation:

$$
\begin{gather*}
y+z^{3}+3 z^{2} z_{X} x-2 y z_{x}=0 \\
z_{x}\left(3 x z^{2}-2 y\right)=-y-z^{3} \\
z_{x}=-\frac{\left(y+z^{3}\right)}{\left(3 x z^{2}-2 y\right)}
\end{gather*}
$$

## Section 14.4

Example
Given $f(x, y)=e^{x y}$, and the coordinate transformation
$x=r \cos (\theta)$ and $y=r \sin (\theta)$, find $\hat{f}_{r}$ and $\hat{f}_{\theta}$, where
$\hat{f}(r, \theta)=f(x(r, \theta), y(r, \theta))$.
Solution: The chain rule implies

$$
\begin{gathered}
\hat{f}_{r}=f_{x} x_{r}+f_{y} y_{r}, \quad \hat{f}_{\theta}=f_{x} x_{\theta}+f_{y} y_{\theta} \\
\hat{f}_{r}=y e^{x y} x_{r}+x e^{x y} y_{r} \quad \Rightarrow \quad \hat{f}_{r} e^{x y}\left(y x_{r}+x y_{r}\right) \\
\hat{f}_{r}=e^{r^{2} \sin (\theta) \cos (\theta)}[r \sin (\theta) \cos (\theta)+r \cos (\theta) \sin (\theta)] \\
\hat{f}_{\theta}=y e^{x y} x_{\theta}+x e^{x y} y_{\theta} \quad \Rightarrow \quad \hat{f}_{\theta}=e^{x y}\left(y x_{\theta}+x y_{\theta}\right) \\
\hat{f}_{\theta}=e^{r^{2} \sin (\theta) \cos (\theta)}\left[-r^{2} \sin (\theta) \sin (\theta)+r^{2} \cos (\theta) \cos (\theta)\right] .
\end{gathered}
$$

Also: $\hat{f}_{r}=r \sin (2 \theta) e^{r^{2} \sin (2 \theta) / 2}$, and $\hat{f}_{\theta}=r^{2} \cos (2 \theta) e^{r^{2} \sin (2 \theta) / 2}$.

## Section 14.5

## Example

Find all directions $\mathbf{u}$ such that $\left(D_{\mathbf{u}} f\right)(1,1)=0$, where $f(x, y)=\frac{x^{2}-y^{2}}{x^{2}+y^{2}}$.
Solution: Recall: The $D_{\mathbf{u}} f=0$ iff $\mathbf{u} \perp \nabla f$. The gradient is

$$
\begin{gathered}
f_{x}=\frac{2 x\left(x^{2}+y^{2}\right)}{\left(x^{2}+y^{2}\right)^{2}}-\frac{\left(x^{2}-y^{2}\right) 2 x}{\left(x^{2}+y^{2}\right)^{2}} \Rightarrow f_{x}=\frac{4 x y^{2}}{\left(x^{2}+y^{2}\right)^{2}} . \\
f_{y}=\frac{-2 y\left(x^{2}+y^{2}\right)}{\left(x^{2}+y^{2}\right)^{2}}-\frac{\left(x^{2}-y^{2}\right) 2 y}{\left(x^{2}+y^{2}\right)^{2}} \Rightarrow f_{y}=\frac{-4 y x^{2}}{\left(x^{2}+y^{2}\right)^{2}} . \\
\nabla f=\frac{4 x y}{\left(x^{2}+y^{2}\right)^{2}}\langle y,-x\rangle . \quad \Rightarrow \quad(\nabla f)(1,1)=\langle 1,-1\rangle .
\end{gathered}
$$

## Section 14.5

## Example

Find all directions $\mathbf{u}$ such that $\left(D_{\mathbf{u}} f\right)(1,1)=0$, where
$f(x, y)=\frac{x^{2}-y^{2}}{x^{2}+y^{2}}$.
Solution: Recall: $(\nabla f)(1,1)=\langle 1,-1\rangle$.
We find all $\mathbf{u}$, unit, such that $\mathbf{u} \perp\langle 1,-1\rangle$.

$$
\left\langle u_{x}, u_{y}\right\rangle \cdot\langle 1,-1\rangle=0 \quad \Rightarrow \quad u_{x}=u_{y} .
$$

Since $\mathbf{u}$ is unit, then

$$
u_{x}^{2}+u_{y}^{2}=1 \quad \Rightarrow \quad 2 u_{x}^{2}=1 \quad \Rightarrow \quad u_{x}= \pm \frac{1}{\sqrt{2}}
$$

We conclude: $\mathbf{u}= \pm \frac{1}{\sqrt{2}}\langle 1,1\rangle$.

## Section 14.5

## Example

Find the direction of most rapid increase of the function $f(x, y, z)=\ln \left(x^{3}+y^{3}-1\right)-y+3 z$ at the point $P_{0}=(1,1,4)$.

Solution: Recall: The direction of most rapid increase is the direction of the gradient vector at $P_{0}$.

$$
\nabla f=\frac{3 x^{2}}{x^{3}+y^{3}-1} \mathbf{i}+\left(\frac{3 y^{2}}{x^{3}+y^{3}-1}-1\right) \mathbf{j}+3 \mathbf{k} .
$$

The direction of maximum increase is

$$
(\nabla f)(1,1,4)=\langle 3,2,3\rangle
$$

## Section 14.5

## Example

(a) Find the direction in which $f(x, y)=x^{2} e^{3 y}$ decreases the most rapidly at $P_{0}=(-1,0)$, and also find the directional derivative of $f(x, y)$ at $P_{0}$ along that direction.
(b) Find the directional derivative of $f(x, y)$ above at the point $P_{0}$ in the direction given by $\mathbf{v}=\langle-1,1\rangle$.

## Solution:

(a) The direction $f$ decreases the most rapidly is given by $-\nabla f$,

$$
\nabla f(x, y)=\left\langle 2 x e^{3 y}, 3 x^{2} e^{3 y}\right\rangle \quad \Rightarrow \quad-\nabla f(-1,0)=\langle 2,-3\rangle .
$$

The value of the directional derivative along this direction is, $-|\nabla f(-1,0)|=-\sqrt{9+4}=-\sqrt{13}$.
(b) A unit vector along $\langle-1,1\rangle$ is $\mathbf{u}=\frac{1}{\sqrt{2}}\langle-1,1\rangle$, then,

$$
D_{u} f(-1,0)=\nabla f(-1,0) \cdot \mathbf{u}=\langle-2,3\rangle \cdot \frac{1}{\sqrt{2}}\langle-1,1\rangle=\frac{5}{\sqrt{2}} .
$$

## Section 14.6

## Example

Find the linear approximation of $f(x, y)=x \cos (\pi y / 2)-y^{2} e^{x}$ at the point $(0,-1)$, and use it to approximate $f(0.1,-0.9)$.

Solution: $f(x, y)=x \cos (\pi y / 2)-y^{2} e^{x}, \quad f(0,-1)=-1$.

$$
\begin{gathered}
f_{x}(x, y)=\cos (\pi y / 2)-y^{2} e^{x}, \quad f_{x}(0,-1)=\cos (-\pi / 2)-1=-1 \\
f_{y}(x, y)=-x \sin (\pi y / 2) \frac{\pi}{2}-2 y e^{x} \quad f_{y}(0,-1)=2
\end{gathered}
$$

Then, the linear approximation $L(x, y)$ is given by

$$
L(x, y)=-(x-0)+2(y+1)-1, \quad \Rightarrow \quad L(x, y)=-x+2 y+1
$$

The linear approximation of $f(0.1,-0.9)$ is $L(0.1,-0.9)$, $L(0.1,-0.9)=-0.1+2(0.1)-1=0.1-1=-0.9$.

## Section 14.6

## Example

(a) Find the linear approximation $L(x, y)$ of the function $f(x, y)=\sin (2 x+3 y)+1$ at the point $(-3,2)$.
(b) Use the approximation above to estimate the value of $f(-2.9,2.1)$.

Solution:
(a) $L(x, y)=f_{x}(-3,2)(x+3)+f_{y}(-3,2)(y-2)+f(-3,2)$.

Since $f_{x}(x, y)=2 \cos (2 x+3 y)$ and $f_{y}(x, y)=3 \cos (2 x+3 y)$,
$f_{x}(-3,2)=2 \cos (-6+6)=2, \quad f_{y}(-3,2)=3 \cos (-6+6)=3$,

$$
f(-3,2)=\sin (-6+6)+1=1
$$

the linear approximation is $L(x, y)=2(x+3)+3(y-2)+1$.

## Section 14.6

## Example

(a) Find the linear approximation $L(x, y)$ of the function

$$
f(x, y)=\sin (2 x+3 y)+1 \text { at the point }(-3,2) .
$$

(b) Use the approximation above to estimate the value of $f(-2.9,2.1)$.

Solution: Recall: $L(x, y)=2(x+3)+3(y-2)+1$.
(b) We use $L$ to find the a linear approximation to $f(-2.9,2.1)$. We need to compute $L(-2.9,2.1)$.

$$
\begin{gathered}
L(-2.9,2.1)=2(-2.9+3)+3(2.1-2)+2 \\
L(-2.9,2.1)=2(0.1)+3(0.1)+1 \quad \Rightarrow \quad L(-2.9,2.1)=1.5 .
\end{gathered}
$$

Exact value is close to 1.479 .

## Section 14.7

## Example

(a) Find all the critical points of $f(x, y)=12 x y-2 x^{3}-3 y^{2}$.
(b) For each critical point of $f$, determine whether $f$ has a local maximum, local minimum, or saddle point at that point.

Solution:
(a) $\nabla f(x, y)=\left\langle 12 y-6 x^{2}, 12 x-6 y\right\rangle=\langle 0,0\rangle$, then,

$$
x^{2}=2 y, \quad y=2 x, \quad \Rightarrow \quad x(x-4)=0
$$

There are two solutions, $x=0 \Rightarrow y=0$, and $x=4 \Rightarrow y=8$.
That is, there are two critical points, $(0,0)$ and $(4,8)$.

## Section 14.7

## Example

(a) Find all the critical points of $f(x, y)=12 x y-2 x^{3}-3 y^{2}$.
(b) For each critical point of $f$, determine whether $f$ has a local maximum, local minimum, or saddle point at that point.

## Solution:

(b) Recalling $\nabla f(x, y)=\left\langle 12 y-6 x^{2}, 12 x-6 y\right\rangle$, we compute

$$
\begin{gathered}
f_{x x}=-12 x, \quad f_{y y}=-6, \quad f_{x y}=12 \\
D(x, y)=f_{x x} f_{y y}-\left(f_{x y}\right)^{2}=144\left(\frac{x}{2}-1\right),
\end{gathered}
$$

Since $D(0,0)=-144<0$, the point $(0,0)$ is a saddle point of $f$.
Since $D(4,8)=144(2-1)>0$, and $f_{x x}(4,8)=(-12) 4<0$, the point $(4,8)$ is a local maximum of $f$.

## Section 14.7

## Example

Find the absolute maximum and absolute minimum of
$f(x, y)=2+x y-2 x-\frac{1}{4} y^{2}$ in the closed triangular region with vertices given by $(0,0),(1,0)$, and ( 0,2 ).

## Solution:

We start finding the critical points inside the triangular region.

$$
\nabla f(x, y)=\left\langle y-2, x-\frac{1}{2} y\right\rangle=\langle 0,0\rangle, \quad \Rightarrow \quad y=2, \quad y=2 x
$$

The solution is $(1,2)$. This point is outside in the triangular region given by the problem, so there is no critical point inside the region.

## Section 14.7

## Example

Find the absolute maximum and absolute minimum of $f(x, y)=2+x y-2 x-\frac{1}{4} y^{2}$ in the closed triangular region with vertices given by $(0,0),(1,0)$, and ( 0,2 ).

## Solution:

We now find the candidates for absolute maximum and minimum on the borders of the triangular region. We first record the boundary vertices:

$$
\begin{aligned}
& (0,0) \quad \Rightarrow \quad f(0,0)=2 \\
& (1,0) \quad \Rightarrow \quad f(1,0)=0 \\
& (0,2) \quad \Rightarrow \quad f(0,2)=1
\end{aligned}
$$

## Section 14.7

## Example

Find the absolute maximum and absolute minimum of
$f(x, y)=2+x y-2 x-\frac{1}{4} y^{2}$ in the closed triangular region with vertices given by $(0,0),(1,0)$, and ( 0,2 ).

## Solution:

- The horizontal side of the triangle, $y=0, x \in(0,1)$. Since

$$
g(x)=f(x, 0)=2-2 x, \quad \Rightarrow \quad g^{\prime}(x)=-2 \neq 0
$$

there are no candidates in this part of the boundary.

- The vertical side of the triangle is $x=0, y \in(0,2)$. Then,

$$
g(y)=f(0, y)=2-\frac{1}{4} y^{2}, \quad \Rightarrow \quad g^{\prime}(y)=-\frac{1}{2} y=0
$$

so $y=0$ and we recover the point $(0,0)$.

## Section 14.7

## Example

Find the absolute maximum and absolute minimum of
$f(x, y)=2+x y-2 x-\frac{1}{4} y^{2}$ in the closed triangular region with vertices given by $(0,0),(1,0)$, and ( 0,2 ).

## Solution:

- The hypotenuse of the triangle $y=2-2 x, x \in(0,1)$. Then,

$$
\begin{aligned}
g(x)=f(x, 2-2 x) & =2+x(2-2 x)-2 x-\frac{1}{4}(2-2 x)^{2} \\
& =2+2 x-2 x^{2}-2 x-\left(x^{2}-2 x+1\right) \\
& =1+2 x-3 x^{2}
\end{aligned}
$$

Then, $g^{\prime}(x)=2-6 x=0$ implies $x=\frac{1}{3}$, hence $y=\frac{4}{3}$. The candidate is $\left(\frac{1}{3}, \frac{4}{3}\right)$.

## Section 14.7

## Example

Find the absolute maximum and absolute minimum of
$f(x, y)=2+x y-2 x-\frac{1}{4} y^{2}$ in the closed triangular region with vertices given by $(0,0),(1,0)$, and $(0,2)$.
Solution:

- Recall that we have obtained a candidate point $\left(\frac{1}{3}, \frac{4}{3}\right)$. We evaluate $f$ at this point,

$$
f\left(\frac{1}{3}, \frac{4}{3}\right)=2+\frac{4}{9}-\frac{2}{3}-\frac{1}{4} \frac{16}{9}=\frac{4}{3} .
$$

Recalling that $f(0,0)=2, f(1,0)=0$, and $f(0,2)=1$, the absolute maximum is at $(0,0)$, and the minimum is at $(1,0) . \quad \triangleleft$

