

## Surface area and surface integrals. (Sect. 16.6)

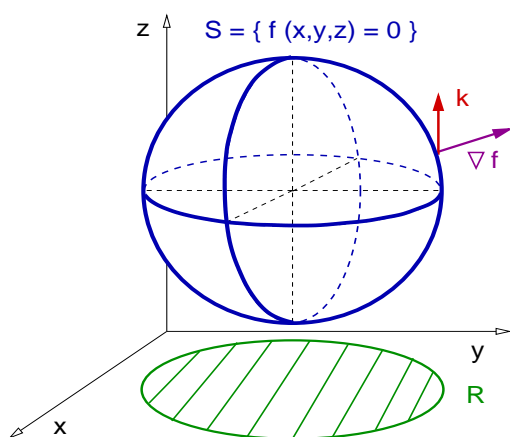
- ▶ Review: The area of a surface in space.
- ▶ Surface integrals of a scalar field.
- ▶ The flux of a vector field on a surface.
- ▶ Mass and center of mass thin shells.

### Review: The area of a surface in space

#### Theorem

Given a smooth function  $f : \mathbb{R}^3 \rightarrow \mathbb{R}$ , the area of a level surface  $S = \{f(x, y, z) = 0\}$ , over a closed, bounded region  $R$  in the plane  $\{z = 0\}$ , is given by

$$A(S) = \iint_R \frac{|\nabla f|}{|\nabla f \cdot \mathbf{k}|} dA.$$



**Remark:** Eq. (7), page 949, in the textbook is more general than the equation above, since the region  $R$  can be located on any plane, not only the plane  $\{z = 0\}$  considered here.

The vector  $\mathbf{p}$  in the textbook is the vector normal to  $R$ . In our case  $\mathbf{p} = \mathbf{k}$ .

## Surface area and surface integrals. (Sect. 16.6)

- ▶ Review: The area of a surface in space.
- ▶ **Surface integrals of a scalar field.**
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## Surface integrals of a scalar field

### Theorem

The integral of a continuous scalar function  $g : \mathbb{R}^3 \rightarrow \mathbb{R}$  over a surface  $S$  defined as the level set of  $f(x, y, z) = 0$  over the bounded plane  $R$  is given by

$$\iint_S g \, d\sigma = \iint_R g \frac{|\nabla f|}{|\nabla f \cdot \mathbf{p}} \, dA,$$

where  $\mathbf{p}$  is a unit vector normal to  $R$  and  $\nabla f \cdot \mathbf{p} \neq 0$ .

**Remark:** In the particular case  $g = 1$ , we recover the formula for the area  $A(S) = \iint_S d\sigma$  of the surface  $S$ , that is,

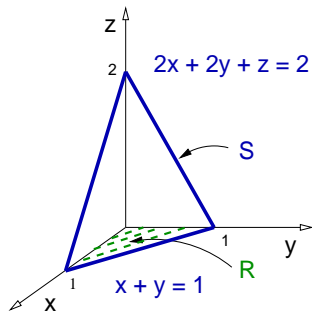
$$A(S) = \iint_R \frac{|\nabla f|}{|\nabla f \cdot \mathbf{p}} \, dA.$$

## Surface integrals of a scalar field

### Example

Integrate the function  $g(x, y, z) = x + y + z$  over the surface given by the portion of the plane  $2x + 2y + z = 2$  that lies in the first octant.

Solution: Recall: 
$$\iint_S g \, d\sigma = \iint_R g \frac{|\nabla f|}{|\nabla f \cdot \mathbf{p}|} \, dA.$$



Here  $f = 2x + 2y + z - 2$ , so the surface  $S$  is given by  $f = 0$  in the first octant. Hence, the region  $R$  is on the  $z = 0$  plane, (therefore  $\mathbf{p} = \mathbf{k}$ ) given by the triangle with sides  $x = 0$ ,  $y = 0$  and  $x + y = 1$ .

So,  $\nabla f = \langle 2, 2, 1 \rangle$ , hence  $|\nabla f| = 3$ , and  $|\nabla f \cdot \mathbf{k}| = 1$ . Therefore

$$\iint_S g \, d\sigma = \iint_R g(x, y, z) 3 \, dA.$$

## Surface integrals of a scalar field

### Example

Integrate the function  $g(x, y, z) = x + y + z$  over the surface given by the portion of the plane  $2x + 2y + z = 2$  that lies in the first octant.

Solution: Recall: 
$$\iint_S g \, d\sigma = \iint_R g(x, y, z) 3 \, dA.$$

Now, function  $g$  must be evaluated on the surface  $S$ . That means

$$g(x, y, z(x, y)) = x + y + z(x, y) = x + y + (2 - 2x - 2y).$$

$$g(x, y, z(x, y)) = 2 - x - y.$$

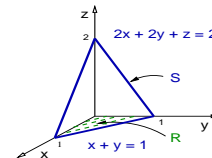
$$\iint_S g \, d\sigma = 3 \iint_R (2 - x - y) \, dA.$$

## Surface integrals of a scalar field

### Example

Integrate the function  $g(x, y, z) = x + y + z$  over the surface given by the portion of the plane  $2x + 2y + z = 2$  that lies in the first octant.

Solution: 
$$\iint_S g \, d\sigma = 3 \iint_R (2 - x - y) \, dA.$$



The region  $R$  is the triangle in the plane  $z = 0$  given by the lines  $x = 0$ ,  $y = 0$ , and  $x + y = 1$ . Therefore,

$$3 \int_0^1 \int_0^{1-y} (2-x-y) \, dx \, dy = 3 \int_0^1 \left[ (2-y) \left( x \Big|_0^{1-y} \right) - \left( \frac{x^2}{2} \Big|_0^{1-y} \right) \right] dy$$

$$\iint_S g \, d\sigma = 3 \int_0^1 \left[ (2-y)(1-y) - \frac{1}{2}(1-y)^2 \right] dy$$

$$\iint_S g \, d\sigma = 3 \int_0^1 \left( \frac{3}{2} - 2y + \frac{y^2}{2} \right) dy \quad \Rightarrow \quad \iint_S g \, d\sigma = 2. \quad \triangleleft$$

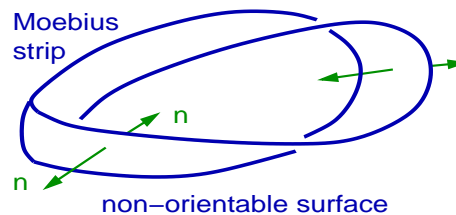
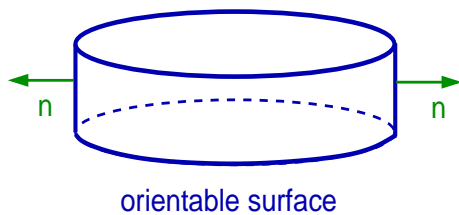
## Surface area and surface integrals. (Sect. 16.6)

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- ▶ **The flux of a vector field on a surface.**
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## The flux of a vector field on a surface

### Definition

A surface  $S \subset \mathbb{R}^3$  is called *orientable* if it is possible to define on  $S$  a continuous, unit vector field  $\mathbf{n}$  normal to  $S$ .



### Definition

The *flux* of a continuous vector field  $\mathbf{F} : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  over an orientable surface  $S$  in the direction of a unit normal  $\mathbf{n}$  is given by

$$\mathbb{F} = \iint_S \mathbf{F} \cdot \mathbf{n} \, d\sigma.$$

Remark:  $d\sigma = \frac{|\nabla f|}{|\nabla f \cdot \mathbf{p}|} dA$ , where  $S$  is the level surface  $f = 0$ .

## The flux of a vector field on a surface

### Example

Find the flux of the field  $\mathbf{F} = \langle 0, 0, z \rangle$  across the portion of the sphere  $x^2 + y^2 + z^2 = a^2$  in the first octant in the direction away from the origin.

Solution: Recall:  $\mathbb{F} = \iint_S \mathbf{F} \cdot \mathbf{n} \, d\sigma$ .

In this case  $S$  is the level surface  $f = 0$ , for  $f = x^2 + y^2 + z^2 - a^2$ . The unit normal vector  $\mathbf{n}$  is proportional to  $\nabla f$ .

$$\nabla f = \langle 2x, 2y, 2z \rangle, \quad |\nabla f| = 2\sqrt{x^2 + y^2 + z^2}.$$

On the surface  $S$  we have that  $x^2 + y^2 + z^2 = a^2$ , therefore,  $|\nabla f| = 2a$  on this surface. We obtain that on  $S$  the appropriate normal vector is

$$\mathbf{n} = \frac{\nabla f}{|\nabla f|} \Rightarrow \mathbf{n} = \frac{1}{a} \langle x, y, z \rangle, \quad z|_S = z(x, y).$$

## The flux of a vector field on a surface

### Example

Find the flux of the field  $\mathbf{F} = \langle 0, 0, z \rangle$  across the portion of the sphere  $x^2 + y^2 + z^2 = a^2$  in the first octant in the direction away from the origin.

**Solution:** Recall:  $\mathbb{F} = \iint_S \mathbf{F} \cdot \mathbf{n} \, d\sigma$  and  $\mathbf{n} = \frac{1}{a} \langle x, y, z \rangle$  on  $S$ .

Since  $d\sigma = \frac{|\nabla f|}{|\nabla f \cdot \mathbf{k}|} \, dx \, dy$ , and  $\nabla f = 2\langle x, y, z \rangle$ , which on  $S$  says

$|\nabla f| = 2a$ , we conclude,  $d\sigma = \frac{2a}{2z} \, dx \, dy$ , hence  $d\sigma = \frac{a}{z} \, dx \, dy$ .

$$\mathbb{F} = \iint_R \left( \langle 0, 0, z \rangle \cdot \frac{1}{a} \langle x, y, z \rangle \right) \frac{a}{z} \, dx \, dy.$$

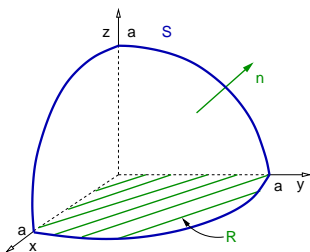
$$\mathbb{F} = \iint_R \frac{z^2}{a} \frac{a}{z} \, dx \, dy \quad \Rightarrow \quad \mathbb{F} = \iint_R z \, dx \, dy, \quad z|_S = z(x, y).$$

## The flux of a vector field on a surface.

### Example

Find the flux of the field  $\mathbf{F} = \langle 0, 0, z \rangle$  across the portion of the sphere  $x^2 + y^2 + z^2 = a^2$  in the first octant in the direction away from the origin.

**Solution:** Recall:  $\mathbb{F} = \iint_R z \, dx \, dy$ , and  $z$  must be evaluated on  $S$ .



The integral is only on the first octant.

$$\mathbb{F} = \iint_R \sqrt{a^2 - x^2 - y^2} \, dx \, dy.$$

We use polar coordinates on  $R \subset \{z = 0\}$ .

$$\mathbb{F} = \int_0^{\pi/2} \int_0^a \sqrt{a^2 - r^2} \, r \, dr \, d\theta. \quad u = a^2 - r^2, \quad du = -2r \, dr.$$

$$\mathbb{F} = \frac{\pi}{2} \int_{a^2}^0 u^{1/2} \frac{(-du)}{2} = \frac{\pi}{4} \int_0^{a^2} u^{1/2} \, du = \frac{\pi}{4} \frac{2}{3} (a^2)^{3/2} \Rightarrow \mathbb{F} = \frac{\pi a^3}{6}.$$

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## Mass and center of mass of thin shells

### Definition

The *mass*  $M$  of a thin shell described by the surface  $S$  in space with mass per unit area function  $\rho : S \rightarrow \mathbb{R}$  is given by

$$M = \iint_S \rho \, d\sigma.$$

The *center of mass*  $\bar{\mathbf{r}} = \langle \bar{x}_1, \bar{x}_2, \bar{x}_3 \rangle$  of the thin shell above is

$$\bar{x}_i = \frac{1}{M} \iint_S x_i \rho \, d\sigma, \quad i = 1, 2, 3.$$

### Remark:

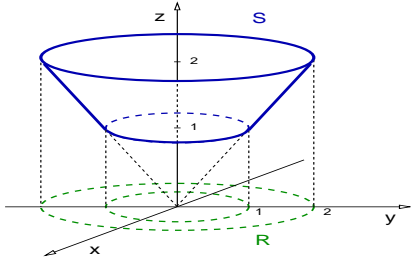
- ▶ The *centroid vector* is the particular case of the center of mass vector for an object with constant density.
- ▶ See in the textbook the definitions of moments of inertia  $I_{x_i}$ , with  $i = 1, 2, 3$ , for thin shells.

## Mass and center of mass of thin shells

### Example

Find the centroid of the surface  $S$  given by  $x^2 + y^2 = z^2$  between the planes  $z = 1$  and  $z = 2$ .

**Solution:** The surface  $S$  is a cone section, given in the figure.



We first compute the area,  $M$ , of  $S$ ,

$$M = \iint_S d\sigma = \iint_R \frac{|\nabla f|}{|\nabla f \cdot \mathbf{k}|} dA.$$

Here  $f = x^2 + y^2 - z^2$ , therefore,

$$\nabla f = \langle 2x, 2y, -2z \rangle.$$

Hence  $|\nabla f| = 2\sqrt{x^2 + y^2 + z^2}$ , evaluated on  $S$ . Since  $z^2 = x^2 + y^2$ , we get  $|\nabla f| = 2\sqrt{2}z$ . Also  $\nabla f \cdot \mathbf{k} = -2z$ . So,

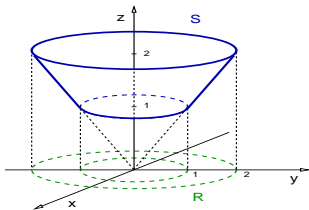
$$\frac{|\nabla f|}{|\nabla f \cdot \mathbf{k}|} = \frac{2\sqrt{2}z}{2z} = \sqrt{2} \quad \Rightarrow \quad M = \iint_R \sqrt{2} dA.$$

## Mass and center of mass of thin shells

### Example

Find the centroid of the surface  $S$  given by  $x^2 + y^2 = z^2$  between the planes  $z = 1$  and  $z = 2$ .

**Solution:** Recall:  $\frac{|\nabla f|}{|\nabla f \cdot \mathbf{k}|} = \sqrt{2}$  and  $M = \iint_R \sqrt{2} dA$ .



We use polar coordinates in  $\{z = 0\}$ ,

$$M = \sqrt{2} \int_0^{2\pi} \int_1^2 r dr d\theta = 2\pi\sqrt{2} \left( \frac{r^2}{2} \Big|_1^2 \right)$$

We conclude  $M = 3\sqrt{2}\pi$ .

By symmetry, the only non-zero component of the centroid is  $\bar{z}$ .

$$\bar{z} = \frac{1}{M} \iint_R z \frac{|\nabla f|}{|\nabla f \cdot \mathbf{k}|} dA = \frac{\sqrt{2}}{3\sqrt{2}\pi} \iint_R \sqrt{x^2 + y^2} dx dy.$$

$$\bar{z} = \frac{1}{3\pi} \int_0^{2\pi} \int_1^2 r^2 dr d\theta = \frac{2\pi}{3\pi} \left( \frac{r^3}{3} \Big|_1^2 \right) = \frac{2}{9} (8 - 1) \quad \Rightarrow \quad \bar{z} = \frac{14}{9}.$$