

Partial derivatives and continuity

Recall: The following result holds for single variable functions.

Theorem

If the function $f : \mathbb{R} \to \mathbb{R}$ is differentiable, then f is continuous.

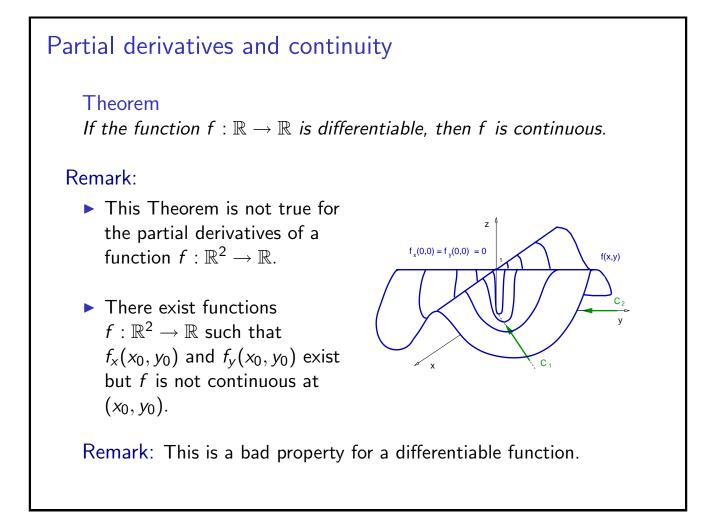
Proof:

$$\lim_{h \to 0} [f(x+h) - f(x)] = \lim_{h \to 0} \left[\frac{f(x+h) - f(x)}{h} \right] h$$

$$\lim_{h\to 0} [f(x+h) - f(x)] = f'(x) \lim_{h\to 0} h = 0.$$

That is, $\lim_{h\to 0} f(x+h) = f(x)$, so f is continuous.

Remark: However, the claim "If $f_x(x, y)$ and $f_y(x, y)$ exist, then f(x, y) is continuous" is false.



Partial derivatives and continuity

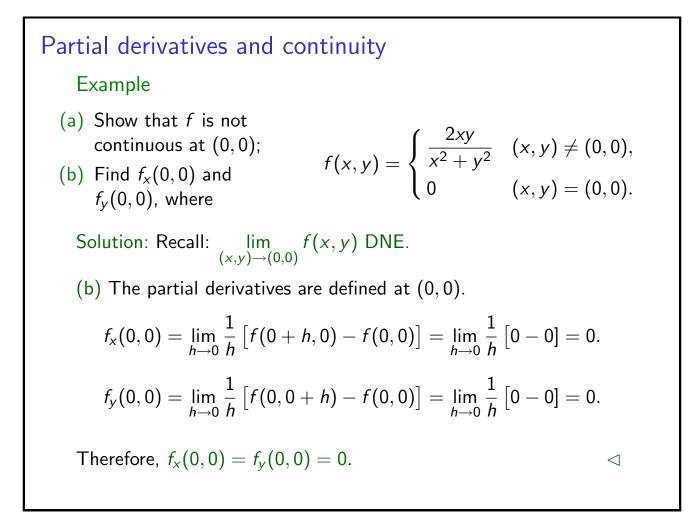
Remark: Here is another discontinuous function at (0,0) having partial derivatives at (0,0).

Example

(a) Show that f is not continuous at (0,0); (b) Find $f_x(0,0)$ and $f_y(0,0)$, where $f(x,y) = \begin{cases} \frac{2xy}{x^2 + y^2} & (x,y) \neq (0,0), \\ 0 & (x,y) = (0,0). \end{cases}$

Solution: (a) Along x = 0, f(0, y) = 0, so $\lim_{y \to 0} f(0, y) = 0$. Along the path x = y, $f(x, x) = \frac{2x^2}{2x^2} = 1$, so $\lim_{x \to 0} f(x, x) = 1$.

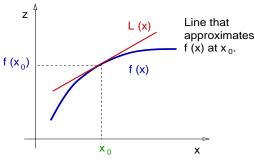
The Two-Path Theorem implies that $\lim_{(x,y)\to(0,0)} f(x,y)$ DNE.



Partial derivatives and differentiability (Sect. 14.3) Partial derivatives and continuity. Differentiable functions $f : D \subset \mathbb{R}^2 \to \mathbb{R}$. Differentiability and continuity. A primer on differential equations.

Differentiable functions $f: D \subset \mathbb{R}^2 \to \mathbb{R}$

Recall: A differentiable function $f : \mathbb{R} \to \mathbb{R}$ at x_0 must be approximated by a line L(x) by $(x_0, f(x_0))$ with slope $f'(x_0)$.



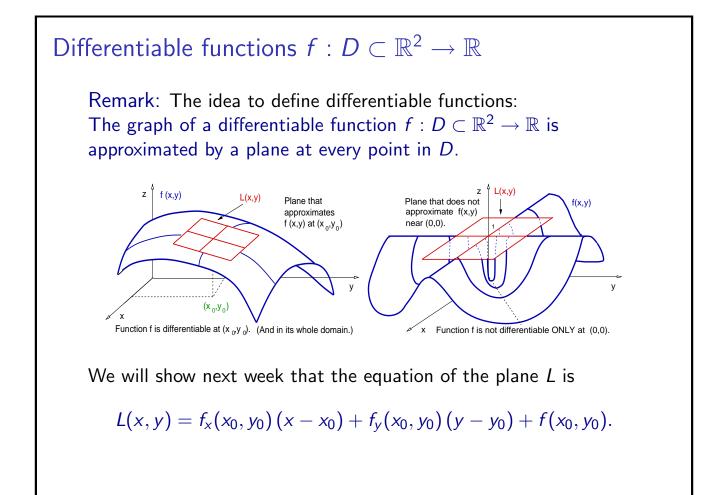
The equation of the tangent line is

 $L(x) = f'(x_0)(x - x_0) + f(x_0).$

The function f is approximated by the line L near x_0 means

$$f(x) = L(x) + \epsilon_1 \left(x - x_0
ight) \quad ext{with} \ \epsilon_1(x) o 0 \ ext{as} \ x o x_0.$$

Remark: The graph of a differentiable function $f : D \subset \mathbb{R} \to \mathbb{R}$ is approximated by a line at every point in D.



Differentiable functions $f: D \subset \mathbb{R}^2 \to \mathbb{R}$

Definition

Given a function $f : D \subset \mathbb{R}^2 \to \mathbb{R}$ and an interior point (x_0, y_0) in D, let L be the linear function

$$L(x, y) = f_x(x_0, y_0) (x - x_0) + f_y(x_0, y_0) (y - y_0) + f(x_0, y_0).$$

The function f is called *differentiable at* (x_0, y_0) iff the function f is approximated by the linear function L near (x_0, y_0) , that is,

$$f(x, y) = L(x, y) + \epsilon_1 (x - x_0) + \epsilon_2 (y - y_0)$$

where the functions ϵ_1 and $\epsilon_2 \rightarrow 0$ as $(x, y) \rightarrow (x_0, y_0)$. The function f is *differentiable* iff f is differentiable at every interior point of D.

Differentiable functions $f: D \subset \mathbb{R}^2 \to \mathbb{R}$

Remark: Recalling the linear function L given above,

$$L(x,y) = f_x(x_0,y_0)(x-x_0) + f_y(x_0,y_0)(y-y_0) + f(x_0,y_0),$$

an equivalent expression for f being differentiable,

$$f(x,y) = L(x,y) + \epsilon_1 (x - x_0) + \epsilon_2 (y - y_0),$$

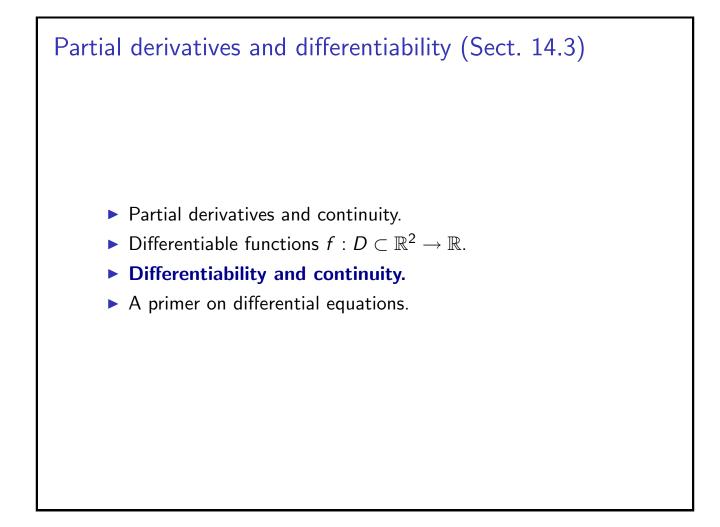
is the following: Denote z = f(x, y) and $z_0 = f(x_0, y_0)$, and introduce the increments

$$\Delta z = (z - z_0), \quad \Delta y = (y - y_0), \quad \Delta x = (x - x_0);$$

then, the equation above is

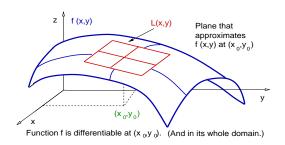
 $\Delta z = f_x(x_0, y_0) \Delta x + f_y(x_0, y_0) \Delta y + \epsilon_1 \Delta x + \epsilon_2 \Delta y.$

(Equation used in the textbook to define a differentiable function.)



Differentiability and continuity

Remark: We will show in Sect. 14.6 that the graph of a differentiable function $f: D \subset \mathbb{R}^2 \to \mathbb{R}$ is approximated by a plane at every point in D.



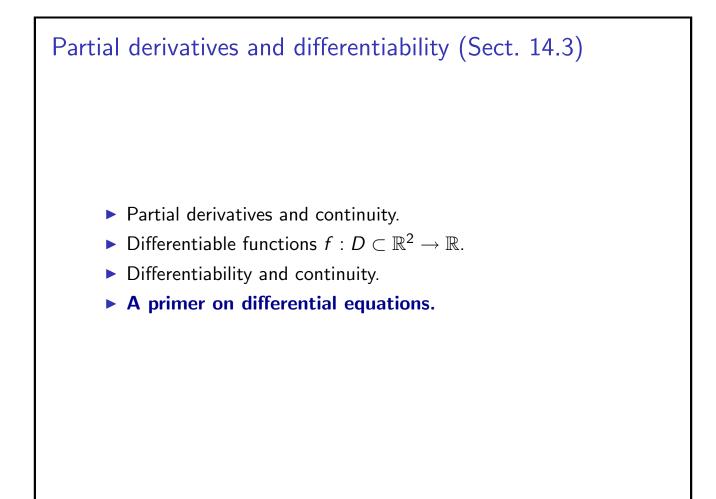
Theorem

If a function $f : D \subset \mathbb{R}^2 \to \mathbb{R}$ is differentiable, then f is continuous.

Remark: A simple sufficient condition on a function $f: D \subset \mathbb{R}^2 \to \mathbb{R}$ guarantees that f is differentiable.

Theorem

If the partial derivatives f_x and f_y of a function $f : D \subset \mathbb{R}^2 \to \mathbb{R}$ are continuous in an open region $R \subset D$, then f is differentiable in R.



A primer on differential equations

Remark: A differential equation is an equation where the unknown is a function and the function together with its derivatives appear in the equation.

Example

Given a constant $k \in \mathbb{R}$, find all solutions $f : \mathbb{R} \to \mathbb{R}$ to the differential equation

$$f'(x) = k f(x).$$

Solution: Multiply by e^{-kx} the equation above f'(x) - kf(x) = 0. The result is $f'(x) e^{-kx} - f(x) k e^{-kx} = 0$.

The left-hand side is a total derivative, $[f(x)e^{-kx}]' = 0$. The solution of the equation above is $f(x)e^{-kx} = c$, with $c \in \mathbb{R}$.

Therefore, $f(x) = c e^{kx}$.

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A primer on differential equations Remark: Often in physical applications appear three differential equations for functions $f : D \subset \mathbb{R}^n \to \mathbb{R}$, with n = 2, 3, 4. • The Laplace equation: (Gravitation, electrostatics.) $f_{xx} + f_{yy} + f_{zz} = 0$. • The Heat equation: (Heat propagation, diffusion.) $f_t = k (f_{xx} + f_{yy} + f_{zz})$.

► The Wave equation: (Light, sound, gravitation.)

$$f_{tt} = v \left(f_{xx} + f_{yy} + f_{zz} \right).$$

A primer on differential equations

Example

Verify that the function $T(t, x) = e^{-4t} \sin(2x)$ satisfies the one-space dimensional heat equation $T_t = T_{xx}$.

Solution: We first compute T_t ,

$$T_t = -4e^{-t}\sin(2x).$$

Now compute T_{xx} ,

$$T_x = 2e^{-t}\cos(2x) \quad \Rightarrow \quad T_{xx} = -4e^{-t}\sin(2x)$$

We conclude that $T_t = T_{xx}$.

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A primer on differential equations

Example

Verify that $f(x, y, z) = \frac{1}{\sqrt{x^2 + y^2 + z^2}}$ satisfies the Laplace equation : $f_{xx} + f_{yy} + f_{zz} = 0$. Solution: Recall: $f_x = -\frac{x}{(x^2 + y^2 + z^2)^{3/2}}$. Then, $f_{xx} = -\frac{1}{(x^2 + y^2 + z^2)^{3/2}} + \frac{3}{2} \frac{2x^2}{(x^2 + y^2 + z^2)^{5/2}}$. Denote $r = \sqrt{x^2 + y^2 + z^2}$, then $f_{xx} = -\frac{1}{r^3} + \frac{3x^2}{r^5}$. Analogously, $f_{yy} = -\frac{1}{r^3} + \frac{3y^2}{r^5}$, and $f_{zz} = -\frac{1}{r^3} + \frac{3z^2}{r^5}$. Then, $f_{xx} + f_{yy} + f_{zz} = -\frac{3}{r^3} + \frac{3(x^2 + y^2 + z^2)}{r^5} = -\frac{3}{r^3} + \frac{3r^2}{r^5} = 0$. We conclude that $f_{xx} + f_{yy} + f_{zz} = 0$.

A primer on differential equations

Example

Verify that the function $f(t,x) = (vt - x)^3$, with $v \in \mathbb{R}$, satisfies the one-space dimensional wave equation $f_{tt} = v^2 f_{xx}$.

Solution: We first compute f_{tt} ,

$$f_t = 3v(vt - x)^2 \quad \Rightarrow \quad f_{tt} = 6v^2(vt - x).$$

Now compute f_{XX} ,

$$f_x = -3(vt-x)^2 \quad \Rightarrow \quad f_{xx} = 6(vt-x).$$

Since $v^2 f_{xx} = 6v^2 (vt - x)$, then $f_{tt} = v^2 f_{xx}$.

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A primer on differential equations

Example

Given any $v \in \mathbb{R}$ and any twice continuously differentiable function $u : \mathbb{R} \to \mathbb{R}$, verify that f(t, x) = u(vt - x), satisfies the one-space dimensional wave equation $f_{tt} = v^2 f_{xx}$.

Solution: We first compute f_{tt} ,

$$f_t = v u'(vt - x) \quad \Rightarrow \quad f_{tt} = v^2 u''(vt - x).$$

Now compute f_{xx} ,

$$f_x = -u'(vt-x)^2 \quad \Rightarrow \quad f_{xx} = u''(vt-x).$$

Since $v^2 f_{xx} = v^2 u'' (vt - x)$, then $f_{tt} = v^2 f_{xx}$.

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