

1. Let

$$A = \begin{pmatrix} 1 & -3 & -5 \\ 1 & 1 & -2 \\ 1 & -3 & 1 \\ 1 & 1 & 4 \end{pmatrix}, \quad \vec{b} = \begin{pmatrix} -6 \\ 1 \\ 1 \\ 6 \end{pmatrix}.$$

If the Gram-Schmidt process is applied to determine an orthonormal basis for $C(A)$ and a QR factorization of A , then, after the first two orthonormal vectors \vec{q}_1 and \vec{q}_2 are computed, we have

$$Q = \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix}, \quad R = \begin{pmatrix} 2 & -2 & -1 \\ 0 & 4 & 3 \\ 0 & 0 & 6 \end{pmatrix}.$$

(a) Finish the process. Determine \vec{q}_3 and fill in the third columns of Q and R . [6 points]

$$\text{Let } \vec{a}_3 = \begin{pmatrix} -5 \\ -2 \\ 1 \\ 4 \end{pmatrix}, \quad \vec{q}_1 = \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \text{ and } \vec{q}_2 = \begin{pmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ -\frac{1}{2} \\ \frac{1}{2} \end{pmatrix}$$

$$\text{Then } \vec{q}_3 = \frac{\vec{a}_3 - P_{\text{span}\{\vec{q}_1, \vec{q}_2\}} \vec{a}_3}{\|\vec{a}_3 - P_{\text{span}\{\vec{q}_1, \vec{q}_2\}} \vec{a}_3\|} \quad \text{where } P_{\text{span}\{\vec{q}_1, \vec{q}_2\}} \vec{a}_3 = \vec{p}_2 = r_{13} \vec{q}_1 + r_{23} \vec{q}_2$$

$$r_{13} = \vec{a}_3 \cdot \vec{q}_1 = \vec{a}_3^T \vec{q}_1 = -\frac{5}{2} - \frac{2}{2} + \frac{1}{2} + \frac{4}{2} = -1$$

$$r_{23} = \vec{a}_3 \cdot \vec{q}_2 = \vec{a}_3^T \vec{q}_2 = \frac{5}{2} - \frac{2}{2} - \frac{1}{2} + \frac{4}{2} = 3$$

$$P_{\text{span}\{\vec{q}_1, \vec{q}_2\}} \vec{a}_3 = (-1) \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} + 3 \begin{pmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ -\frac{1}{2} \\ \frac{1}{2} \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \\ -2 \\ 1 \end{pmatrix}$$

$$\vec{a}_3 - P_{\text{span}\{\vec{q}_1, \vec{q}_2\}} \vec{a}_3 = \begin{pmatrix} -5 \\ -2 \\ 1 \\ 4 \end{pmatrix} - \begin{pmatrix} -2 \\ 1 \\ -2 \\ 1 \end{pmatrix} = \begin{pmatrix} -3 \\ -3 \\ 3 \\ 3 \end{pmatrix}$$

$$r_{33} = \left\| \vec{a}_3 - P_{\text{span}\{\vec{q}_1, \vec{q}_2\}} \vec{a}_3 \right\| = \sqrt{(-3)^2 + (-3)^2 + 3^2 + 3^2} = \sqrt{4(9)} = 6$$

$$\text{Hence, } \vec{q}_3 = \frac{\vec{a}_3 - P_{\text{span}\{\vec{q}_1, \vec{q}_2\}} \vec{a}_3}{r_{33}} = \begin{pmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \end{pmatrix}_1$$

(b) Use the QR factorization to find the least squares solution of $A\vec{x} = \vec{b}$. [4 points]

Least-squares solution is $A^T A \vec{x} = A^T \vec{b}$

Using $A = QR$, we get

$$(QR)^T (QR) \vec{x} = (QR)^T \vec{b}$$

or, $R^T (Q^T Q) R \vec{x} = R^T Q^T \vec{b}$

or, $R^T R \vec{x} = R^T Q^T \vec{b}$ (since Q is orthogonal)

or, $R \vec{x} = Q^T \vec{b}$

$$\begin{bmatrix} 2 & -2 & -1 \\ 0 & 4 & 3 \\ 0 & 0 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} -6 \\ 1 \\ 1 \\ 6 \end{bmatrix}$$

$$\begin{bmatrix} 2 & -2 & -1 \\ 0 & 4 & 3 \\ 0 & 0 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 6 \\ 6 \end{bmatrix}$$

Doing back substitution, $x_3 = 1$

$$4x_2 = 6 - 3x_3$$

$$\Rightarrow 4x_2 = 6 - 3$$

$$\Rightarrow x_2 = \frac{3}{4}$$

and $2x_1 - 2x_2 - x_3 = 1$

$$\Rightarrow 2x_1 = 1 + 2\left(\frac{3}{4}\right) + 1$$

$$\Rightarrow 2x_1 = \frac{7}{2}$$

$$\Rightarrow x_1 = \frac{7}{4}$$

Least Squares
Solⁿ.

$$\vec{x} = \begin{bmatrix} \frac{7}{4} \\ \frac{3}{4} \\ 1 \end{bmatrix}$$