

LAST TIME

- * Orthogonal subspaces
- * Orthogonal complements
- * Orthogonality of the four subspaces

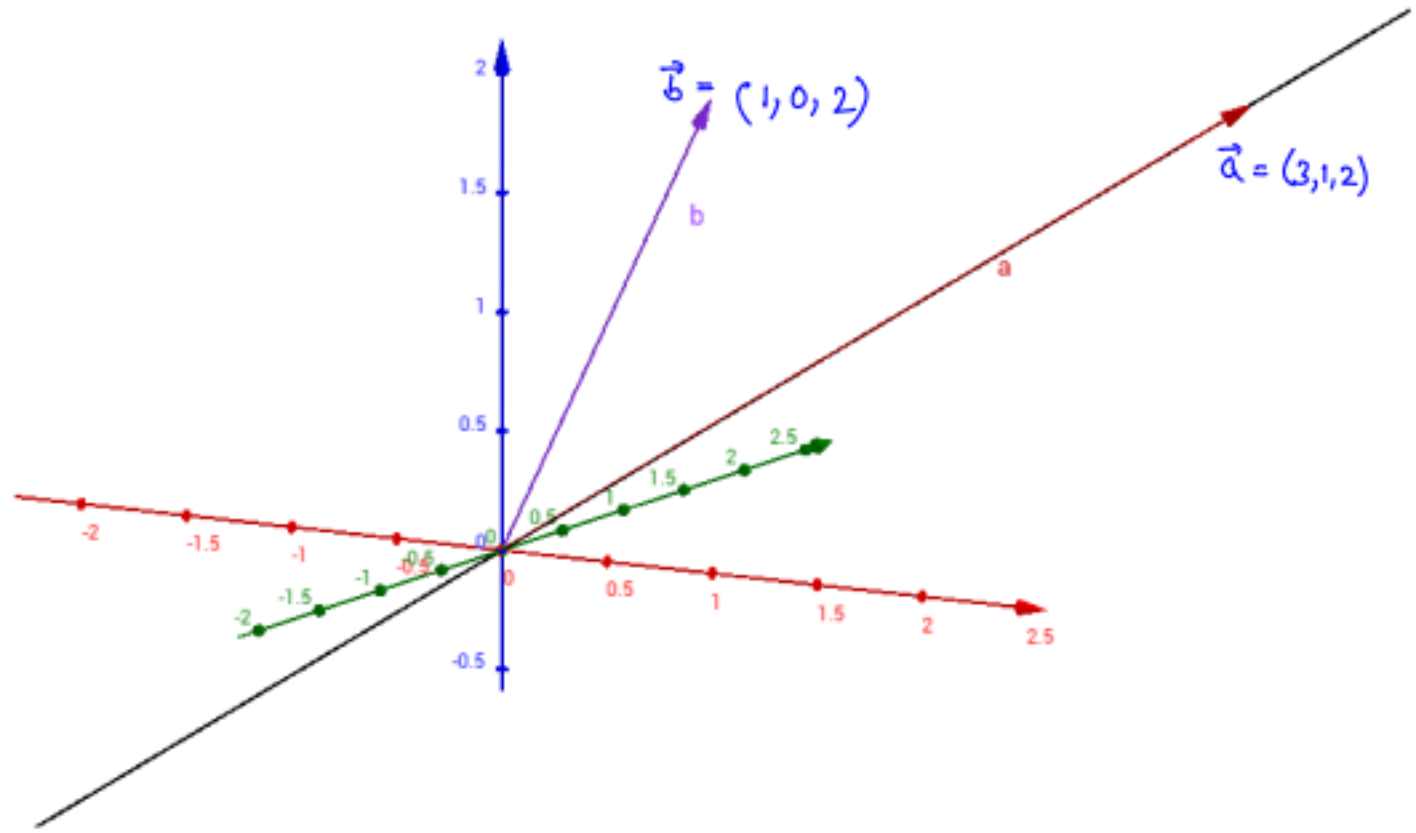
TODAY

- * Projections
- * Normal equations
- * Projection matrices

PROJECTION ONTO A LINE

AN EXAMPLE.....

Find the projection of $\vec{b} = (1, 0, 2)$ onto $\vec{a} = (3, 1, 2)$



FINDING THE PROJECTION OF \vec{b} ONTO \vec{a}

INGREDIENTS

- line going through $\vec{a} = (a_1, a_2, \dots, a_m)$
- given point $\vec{b} = (b_1, b_2, \dots, b_m)$

Note: projection \vec{p} is the part of \vec{b} along the line through \vec{a}

KEY IDEA

The line from \vec{b} to \vec{p} is perpendicular to the vector \vec{a}

$$\Rightarrow \vec{a} \cdot \vec{e} = 0$$

$$\Rightarrow \vec{a} \cdot (\vec{b} - \hat{\lambda} \vec{a}) = 0$$

$$\Rightarrow \vec{a} \cdot \vec{b} - \hat{\lambda} \vec{a} \cdot \vec{a} = 0$$

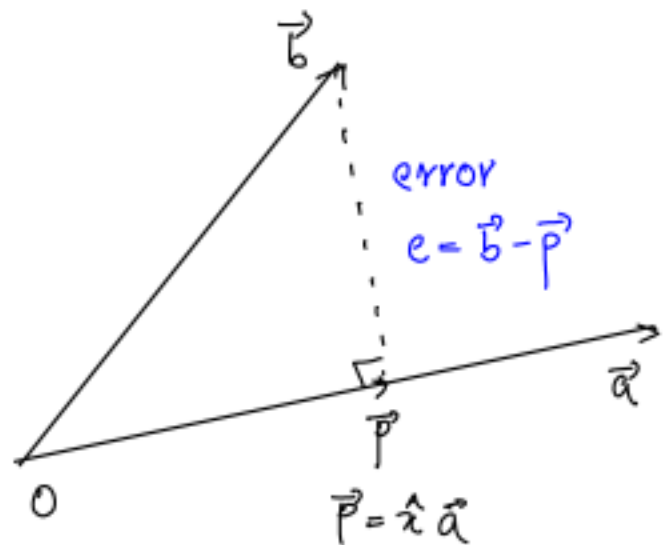
$$\Rightarrow \hat{\lambda} = \frac{\vec{a} \cdot \vec{b}}{\vec{a} \cdot \vec{a}} = \frac{\vec{a}^T \vec{b}}{\vec{a}^T \vec{a}}$$

NOTATION

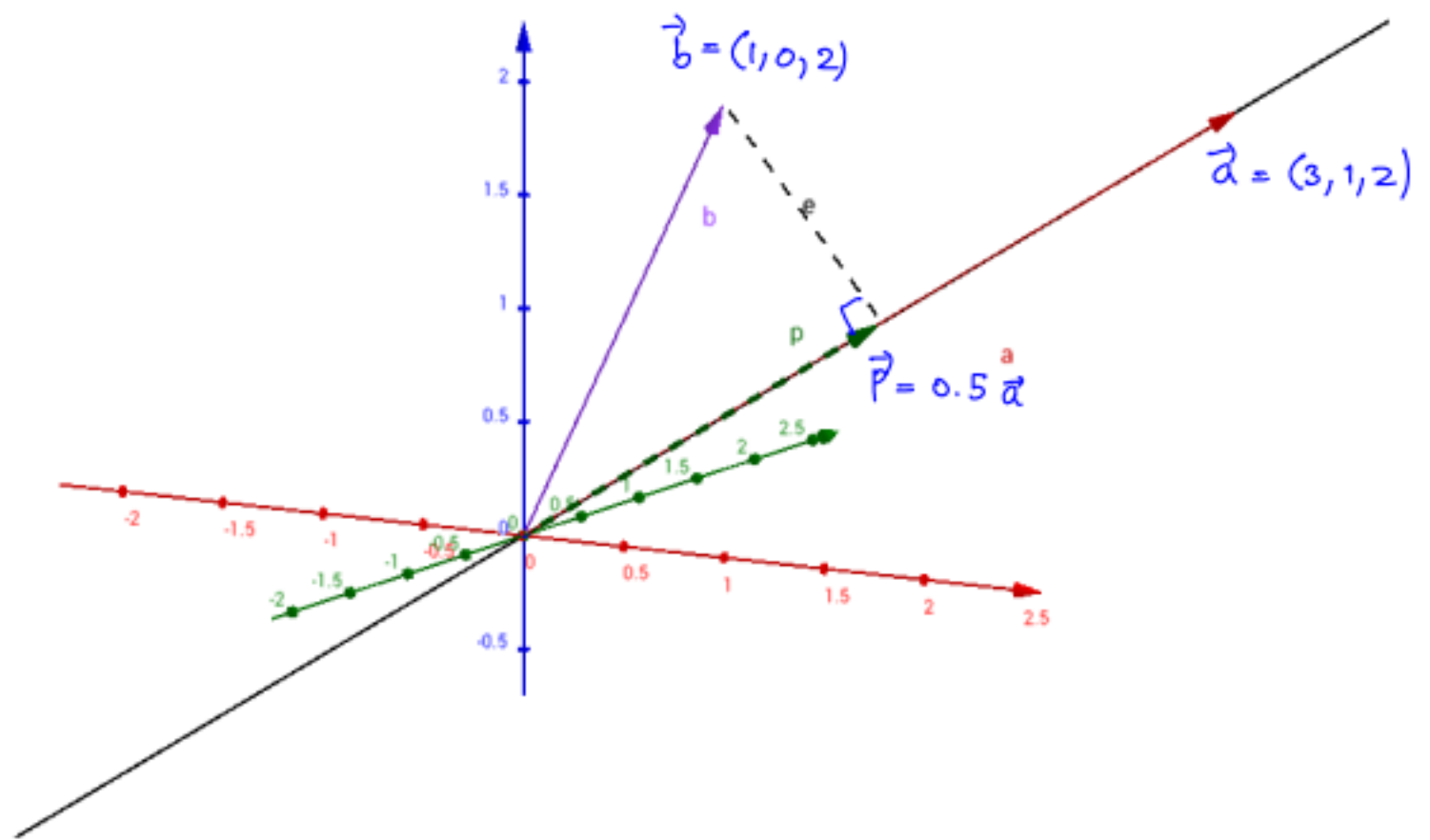
* denote the projection by \vec{p}

* will denote $\vec{p} = \hat{\lambda} \vec{a}$

* projection matrix - P
we have $\vec{p} = P\vec{b}$



FINDING THE PROJECTION OF \vec{b} ONTO \vec{a}



PROJECTION OF \vec{b} ONTO THE LINE THROUGH \vec{a}

$$\hat{\alpha} = \frac{\vec{a} \cdot \vec{b}}{\vec{a} \cdot \vec{a}} = \frac{\vec{a}^T \vec{b}}{\vec{a}^T \vec{a}}$$

Projection of \vec{b} onto the line through \vec{a} is the vector $\vec{p} = \hat{\alpha} \vec{a} = \left(\frac{\vec{a}^T \vec{b}}{\vec{a}^T \vec{a}} \right) \vec{a}$

Projection Matrix

$$P = \frac{\vec{a} \vec{a}^T}{\vec{a}^T \vec{a}}$$

- Note:
- P is rank-1 with $P^2 = P$
 - we are projecting onto a one-dimensional subspace (line)
 - this line is the column space of P

Special cases

① $\vec{b} = \vec{a}$ ($\hat{\alpha} = 1$, $\vec{p} = \vec{a}$)

② \vec{b} is perpendicular to \vec{a} ($\hat{\alpha} = 0$, $\vec{p} = \vec{0}$)

PROJECTION ONTO A SUBSPACE

PROBLEM STATEMENT Let $\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n \in \mathbb{R}^m$ be linearly independent.
Find the combination $\vec{p} = \hat{x}_1 \vec{a}_1 + \hat{x}_2 \vec{a}_2 + \dots + \hat{x}_n \vec{a}_n$
closest to a given vector \vec{b} .

* Construct matrix A whose columns are $\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n$

* We are looking for the particular combination of the columns $\vec{p} = A\hat{x}$
that is closest to \vec{b} .

KEY IDEA

- Our subspace is the column space of A
- Like the projection onto a line, we want the error vector $\vec{b} - A\hat{x}$ to be perpendicular - to all vectors in the column space

$$\Rightarrow \vec{b} - A\hat{x} \text{ is in the left nullspace, or } \underline{A^T(\vec{b} - A\hat{x}) = \vec{0}}$$

PROJECTION ONTO A SUBSPACE

Note: $A \in \mathbb{R}^{m \times n}$
 $\vec{p} = \hat{\lambda}_1 \vec{a}_1 + \dots + \hat{\lambda}_n \vec{a}_n = A \hat{\lambda}$

To find $\hat{\lambda}$ (vector, $n \times 1$)

Solve $A^T (\vec{b} - A \hat{\lambda}) = 0$ or $A^T A \hat{\lambda} = A^T \vec{b}$

$A^T A \in \mathbb{R}^{n \times n}$, invertible if \vec{a}_i are independent

$$\hat{\lambda} = (A^T A)^{-1} A^T \vec{b}$$

normal equations

Projection of \vec{b} onto the subspace is \vec{p} (vector, $m \times 1$)

$$\vec{p} = A \hat{\lambda} = A (A^T A)^{-1} A^T \vec{b}$$

Projection matrix, $P \in \mathbb{R}^{m \times m}$

$$P = A (A^T A)^{-1} A^T$$

Example Let $A = \begin{bmatrix} 1 & 1 \\ 2 & 0 \\ 1 & 2 \end{bmatrix}$ and $\vec{b} = \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}$. Find $\hat{\vec{x}}$, \vec{p} and \vec{e} .

- Start by computing $A^T A$

$$A^T A = \begin{bmatrix} 1 & 2 & 1 \\ 1 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 2 & 0 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 6 & 3 \\ 3 & 5 \end{bmatrix}$$

- Now compute $A^T \vec{b}$ $A^T \vec{b} = \begin{bmatrix} 1 & 2 & 1 \\ 1 & 0 & 2 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$

- Solve normal equation $(A^T A) \hat{\vec{x}} = A^T \vec{b}$

$$\begin{bmatrix} 6 & 3 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

elimination gives $\begin{bmatrix} 6 & 3 & | & 2 \\ 3 & 5 & | & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 6 & 3 & | & 2 \\ 0 & 7/2 & | & 0 \end{bmatrix} \rightarrow \hat{x}_2 = 0, \hat{x}_1 = 1/3$

$$\hat{\vec{x}} = (0, 1/3)$$

- $\vec{p} = A \hat{\vec{x}} = \frac{1}{3} \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} + 0 \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} = \begin{pmatrix} 1/3 \\ 2/3 \\ 1/3 \end{pmatrix}$

Note: $\vec{e} = \vec{b} - \vec{p} = \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 1/3 \\ 2/3 \\ 1/3 \end{pmatrix} = \begin{pmatrix} -4/3 \\ 1/3 \\ 2/3 \end{pmatrix}$

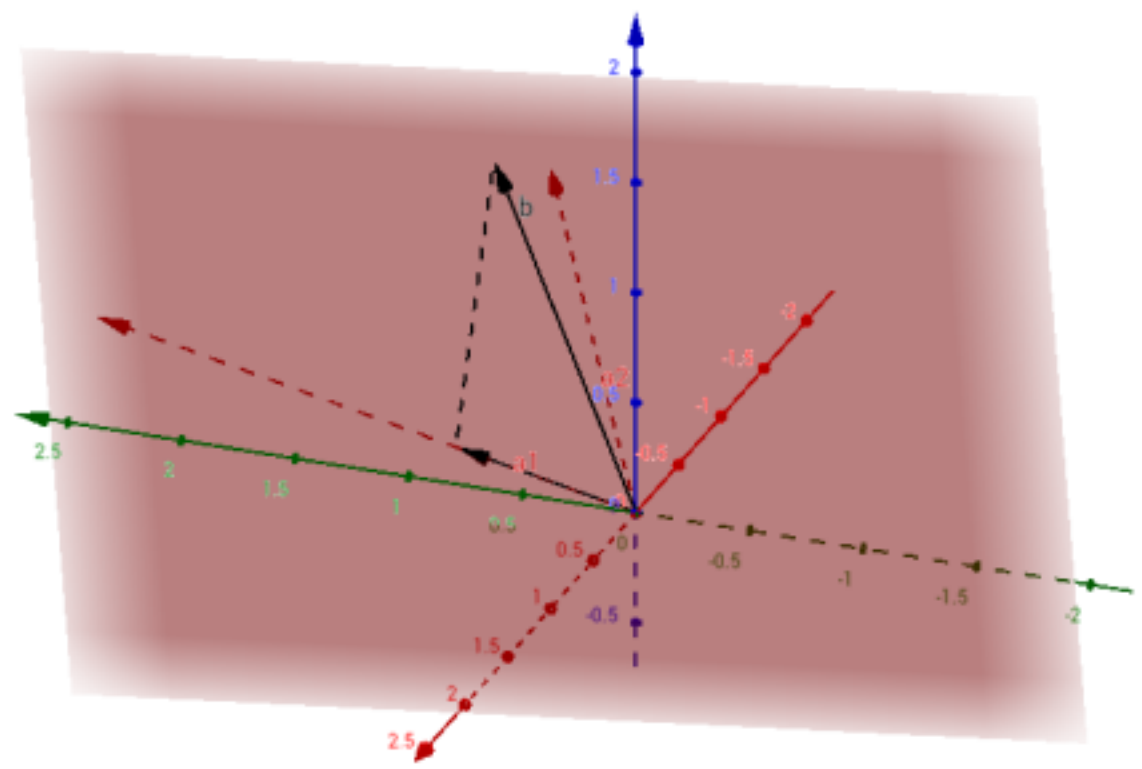
\vec{e} is perpendicular to both columns of A

Example Let $A = \begin{bmatrix} 1 & 1 \\ 2 & 0 \\ 1 & 2 \end{bmatrix}$ and $\vec{b} = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$. Find \hat{x} , $\hat{\beta}$ and P .

$$A^T A = \begin{bmatrix} 6 & 3 \\ 3 & 5 \end{bmatrix} \quad (A^T A)^{-1} = \frac{1}{21} \begin{bmatrix} 5 & -3 \\ -3 & 6 \end{bmatrix}$$

$$\begin{aligned} P &= A (A^T A)^{-1} A^T = \begin{bmatrix} 1 & 1 \\ 2 & 0 \\ 1 & 2 \end{bmatrix} \left(\frac{1}{21} \begin{bmatrix} 5 & -3 \\ -3 & 6 \end{bmatrix} \right) \begin{pmatrix} 1 & 2 & 1 \\ 1 & 0 & 2 \end{pmatrix} \\ &= \frac{1}{21} \begin{bmatrix} 1 & 1 \\ 2 & 0 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 2 & 10 & -1 \\ 3 & -6 & 9 \end{bmatrix} \\ &= \frac{1}{21} \begin{bmatrix} 5 & 4 & 8 \\ 4 & 20 & -2 \\ 8 & -2 & 17 \end{bmatrix} \end{aligned}$$

PROJECTION ONTO A SUBSPACE



PROPERTIES OF P

Theorem $A^T A$ is invertible if $A \in \mathbb{R}^{m \times n}$ has rank n

or

$A^T A$ is invertible if A has linearly independent columns.

$$\begin{aligned} * P^2 &= P P = (A (A^T A)^{-1} A^T) (A (A^T A)^{-1} A^T) \\ &= A (A^T A)^{-1} \underbrace{(A^T A)}_{= I} (A^T A)^{-1} A^T \\ &= A (A^T A)^{-1} A^T \\ &= P \end{aligned}$$

$$\begin{aligned} * P^T &= (A (A^T A)^{-1} A^T)^T = A ((A^T A)^{-1})^T A^T = A ((A^T A)^T)^{-1} A^T \\ &= A (A^T A)^{-1} A^T \\ &= P \end{aligned}$$

$\Rightarrow P$ is symmetric