

Eigenvalues and Eigenvectors

① Let $A = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 0 & 1 \\ 1 & 0 & 2 \end{pmatrix}$. Find the eigenvalues of A . Calculate the eigenvectors of A for the two largest eigenvalues.

② Factor the matrix A into a product XDX^{-1} where D is diagonal $A = \begin{bmatrix} 2 & -3 \\ 2 & -5 \end{bmatrix}$

③ Let $A = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 3 & 1 & 0 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & 2 & 5 \end{pmatrix}$.

- (i) How many negative eigenvalues does A have?
- (ii) Calculate the product of the eigenvalues of A .
- (iii) Calculate the sum of the eigenvalues of A .
- (iv) Suppose you are given 3 eigenvectors of A . Explain how you find the fourth eigenvector without knowing any of A 's eigenvalues.

④ Compute $v_{20} = A^{20} u_0$ starting with $A = \begin{bmatrix} 0.7 & 0.5 \\ 0.3 & 0.5 \end{bmatrix}$ and $u_0 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$.

⑤ If you transpose $S^{-1} A S = \Lambda$, we get the eigenvalues of $A^T =$ _____
the eigenvectors of $A^T =$ _____

① Let $A = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 0 & 1 \\ 1 & 0 & 2 \end{pmatrix}$. Find the eigenvalues of A . Calculate the eigenvectors of A for the two largest eigenvalues

Eigenvalues $|A - \lambda I| = 0 \Rightarrow \begin{vmatrix} 1-\lambda & 0 & 0 \\ -1 & -\lambda & 1 \\ 1 & 0 & 2-\lambda \end{vmatrix} = 0$

$$\Rightarrow (1-\lambda)(-\lambda)(2-\lambda) = 0$$

$$\Rightarrow \underline{\lambda = 0 \text{ or } \lambda = 1 \text{ or } \lambda = 2}$$

Eigenvectors

$$\boxed{\lambda = 1}$$

Solve $(A - \lambda I)\vec{x} = \vec{0}$

$$\begin{pmatrix} 0 & 0 & 0 \\ -1 & -1 & 1 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \left. \begin{array}{l} -x_1 - x_2 + x_3 = 0 \\ x_1 + x_3 = 0 \end{array} \right\}$$

choosing $x_3 = 1$, we get
(free var)

$$\boxed{\vec{x} = \begin{pmatrix} -1 \\ 2 \\ 1 \end{pmatrix}}$$

$$\lambda = 2$$

Solve $(A - 2I)\vec{y} = \vec{0}$

$$\begin{pmatrix} -1 & 0 & 0 \\ -1 & -2 & 1 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \left. \begin{array}{l} -y_1 = 0 \\ -y_1 - 2y_2 + y_3 = 0 \\ y_1 = 0 \end{array} \right\}$$

$\Rightarrow y_1 = 0$; choose $y_3 = 1$, we get
(free var)

$$\boxed{\vec{y} = \begin{pmatrix} 0 \\ \frac{1}{2} \\ 1 \end{pmatrix}}$$

(2) Factor the matrix A into a product XDX^{-1} where D is diagonal $A = \begin{bmatrix} 2 & -3 \\ 2 & -5 \end{bmatrix}$

Eigenvalues $|A - \lambda I| = 0 \Rightarrow \begin{vmatrix} 2-\lambda & -3 \\ 2 & -5-\lambda \end{vmatrix} = 0 \Rightarrow (2-\lambda)(-5-\lambda) + 6 = 0$
 $\Rightarrow \lambda^2 + 3\lambda - 4 = 0$
 $\Rightarrow (\lambda + 4)(\lambda - 1) = 0$
 $\Rightarrow \lambda = -4 \text{ or } \lambda = 1$

Eigenvectors $\lambda = -4$ $(A + 4I)\vec{x} = \vec{0}$ $\begin{pmatrix} 6 & -3 \\ 2 & -1 \end{pmatrix} \vec{x} = \vec{0} \Rightarrow \vec{x} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$ is an eigenvector

$\lambda = 1$ $(A - \lambda I)\vec{y} = \vec{0}$ $\begin{pmatrix} 1 & -3 \\ 2 & -6 \end{pmatrix} \vec{y} = \vec{0} \Rightarrow \vec{y} = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$ is an eigenvector

let $X = \begin{pmatrix} 1 & 3 \\ 2 & 1 \end{pmatrix}$ then $X^{-1} = \frac{1}{-5} \begin{pmatrix} 1 & 3 \\ -2 & 1 \end{pmatrix} = \begin{pmatrix} -\frac{1}{5} & \frac{3}{5} \\ \frac{2}{5} & -\frac{1}{5} \end{pmatrix}$

$D = \begin{pmatrix} -4 & 0 \\ 0 & 1 \end{pmatrix}$. Then $A = \begin{pmatrix} 1 & 3 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} -4 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} -\frac{1}{5} & \frac{3}{5} \\ \frac{2}{5} & -\frac{1}{5} \end{pmatrix}$

We can verify that $A = XDX^{-1}$ and $D = X^{-1}AX$.

- (3) Let $A = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 3 & 1 & 0 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & 2 & 5 \end{pmatrix}$.
- How many negative eigenvalues does A have?
 - Calculate the product of the eigenvalues of A .
 - Calculate the sum of the eigenvalues of A .
 - Suppose you are given 3 eigenvectors of A . Explain how you find the fourth eigenvector without knowing any of A 's eigenvalues.

Note that A is symmetric. We use elimination to reduce to upper triangular form. Then
 # negative eigenvalues = # negative pivots

$$\begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 3 & 1 & 0 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & 2 & 5 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & 2 & 5 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & \frac{1}{2} & 2 \\ 0 & 0 & 2 & 5 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & \frac{1}{2} & 2 \\ 0 & 0 & 0 & -3 \end{pmatrix}$$

- 1 negative pivot \Rightarrow 1 negative eigenvalue.
- Product of eigenvalues = $\prod_{i=1}^4 \lambda_i = |A| =$ product of pivots in triangular form = -3
- Sum of eigenvalues = $\sum_{i=1}^4 \lambda_i = \text{trace}(A) = 10$
- Since A is symmetric, its eigenvectors are orthogonal. The fourth e-vector is the vector perpendicular to the given three e-vectors.

④ Compute $u_{20} = A^{20} u_0$ starting with $A = \begin{bmatrix} 0.7 & 0.5 \\ 0.3 & 0.5 \end{bmatrix}$ and $u_0 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$.

Use same procedure as ③ to find e-values and e-vectors (Note: A is a Markov matrix)
 $\Rightarrow \lambda_1 = 1$

We get e-values $\lambda_1 = 1 \quad \lambda_2 = 0.2$

e-vectors $\vec{x}_1 = \begin{pmatrix} 5 \\ 3 \end{pmatrix} \quad \vec{x}_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$

Distinct e-values \Rightarrow
 (diagonalization)

$$A = \underbrace{\begin{pmatrix} 5 & -1 \\ 3 & 1 \end{pmatrix}}_X \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 0.2 \end{pmatrix}}_D \underbrace{\begin{pmatrix} 1/8 & 1/8 \\ -3/8 & 5/8 \end{pmatrix}}_{X^{-1}}$$

$$\begin{aligned} \Rightarrow u_{20} = A^{20} u_0 &= \frac{1}{8} \begin{pmatrix} 5 & -1 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} 1^{20} & 0 \\ 0 & 0.2^{20} \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -3 & 5 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ &= \frac{1}{8} \begin{pmatrix} 5 & -1 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0.2^{20} \end{pmatrix} \begin{pmatrix} 1 \\ -3 \end{pmatrix} \\ &= \frac{1}{8} \begin{pmatrix} 5 & -1 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ -3(0.2^{20}) \end{pmatrix} \end{aligned}$$

$$\boxed{u_{20} = \frac{1}{8} \begin{pmatrix} 5 + 3(0.2^{20}) \\ 3 - 3(0.2^{20}) \end{pmatrix}} \quad \text{note: } u_{20} \approx \begin{pmatrix} 5/8 \\ 3/8 \end{pmatrix}$$

⑤ If you transpose $\vec{S}^T A S = \Lambda$, we get the eigenvalues of $A^T =$ same as A
 the eigenvectors of $A^T =$ are columns of $(S^T)^{-1}$

Note: $(\vec{S}^T A S)^T = \Lambda^T = \Lambda \Rightarrow S^T A^T (\vec{S}^T)^T = \Lambda$
 $\Rightarrow A^T = (\vec{S}^T)^{-1} \Lambda S^T$

QR, Least-Squares, Projections

- ① Given $A = \begin{pmatrix} 2 & -3 & -5 \\ 2 & 1 & -2 \\ 2 & -3 & 1 \\ 2 & 1 & 4 \end{pmatrix}$, (i) apply Gram-Schmidt to determine an orthonormal basis for $C(A)$ and a QR factorization of A
(ii) Use the QR factorization to determine the least-squares solution of $A\vec{x} = \vec{b}$ where $\vec{b} = \begin{pmatrix} -3 \\ 1 \\ 0 \\ 2 \end{pmatrix}$

- ② Find the curve $y = a + 2^x b$ which gives the best least-squares fit to the points $(x, y) = (0, 6), (1, 4), (2, 0)$

- ③ Let $\vec{x} = \begin{pmatrix} 1 \\ 1 \\ 2 \\ 2 \end{pmatrix}$ and $\vec{y} = \begin{pmatrix} -2 \\ 1 \\ 2 \\ 0 \end{pmatrix}$ (i) Find the projection \vec{p} of \vec{x} onto \vec{y} .
(ii) Verify that $\vec{x} - \vec{p}$ is orthogonal to \vec{y} .

- ④ Let $A = \begin{pmatrix} 2 & 1 \\ 1 & 1 \\ 2 & 1 \end{pmatrix}$ and $\vec{b} = \begin{pmatrix} 12 \\ 6 \\ 18 \end{pmatrix}$. Find the projection of \vec{b} onto $C(A)$

- ① Given $A = \begin{pmatrix} 2 & -3 & -5 \\ 2 & 1 & -2 \\ 2 & -3 & 1 \\ 2 & 1 & 4 \end{pmatrix}$ (i) apply Gram-Schmidt to determine an orthonormal basis for $C(A)$ and a QR factorization of A
 (ii) Use the QR factorization to determine the least-squares solution of $A\vec{x} = \vec{b}$ where $\vec{b} = \begin{pmatrix} -3 \\ 1 \\ 0 \\ 2 \end{pmatrix}$

GRAM-SCHMIDT

STEP 1 $r_{11} = \|\vec{a}_1\| = \sqrt{2^2 + 2^2 + 2^2 + 2^2} = 4$
 $\vec{q}_1 = \frac{\vec{a}_1}{\|\vec{a}_1\|} = \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \end{pmatrix}$

STEP 3 $r_{13} = (\vec{a}_3 \cdot \vec{q}_1) = (-5, -2, 1, 4) \cdot (\frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}) = -1$
 $r_{23} = (\vec{a}_3 \cdot \vec{q}_2) = (-5, -2, 1, 4) \cdot (-\frac{1}{2}, \frac{1}{2}, -\frac{1}{2}, \frac{1}{2}) = 3$

Let $\vec{v}_3 = \vec{a}_3 - (\vec{a}_3 \cdot \vec{q}_1) \vec{q}_1 - (\vec{a}_3 \cdot \vec{q}_2) \vec{q}_2$
 $= \begin{pmatrix} -5 \\ -2 \\ 1 \\ 4 \end{pmatrix} - (-1) \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} - 3 \begin{pmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ -\frac{1}{2} \\ \frac{1}{2} \end{pmatrix} = \begin{pmatrix} -3 \\ -3 \\ 3 \\ 3 \end{pmatrix}$

$r_{33} = \|\vec{v}_3\| = \sqrt{(-3)^2 + (-3)^2 + 3^2 + 3^2} = 6$

$\vec{q}_3 = \frac{\vec{v}_3}{\|\vec{v}_3\|} = \begin{pmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \end{pmatrix}$

STEP 2 $r_{12} = (\vec{a}_2 \cdot \vec{q}_1) = (-3, 1, -3, 1) \cdot (\frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}) = -2$

Let $\vec{v}_2 = \vec{a}_2 - (\vec{a}_2 \cdot \vec{q}_1) \vec{q}_1$
 $= \begin{pmatrix} -3 \\ 1 \\ -3 \\ 1 \end{pmatrix} - (-2) \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} = \begin{pmatrix} -2 \\ 2 \\ -2 \\ 2 \end{pmatrix}$

$r_{22} = \|\vec{v}_2\| = 4$

$\vec{q}_2 = \frac{\vec{v}_2}{\|\vec{v}_2\|} = \begin{pmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ -\frac{1}{2} \\ \frac{1}{2} \end{pmatrix}$

QR Decomposition

$Q = \frac{1}{2} \begin{bmatrix} 1 & -1 & -1 \\ 1 & 1 & -1 \\ 1 & -1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$ $R = \begin{bmatrix} 4 & -2 & -1 \\ 0 & 4 & 3 \\ 0 & 0 & 6 \end{bmatrix}$
 $\vec{q}_1 \quad \vec{q}_2 \quad \vec{q}_3$

Least-Squares Solution

$$A^T A \vec{x} = A^T \vec{b}$$

using $A = QR$, we get

$$(QR)^T (QR) \vec{x} = (QR)^T \vec{b}$$

$$\Rightarrow R^T \underbrace{(Q^T Q)}_{=I} \vec{x} = R^T Q^T \vec{b}$$

$$\Rightarrow R \vec{x} = Q^T \vec{b}$$

$$Q^T \vec{b} = \frac{1}{2} \begin{bmatrix} 1 & 1 & 1 & 1 \\ -1 & 1 & -1 & 1 \\ -1 & -1 & 1 & 1 \end{bmatrix} \begin{pmatrix} -3 \\ 1 \\ 0 \\ 2 \end{pmatrix} = \begin{pmatrix} 0 \\ 3 \\ 2 \end{pmatrix}$$

$$R \vec{x} = Q^T \vec{b} \Leftrightarrow \begin{bmatrix} 4 & -2 & -1 \\ 0 & 4 & 3 \\ 0 & 0 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \\ 2 \end{bmatrix}$$

(Solving by
back substitution)

$$x_3 = \frac{1}{3}$$

$$x_2 = \frac{3 - 3(\frac{1}{3})}{4} = \frac{1}{2}$$

$$x_1 = \frac{\frac{1}{3} + 2(\frac{1}{2})}{4} = \frac{1}{3}$$

L.S. soln

$$\vec{x} = \begin{pmatrix} \frac{1}{3} \\ \frac{1}{2} \\ \frac{1}{3} \end{pmatrix}$$

$$A = \begin{pmatrix} 2 & -3 & -5 \\ 2 & 1 & -2 \\ 2 & -3 & 1 \\ 2 & 1 & 4 \end{pmatrix}$$

$\underbrace{\hspace{1em}}_{\vec{a}_1} \quad \underbrace{\hspace{1em}}_{\vec{a}_2} \quad \underbrace{\hspace{1em}}_{\vec{a}_3}$

QR Decomposition

$$Q = \frac{1}{2} \begin{bmatrix} 1 & -1 & -1 \\ 1 & 1 & -1 \\ 1 & -1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$\underbrace{\hspace{1em}}_{\vec{q}_1} \quad \underbrace{\hspace{1em}}_{\vec{q}_2} \quad \underbrace{\hspace{1em}}_{\vec{q}_3}$

$$R = \begin{bmatrix} 4 & -2 & -1 \\ 0 & 4 & 3 \\ 0 & 0 & 6 \end{bmatrix}$$

$$\vec{b} = (-3, 1, 0, 2)$$

② Find the curve $y = a + 2^x b$ which gives the best least-squares fit to the points $(x, y) = (0, 6), (1, 4), (2, 0)$

If the curve went through all 3 points

$$\begin{array}{l} (x=0) \\ (x=1) \\ (x=2) \end{array} \quad \left. \begin{array}{l} a + b = 6 \\ a + 2b = 4 \\ a + 4b = 0 \end{array} \right\} \underbrace{\begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 4 \end{bmatrix}}_A \underbrace{\begin{bmatrix} a \\ b \end{bmatrix}}_{\vec{x}} = \underbrace{\begin{bmatrix} 6 \\ 4 \\ 0 \end{bmatrix}}_{\vec{y}}$$

$$A^T A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 4 \end{bmatrix} = \begin{bmatrix} 3 & 7 \\ 7 & 21 \end{bmatrix}$$

$$A^T \vec{b} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \end{bmatrix} \begin{bmatrix} 6 \\ 4 \\ 0 \end{bmatrix} = \begin{bmatrix} 10 \\ 14 \end{bmatrix}$$

Least-Squares solution

$$A^T A \vec{x} = A^T \vec{b}$$

\Leftrightarrow

$$\begin{bmatrix} 3 & 7 \\ 7 & 21 \end{bmatrix} \vec{x} = \begin{bmatrix} 10 \\ 14 \end{bmatrix}$$

$$\Rightarrow \vec{x} = \frac{1}{14} \begin{bmatrix} 21 & -7 \\ -7 & 3 \end{bmatrix} \begin{bmatrix} 10 \\ 14 \end{bmatrix}$$

$$\Rightarrow \vec{x} = \begin{bmatrix} 8 \\ -2 \end{bmatrix}$$

Least-Squares parametric fit: $a=8, b=-2$

③ Let $\vec{x} = \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}$ and $\vec{y} = \begin{pmatrix} -2 \\ 1 \\ 2 \\ 0 \end{pmatrix}$ (i) Find the projection \vec{p} of \vec{x} onto \vec{y} .
(ii) Verify that $\vec{x} - \vec{p}$ is orthogonal to \vec{y} .

$$(i) \vec{p} = \frac{(\vec{x} \cdot \vec{y})}{(\vec{y} \cdot \vec{y})} \vec{y} = \frac{3}{9} \vec{y} = \frac{1}{3} \begin{pmatrix} -2 \\ 1 \\ 2 \\ 0 \end{pmatrix} \quad (ii) \vec{x} - \vec{p} = \frac{1}{2} \begin{pmatrix} 5 \\ 2 \\ 4 \\ 6 \end{pmatrix} \quad (\vec{x} - \vec{p}) \cdot \vec{y} = -\frac{10}{3} + \frac{2}{3} + \frac{8}{3} + 0 = 0$$

#4

$$A = \begin{pmatrix} 2 & 1 \\ 1 & 1 \\ 2 & 1 \end{pmatrix} \quad \vec{b} = \begin{pmatrix} 12 \\ 6 \\ 18 \end{pmatrix}$$

Projection of \vec{b} onto $C(A)$ $\vec{p} = A(A^T A)^{-1} A^T \vec{b}$

$$A^T A = \begin{bmatrix} 2 & 1 & 2 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 1 \\ 2 & 1 \end{bmatrix} = \begin{bmatrix} 9 & 5 \\ 5 & 3 \end{bmatrix} \quad (A^T A)^{-1} = \frac{1}{2} \begin{pmatrix} 3 & -5 \\ -5 & 9 \end{pmatrix}$$

$$A^T \vec{b} = \begin{bmatrix} 2 & 1 & 2 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 12 \\ 6 \\ 18 \end{bmatrix} = \begin{bmatrix} 66 \\ 36 \end{bmatrix} = 6 \begin{bmatrix} 11 \\ 6 \end{bmatrix}$$

$$\vec{p} = A(A^T A)^{-1} A^T \vec{b} = \begin{bmatrix} 2 & 1 \\ 1 & 1 \\ 2 & 1 \end{bmatrix} \left(\frac{1}{2} \begin{bmatrix} 3 & -5 \\ -5 & 9 \end{bmatrix} \right) \left(6 \begin{bmatrix} 11 \\ 6 \end{bmatrix} \right)$$

$$= 3 \begin{bmatrix} 2 & 1 \\ 1 & 1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ -1 \end{bmatrix}$$

$$= 3 \begin{bmatrix} 5 \\ 2 \\ 5 \end{bmatrix} = \begin{pmatrix} 15 \\ 6 \\ 15 \end{pmatrix}$$

not asked in
problem;
provided here
for illustration